

International Doctoral School Algorithmic Decision Theory: MCDA and MOO

Lecture 3: MOLP Extensions

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Overview

- 1 Primal-Dual Simplex Algorithm
- 2 Radiotherapy and Multiobjective Linear Programming
- 3 Benson's (Approximation) Algorithm in Objective Space
- 4 Geometric Duality
- 5 A Dual (Approximation) Variant of Benson's Algorithm
- 6 Numerical Results

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$$\min\{Cx : Ax = b, x \geq 0\}$$

- $X = \{x \in \mathbb{R}^n : Ax \geq b\}$
- $Y = \{Cx \in \mathbb{R}^p : x \in X\}$
- $\hat{x} \in X$ is (weakly) efficient if there is no $x \in X$ with $Cx \leq C\hat{x}$ ($Cx < C\hat{x}$)
- If \hat{x} is (weakly) efficient then $C\hat{x}$ is (weakly) non-dominated

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Theorem

$\hat{x} \in X$ is (weakly) efficient if and only if there exists $(\lambda \geq 0) \lambda > 0$ such that \hat{x} is an optimal solution of

$$\min\{\lambda^T x : Ax = b, x \geq 0\}. \quad P(\lambda)$$

Dual of weighted sum problem:

$$\max\{u^T b : u^T A \leq \lambda^T C\} \quad D(\lambda)$$

Theorem

$\hat{x} \in X$ is (weakly) efficient if and only if there exists $(\lambda \geq 0) \lambda > 0$ and u with $u^T A \leq \lambda^T C$ such that

$$(u^T A - \lambda^T C)x = 0.$$

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Feasibility of Dual

Lemma

- $D(\lambda)$ is feasible for all $\lambda \geq 0$ if $\min\{c^T x : x \in X\}$ is bounded for all $c \in \text{cone}(C)$, the cone generated by the rows of C .
- Let $\bar{c}_k := \min\{c_k^i : i = 1, \dots, p\}$. $D(\lambda)$ is feasible for all $\lambda \geq 0$ if $\min\{\bar{c}^T x : Ax = b, x \geq 0\}$ is bounded.
- $D(\lambda)$ is feasible for all $\lambda \geq 0$ if $c_{kj} \geq 0$ for all k, j .

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- Assume $u_{\bar{\lambda}}$ feasible for $D(\lambda)$ for all $\lambda \in \bar{\Lambda} \subset \mathbb{R}_{\geq}^p$
- Define $Q(\lambda) = \{j : u_{\bar{\lambda}}^T a_j = c_j(\lambda)\}$
- $\hat{\Lambda} \subset \bar{\Lambda}$ is maximal with respect to $Q(\lambda)$ if for some $\hat{\lambda} \in \hat{\Lambda}$
 - $Q(\hat{\lambda}) = Q(\lambda)$ for all $\lambda \in \hat{\Lambda}$
 - $Q(\hat{\lambda}) \neq Q(\lambda)$ for all $\lambda \in \bar{\Lambda} \setminus \hat{\Lambda}$
- $Q(\hat{\Lambda}) := Q(\hat{\lambda})$ for some $\lambda \in \hat{\Lambda}$
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Restricted primal for $\hat{\Lambda}$:

$$\min\{e^T y : Ax + y = b, x_i = 0 \text{ for } i \notin Q(\hat{\Lambda}), x, y \geq 0\}$$

- If optimal value is 0 then optimal solution \hat{x} is optimal for $P(\lambda)$ for all $\lambda \in \hat{\Lambda}$
- Otherwise improve dual solution

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Restricted dual for $\hat{\Lambda}$:

$$\max\{u^T b : w^T a_j \leq 0 \text{ for } j \in Q(\hat{\Lambda}), w \leq e\}$$

- $\hat{w}(\hat{\Lambda})$ optimal solution
- If there is no $j \notin Q(\hat{\Lambda})$ such that $\hat{w}(\hat{\Lambda}) > 0$ then $P(\lambda)$ infeasible for all $\lambda \in \hat{\Lambda}$, i.e. MOLP infeasible
- Otherwise

$$\hat{\varepsilon}(\lambda) = \min_j \left\{ \frac{c_j(\lambda) - (u_{\hat{\Lambda}}(\lambda))^T a_j}{\hat{w}(\hat{\Lambda})^T a_j} : \hat{w}(\hat{\Lambda})^T a_j > 0 \right\}$$

- $\Lambda^* \subset \Lambda$ maximal with respect to ε if the same for all $\lambda \in \Lambda^*$ and different for all other Λ : $\hat{\varepsilon}_{\Lambda^*}(\lambda)$
- $u_{\Lambda^*}(\lambda) = u_{\hat{\Lambda}}(\lambda) + \hat{\varepsilon}_{\Lambda^*}(\lambda) \hat{w}(\hat{\Lambda})$

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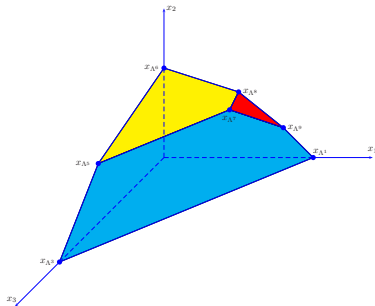
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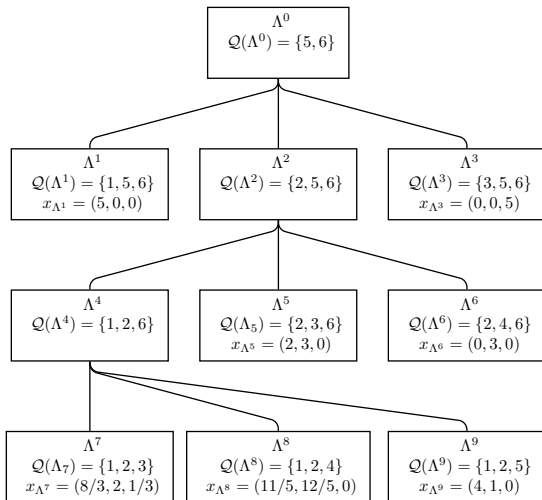
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Algorithm

- 1 Dual feasible $u_{\bar{\lambda}}$ for all $\lambda \in \bar{\Lambda}$, partition $\{\hat{\Lambda}_i : i \in I_0\}$ of $\bar{\Lambda}$.
- 2 For $i \in I_0$ find $Q(\hat{\Lambda}_i)$, $u_{\hat{\Lambda}_i}(\lambda) := u_{\bar{\lambda}}$, $\mathcal{L} = \mathcal{L} \cup \{(\hat{\Lambda}_i, u_{\hat{\Lambda}_i}(\lambda))\}$.
- 3 While $\mathcal{L} \neq \emptyset$, choose $(\hat{\Lambda}, u_{\hat{\Lambda}}(\lambda)) \in \mathcal{L}$ and solve $RP(\hat{\Lambda})$.
 - If optimal value is 0: An optimal solution of $P(\lambda)$ for all $\lambda \in \hat{\Lambda}$ is found. $\mathcal{L} := \mathcal{L} \setminus \{(\hat{\Lambda}, u_{\hat{\Lambda}}(\lambda))\}$.
 - Otherwise solve $DRP(\hat{\Lambda})$ and let $\hat{w}(\hat{\Lambda})$ be an optimal solution.
 - If there is no $j \notin Q(\hat{\Lambda})$ such that $\hat{w}(\hat{\Lambda})^T a_j > 0$: $P(\lambda)$ is infeasible for all $\lambda \in \hat{\Lambda}$ and MOLP is infeasible.
 - Otherwise compute the partition $\{\Lambda_i^* : I \in I^*\}$ of $\hat{\Lambda}$ where each Λ_i^* is maximal. For each $I \in I^*$ compute $\hat{e}_{\Lambda_i^*}(\lambda)$ and update $u_{\Lambda_i^*}(\lambda)$. Compute $Q(\Lambda_i^*)$ and set $\mathcal{L} = \mathcal{L} \cup \{(\Lambda_i^*, u_{\Lambda_i^*}(\lambda))\}$. Set $\mathcal{L} = \mathcal{L} \setminus \{(\hat{\Lambda}, u_{\hat{\Lambda}}(\lambda))\}$.

$$\begin{array}{ll}
 \min & (-x_1, -x_2, -x_3) \\
 \text{s.t} & x_1 + x_2 + x_3 + s_1 = 5 \\
 & x_1 + 3x_2 + x_3 + s_2 = 9 \\
 & 3x_1 + 4x_2 + s_3 = 16 \\
 & x_1, x_2, x_3, s_1, s_2 \geq 0
 \end{array}$$





Theorem

Let the MOLP be nondegenerate. Then Algorithm 3.1 is finite and at termination the output gives an optimal solution of $P(\lambda)$ for each $\lambda \in \Lambda$.

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Primal-Dual Simplex Algorithm

Radiotherapy and Multiobjective Linear Programming

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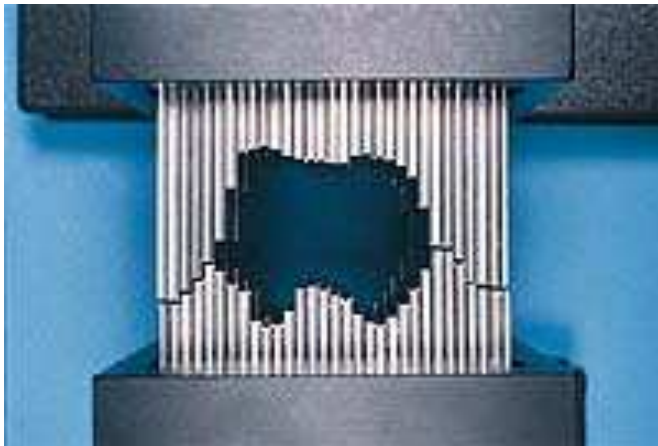
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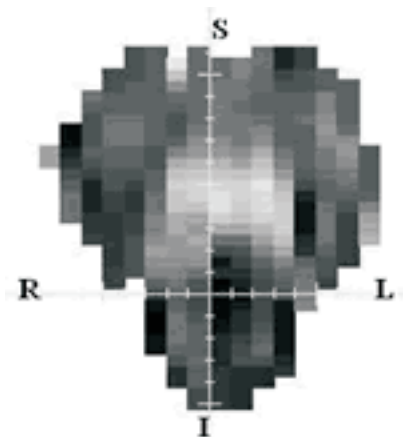
Delivery of Radiotherapy



Intensity Modulation by Multileaf Collimator



Task: Find Intensity (Fluence) Map



Primal-Dual Simplex Algorithm

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Benson's (Approximation) Algorithm in Objective Space

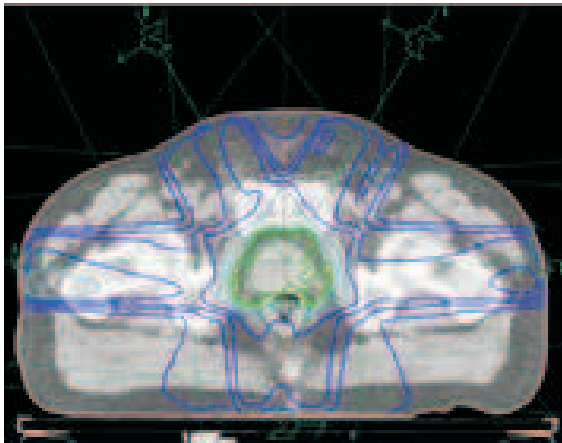
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References

that Produces Desired Dose Distribution



Modelling Intensity Optimization

- Many different (LP, NLP, MIP) models (Shao, 2005)
- Given: a beam directions, dose deposition matrix $A \in \mathbb{R}^{m \times n}$ with a_{ji} dose delivered to voxel j at unit intensity of bixel i
- Wanted: $x = (x_i : i = 1, \dots, n)$ intensity profiles for all beams such that dose $d = Ax$ satisfies the treatment goals
- Goal 1: Destroy the tumour, physician prescribes lower and upper bound l_T and u_T for dose in tumour
- Goal 2: Avoid damage to healthy tissue, physician prescribes upper bounds u_C for critical organs and u_N for other normal tissue

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$$\begin{aligned}
 \min \quad & (y_T, y_C, y_N) \\
 \text{s.t.} \quad & A_T x + y_T e \geq l_T \\
 & A_T x \leq u_T \\
 & A_C x - y_C e \leq u_C \\
 & A_N x - y_N e \leq u_N \\
 & y_T \leq \alpha \\
 & y_C \geq -u_C \\
 & y_C \leq \beta \\
 & y_N \leq \gamma \\
 & x, y_T, y_N \geq 0
 \end{aligned} \tag{1}$$

- Multiobjective version of elastic LP model of (Holder, 2003)
- Always feasible if α, β, γ are not too small

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Multiobjective Linear Programming

$$\min\{Cx : Ax \geq b, x \in \mathbb{R}^n\} \quad (2)$$

- $\mathcal{X} = \{x \in \mathbb{R}^n : Ax \geq b\}$ is **compact**
- $\mathcal{Y} = \{Cx \in \mathbb{R}^p : x \in \mathcal{X}\}$

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Benson's Algorithm

- (Benson, 1998): Solve MOLP in objective space
- $\mathcal{Y}' := \left(\mathcal{Y} + \mathbb{R}_{\geq}^p \right) \cap \left(y' - \mathbb{R}_{\geq}^p \right)$
- $\dim \mathcal{Y}' = p$ and $\mathcal{Y}'_N = \mathcal{Y}_N$

$$P_1(y) \quad \min\{z : Ax \geq b, Cx - ez \leq y\}$$

$$D_1(y) \quad \max\{b^T u - y^T w : A^T u - C^T w = 0, e^T w = 1, u, w \geq 0\}$$

Benson's Algorithm

- (Benson, 1998): Solve MOLP in objective space
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Algorithm (Benson's Algorithm)

- Init:** Compute $\bar{p} \in \text{int } \mathcal{Y}'$
 Construct p -dimensional simplex $\mathcal{S}^0 \supset \mathcal{Y}'$
 Store vertex set $\text{vert}(\mathcal{S}^0)$
 Set $k = 0$ and go to **lt k1**
- lt k1:** If $\text{vert}(\mathcal{S}^k) \subset \mathcal{Y}'$ go to **lt k5**: $\mathcal{Y}' = \mathcal{S}^k$
 Otherwise choose $y^k \in \text{vert}(\mathcal{S}^k) \setminus \mathcal{Y}'$
- lt k2:** Find $0 < \alpha_k < 1$ such that $\alpha_k y^k + (1 - \alpha_k)\bar{p} \in \text{bd } \mathcal{Y}'$
 Set $q^k = \alpha_k y^k + (1 - \alpha_k)\bar{p}$
- lt k3:** Set $\mathcal{S}^{k+1} = \mathcal{S}^k \cap \{y \in \mathbb{R}^p : \langle w^k, y \rangle \geq \langle b, u^k \rangle\}$
 (u^{k^T}, w^{k^T}) is optimal solution to $D_1(q^k)$
- lt k4:** Find $\text{vert}(\mathcal{S}^{k+1})$, set $k = k + 1$ and go to **lt k1**
- lt k5:** $\mathcal{Y}_{NE} = \mathcal{Y}'_{NE} = \{y \in \text{vert}(\mathcal{S}^k) : y < \mathcal{Y}'\}$

$$C = \begin{pmatrix} 3 & 1 \\ -1 & -2 \end{pmatrix}$$

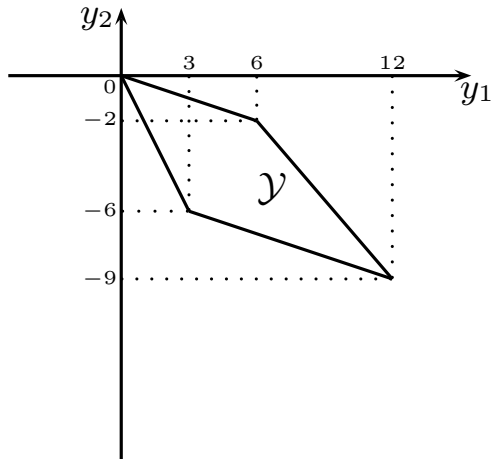
$$A = \begin{pmatrix} 0 & -1 \\ -3 & 1 \\ 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$b = \begin{pmatrix} -3 \\ -6 \\ 0 \\ 0 \end{pmatrix}$$

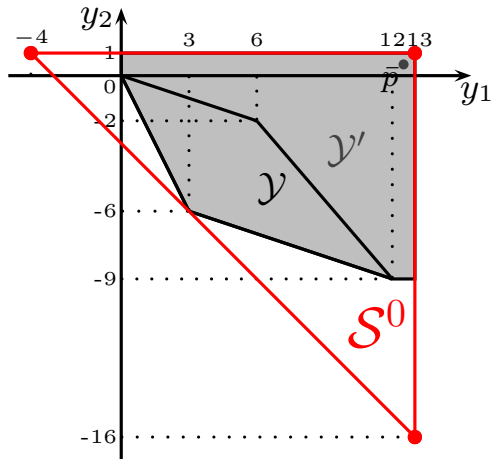
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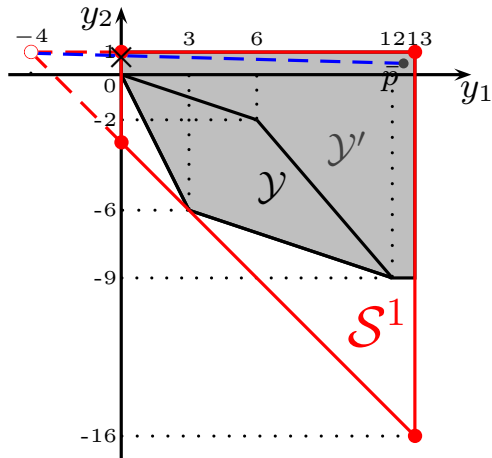
$$b = \begin{pmatrix} -3 \\ -6 \\ 0 \\ 0 \end{pmatrix}$$



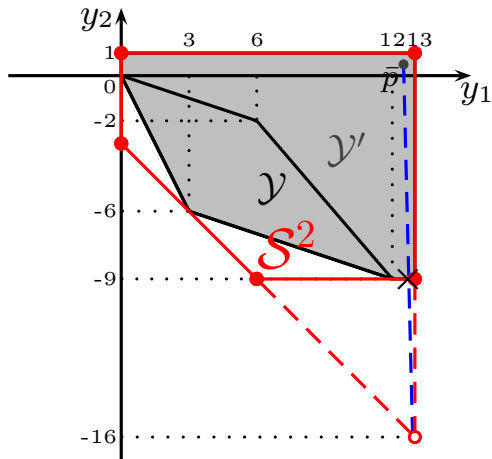
- Initial cover and interior point
- First cut
- Second cut
- Third cut
- Fourth cut



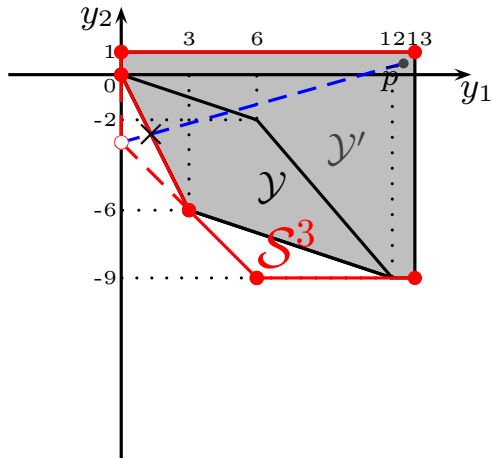
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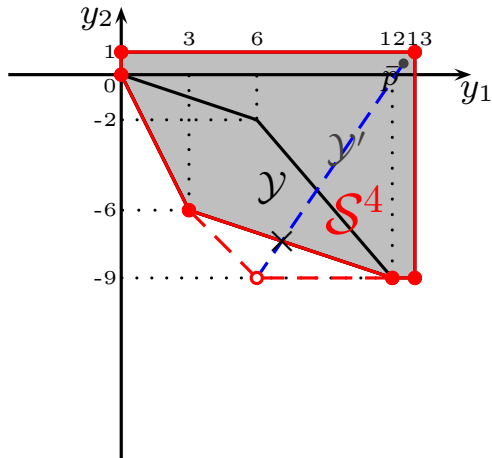
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Approximating the Nondominated Set (Shao and Ehrgott, 2007a)

- If $d(y^k, q^k) < \epsilon$ do not construct hyperplane
- Keep $y^k \in \mathcal{O}$ and $q^k \in \mathcal{I}$ for outer and inner approximation

Algorithm (Approximation Algorithm)

- It k1:** If $\text{vert}(S^k) \subset \mathcal{Y}' \cup \mathcal{O}$ go to **It k5**
Otherwise choose any $y^k \in \text{vert}(S^k) \setminus (\mathcal{O} \cup \mathcal{Y}')$
- It k3:** If $d(y^k, q^k) \leq \epsilon$ add y^k to \mathcal{O} , add q^k to \mathcal{I} , go to **It k1**
Otherwise $S^{k+1} = S^k \cap \{y \in \mathbb{R}^p : \langle w^k, y \rangle \geq \langle b, u^k \rangle\}$
 (u^k, w^k) is optimal solution to $D(q^k)$
- It k5:** $\mathcal{V}_o(S^K) = \text{vert}(S^K)$, $\mathcal{V}_i(S^K) = (\text{vert}(S^K) \setminus \mathcal{O}) \cup \mathcal{I}$
 $\mathcal{Y}^i = \text{conv}(\mathcal{V}_i(S^K))$, $\mathcal{Y}^o = \text{conv}(\mathcal{V}_o(S^K))$

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Approximating the Nondominated Set (Shao and Ehrgott, 2007a)

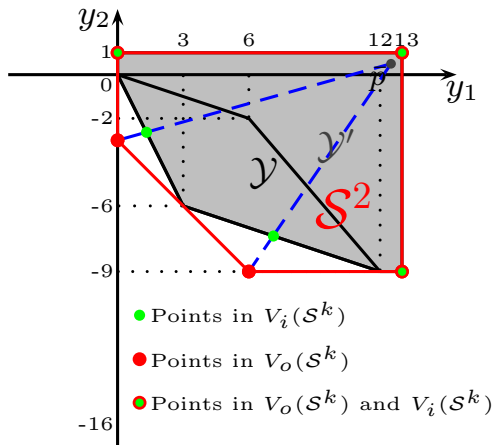
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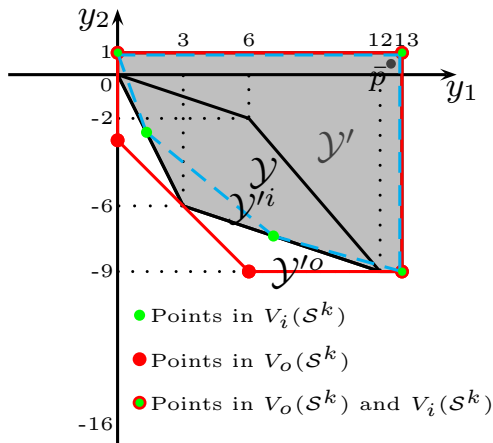
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- $\epsilon = 2.0$
- Two cuts as before
- $d(y^1, q^1) = 1.366$,
 $d(y^2, q^2) = 1.973$
- $\mathcal{V}_o(\mathcal{S}^2) = \{(13,1), (0,1), (0,-3), (6,-9), (13,-9)\}$
- $\mathcal{V}_i(\mathcal{S}^2) = \{(13,1), (0,1), (1.316,-2.632), (7.114,-7.371), (13,-9)\}$
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Proposition

- 1 $|\mathcal{V}_o(\mathcal{S}^K)| = |\mathcal{V}_i(\mathcal{S}^K)|$
- 2 $\mathcal{V}_i(\mathcal{S}^K) \subset bd(\mathcal{Y}')$
- 3 For $y \in \mathcal{V}_o(\mathcal{S}^K)$ it holds $y \notin bd(\mathcal{Y}')$ if and only if $y \notin \mathcal{V}_i(\mathcal{S}^K)$
- 4 If $y_{ov} \in \mathcal{V}_o(\mathcal{S}^K)$ there exists $y_{iv} \in \mathcal{V}_i(\mathcal{S}^K)$ with $d(y_{ov}, y_{iv}) \leq \epsilon$ and vice versa
- 5 $\mathcal{Y}'_N + \mathbb{R}_{\geq}^p \subseteq \mathcal{Y}'_N + \mathbb{R}_{\geq}^p \subseteq \mathcal{Y}'_N + \mathbb{R}_{\geq}^p$

Proposition

If $y_o \in \mathcal{Y}'_{WN}$ there exists $y_i \in \mathcal{Y}'_{WN}$ such that $d(y_o, y_i) \leq \epsilon$.

- $\hat{x} \in \mathcal{X}$ is (weakly) ϵ -efficient if there is no $x \in \mathcal{X}$ with $Cx \leq (<) C\hat{x} - \epsilon$.
- $C\hat{x}$ is (weakly) ϵ -nondominated

Theorem

Let $\epsilon = \epsilon e$, where $e = (1, \dots, 1) \in \mathbb{R}^p$. Then \mathcal{Y}'_{WN} is a set of weakly ϵ -nondominated points for \mathcal{Y}' .

Proposition

If $y_o \in \mathcal{Y}'_o$ there exists $y_i \in \mathcal{Y}'_i$ such that $d(y_o, y_i) \leq \epsilon$.

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Theorem

Let $\epsilon = \epsilon e$, where $e = (1, \dots, 1) \in \mathbb{R}^p$. Then \mathcal{Y}'_i is a set of weakly ϵ -nondominated points for \mathcal{Y}' .

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- $\hat{x} \in \mathcal{X}$ is **(weakly) ϵ -efficient** if there is no $x \in \mathcal{X}$ with $Cx \leq (<) C\hat{x} - \epsilon$.
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Overview

- 1 Primal-Dual Simplex Algorithm
- 2 Radiotherapy and Multiobjective Linear Programming
- 3 Benson's (Approximation) Algorithm in Objective Space
- 4 Geometric Duality**
- 5 A Dual (Approximation) Variant of Benson's Algorithm
- 6 Numerical Results

The Geometric Dual Heyde and Löhne (2006)

- Primal MOLP:

$$\min\{Cx : x \in \mathbb{R}^n, Ax \geq b\}$$

- $\mathcal{K} := \mathbb{R}_{\geq}^p e^p = \{y \in \mathbb{R}^p : y_1 = \dots = y_{p-1} = 0, y_p \geq 0\}$

- Dual MOLP:

$$\max_{\mathcal{K}}\{D(u, \lambda) : (u, \lambda) \in \mathbb{R}^m \times \mathbb{R}^p, (u, \lambda) \geq 0, A^T u = C^T \lambda, e^T \lambda = 1\}$$

$$D(u, \lambda) := (\lambda_1, \dots, \lambda_{p-1}, b^T u)^T = \begin{pmatrix} 0 & I_{p-1} & 0 \\ b^T & 0 & 0 \end{pmatrix} \begin{pmatrix} u \\ \lambda \end{pmatrix}$$

- $\mathcal{P} := C(\mathcal{X}) + \mathbb{R}_{\geq}^p$

- $\mathcal{D} := D(\mathcal{U}) - \mathcal{K}$

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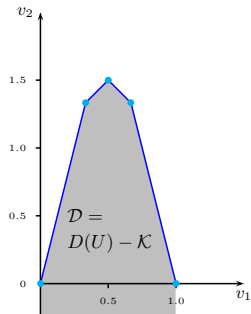
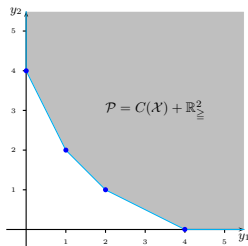
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$$C = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \\ 1 & 2 \\ 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad b = \begin{pmatrix} 4 \\ 3 \\ 4 \\ 0 \\ 0 \end{pmatrix}$$



$$\varphi(y, v) := \sum_{i=1}^{p-1} y_i v_i + y_p \left(1 - \sum_{i=1}^{p-1} v_i \right) - v_p$$

For $x \in \mathcal{X}$ and $(u, \lambda) \in \mathcal{U}$: $\varphi(Cx, D(u, \lambda)) = \lambda^T Px - b^T u$

$$\lambda(v) := \left(v_1, \dots, v_{p-1}, 1 - \sum_{i=1}^{p-1} v_i \right)^T$$

$$\lambda^*(y) := (y_1 - y_p, \dots, y_{p-1} - y_p, -1)^T$$

$$H(v) := \left\{ y \in \mathbb{R}^p : \lambda(v)^T y = v_p \right\}$$

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For $\mathcal{F}^* \subset \mathbb{R}^p$ define $\Psi(\mathcal{F}^*) := \bigcap_{v \in \mathcal{F}^*} H(v) \cap \mathcal{P}$

Theorem (Heyde and Löhne (2006))

Ψ is an inclusion reversing one-to-one map between the set of all proper \mathcal{K} -maximal faces of \mathcal{D} and the set of all proper weakly nondominated faces of \mathcal{P} and the inverse map is given by

$$\Psi^{-1}(\mathcal{F}) = \bigcap_{y \in \mathcal{F}} H^*(y) \cap \mathcal{D}.$$

Moreover, for every proper \mathcal{K} -maximal face \mathcal{F}^* of \mathcal{D} it holds

$$\dim \mathcal{F}^* + \dim \Psi(\mathcal{F}^*) = p - 1$$

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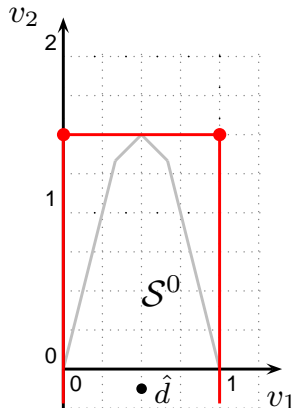
A Dual Algorithm (Ehrgott *et al.*, 2007)

$$P_2(v) \quad \min \{ \lambda(v)^T Cx : x \in \mathbb{R}^n, Ax \geq b \}$$
$$D_2(v) \quad \max \{ b^T u : u \in \mathbb{R}^m, u \geq 0, A^T u = C^T \lambda(v) \}$$

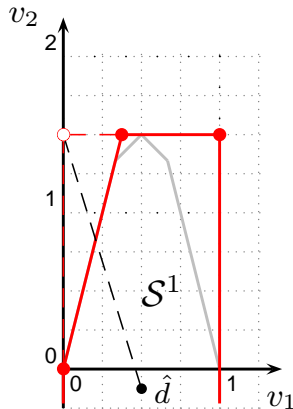
Algorithm

- Init:** For $\hat{d} \in \text{int } \mathcal{D}$ find optimal solution x^0 of $P_2(\hat{d})$
Set $\mathcal{S}^0 := \{v \in \mathbb{R}^p : \lambda(v) \geq 0, \varphi(Cx^0, v) \geq 0\}$; $k := 1$
- It k1:** If $\text{vert}(\mathcal{S}^{k-1}) \subset \mathcal{D}$ stop
otherwise choose $s^k \in \text{vert}(\mathcal{S}^{k-1}) \setminus \mathcal{D}$
- It k2:** Find α^k with $v^k := \alpha^k s^k + (1 - \alpha^k) \hat{d} \in \max_{\mathcal{K}} \mathcal{D}$
- It k3:** Compute an optimal solution x^k of $P_2(v^k)$
- It k4:** Set $\mathcal{S}^k := \mathcal{S}^{k-1} \cap \{v \in \mathbb{R}^p : \varphi(Cx^k, v) \geq 0\}$
- It k5:** Set $k := k + 1$ and go to **It k1**

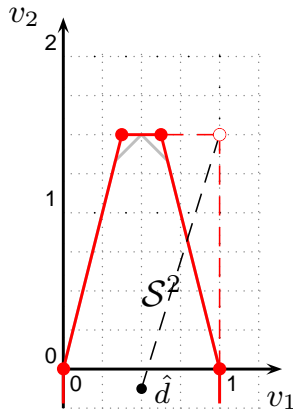
- Initial cover and interior point
- First cut
- Second cut
- Third cut
- Fourth cut



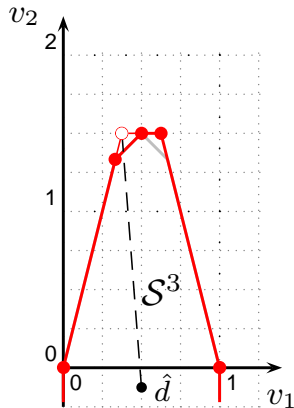
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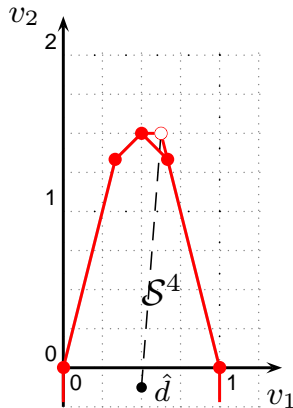
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- Let $S \subset \mathbb{R}^p$ be a polyhedron with $S = \mathcal{S} - \mathcal{K}$ and $\text{proj}_{\mathbb{R}^{p-1}}(S) = \{t \in \mathbb{R}^{p-1} : t \geq 0, \sum_{i=1}^{p-1} t_i \leq 1\}$
- $\mathcal{D}(S) = \{y \in \mathbb{R}^p : \varphi(y, v) \geq 0, \text{ for all } v \in \text{vert}(S)\}$

Proposition

- 1 $\mathcal{D}(S) = \mathcal{D}(S) + \mathbb{R}_{\geq}^p$
- 2 *Theorem 6 holds for $\mathcal{D} = S$ and $\mathcal{P} = \mathcal{D}(S)$*
- 3 *If $S^1 \subset S^0$ then $\mathcal{D}(S^1) \supset \mathcal{D}(S^0)$*

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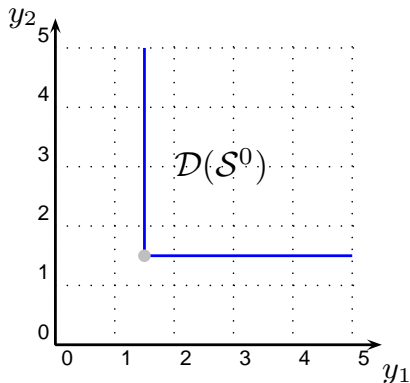
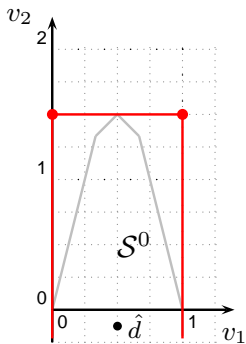
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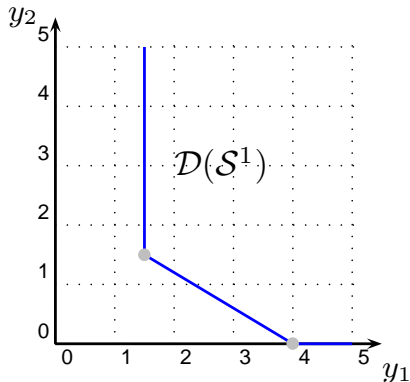
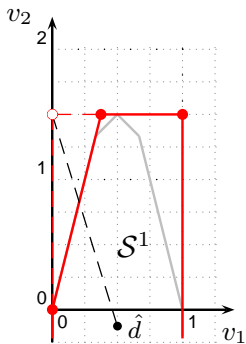
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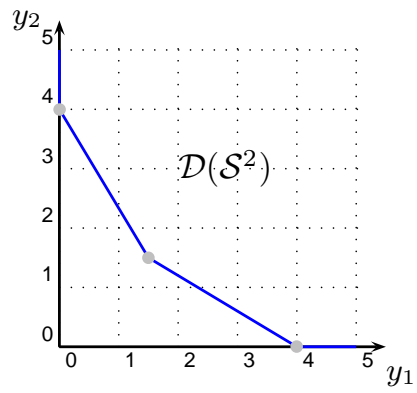
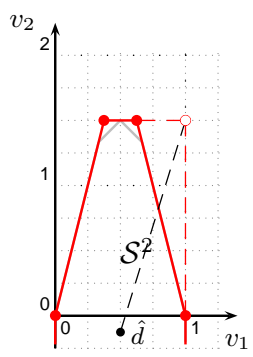
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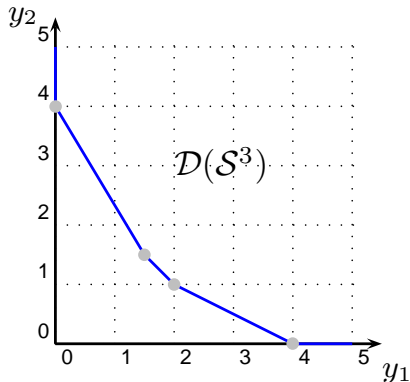
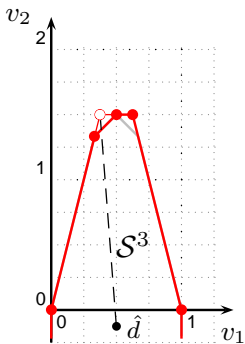
Proposition

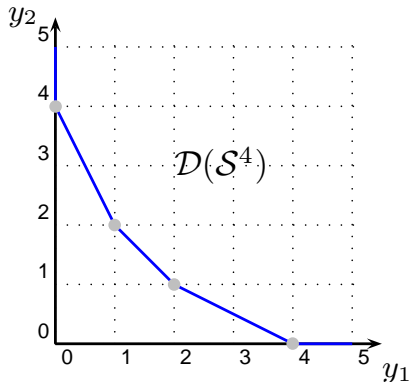
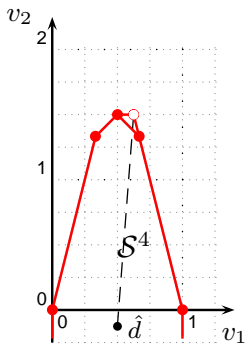
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Dual Approximation (Shao and Ehrgott, 2007b)

- If $\text{vert}(\mathcal{S}^k) \subset \mathcal{D} + \epsilon e^p$ do not construct hyperplane
- If $v_p - f \leq \epsilon$ then $v \in \mathcal{D} + \epsilon e^p$ where f is optimum of $D_2(v)$
- $\mathcal{D}^o := \mathcal{S}^{k-1} \supset \mathcal{D}$ is outer approximation of \mathcal{D}
-

$$\mathcal{P}^i := \mathcal{D}(\mathcal{D}^o) \subset \mathcal{D}(\mathcal{D}) = \mathcal{P}$$

is inner approximation of \mathcal{P}

Theorem

Let $\varepsilon = \epsilon e$, then the nondominated set of \mathcal{P}^i is a set of ε -nondominated points of \mathcal{P} .

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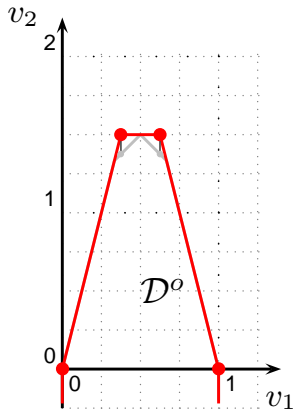
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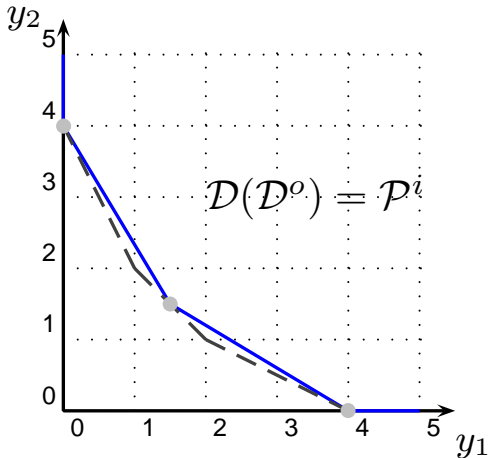
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Let $\varepsilon = \epsilon e$, then the nondominated set of \mathcal{P}^i is a set of ε -nondominated points of \mathcal{P} .

- $\epsilon = 3/20$
- Two cuts as before
- $d(v^1, bd^1) = 1/8$,
 $d(v^2, bd^2) = 1/8$
- $\mathcal{D}^\circ = \mathcal{S}^2$
- $\mathcal{P}^i = \mathcal{D}(\mathcal{D}^\circ)$



- $\epsilon = 3/20$
- Two cuts as before
- $d(v^1, bd^1) = 1/8$,
 $d(v^2, bd^2) = 1/8$
- $\mathcal{D}^o = \mathcal{S}^2$
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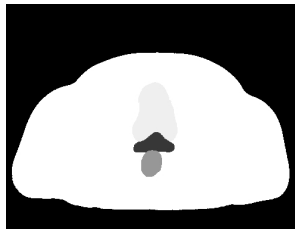
Overview

- 1 Primal-Dual Simplex Algorithm
- 2 Radiotherapy and Multiobjective Linear Programming
- 3 Benson's (Approximation) Algorithm in Objective Space
- 4 Geometric Duality
- 5 A Dual (Approximation) Variant of Benson's Algorithm
- 6 Numerical Results**

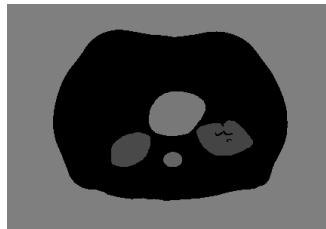
The Test Cases



Acoustic Neuroma



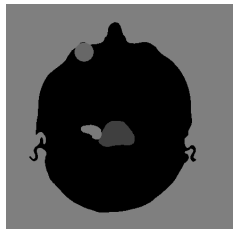
Prostate



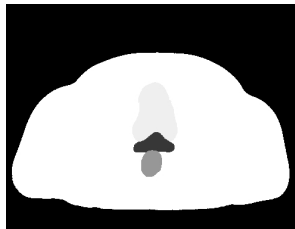
Pancreatic Lesion

- Dose calculation inexact
- Inaccuracies during delivery
- Planning to small fraction of a Gy acceptable

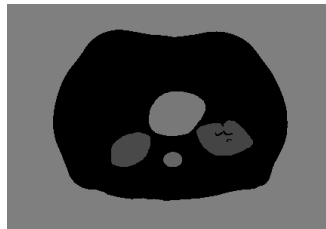
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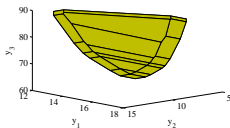
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Case	AN	P	PL
Tumour voxels	9	22	67
Critical organ voxels	47	89	91
Normal tissue voxels	999	1182	986
Bixels	594	821	1140
u_T	87.55	90.64	90.64
l_T	82.45	85.36	85.36
u_C	60/45	60/45	60/45
u_N	0.00	0.00	0.00
α	16.49	42.68	17.07
β	12.00	30.00	12.00
γ	87.55	100.64	90.64

$$\begin{array}{ll}
 \min & (y_T, y_C, y_N) \\
 \text{s.t.} & A_T x + y_T e \geq l_T \\
 & A_T x \leq u_T \\
 & A_C x - y_C e \leq u_C \\
 & A_N x - y_N e \leq u_N \\
 & y_T \leq \alpha \\
 & y_C \geq -u_C \\
 & y_C \leq \beta \\
 & y_N \leq \gamma \\
 & x, y_T, y_N \geq 0
 \end{array} \tag{3}$$

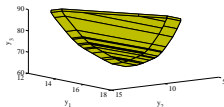
	ϵ	Solving the dual			Solving the primal		
		Time	Vert.	Cuts	Time	Vert.	Cuts
AC	0.1	1.484	17	8	5.938	27	21
	0.01	3.078	33	18	8.703	47	44
	0	8.864	85	55	13.984	55	85
PR	0.1	4.422	39	19	14.781	56	42
	0.01	18.454	157	78	64.954	296	184
	0	792.390	3280	3165	995.050	3165	3280
PL	0.1	58.263	85	44	164.360	152	90
	0.01	401.934	582	298	1184.950	1097	586
	0.005	734.784	1058	539	2147.530	1989	1041

$\epsilon = 0.1$

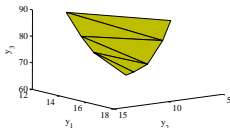
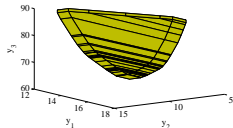


P:

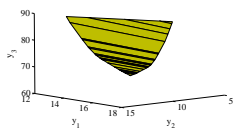
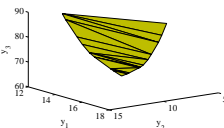
$\epsilon = 0.01$



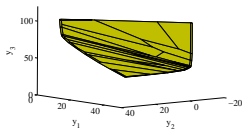
$\epsilon = 0$



D:

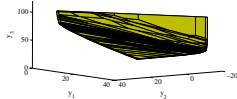


$\epsilon = 0.1$

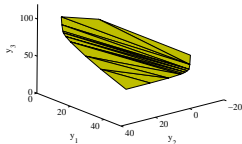
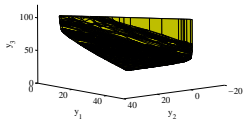


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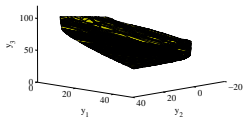
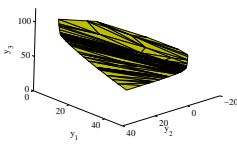
$\epsilon = 0.01$



$\epsilon = 0$



D:

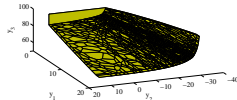
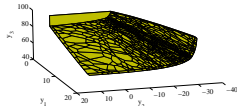
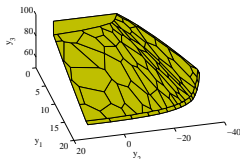


$\epsilon = 0.1$

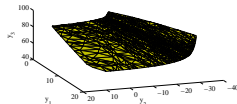
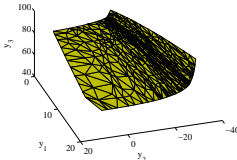
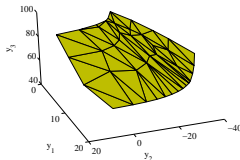
$\epsilon = 0.01$

$\epsilon = 0.0005$

P:



D:



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