

Provenance Annotation and Analysis to Support Process Re-Computation

Jacek Cala^[0000-0002-8322-4370] and Paolo Missier^[0000-0002-0978-2446]

School of Computing, Newcastle University, Newcastle upon Tyne, UK,
{Jacek.Cala, Paolo.Missier}@ncl.ac.uk

Abstract. Many resource-intensive analytics processes evolve over time following new versions of the reference datasets and software dependencies they use. We focus on scenarios in which any version change has the potential to affect many outcomes, as is the case for instance in high throughput genomics where the same process is used to analyse large cohorts of patient genomes, or *cases*. As any version change is unlikely to affect the entire population, an efficient strategy for restoring the currency of the outcomes requires first to identify the *scope of a change*, i.e., the subset of affected data products. In this paper we describe a generic and reusable provenance-based approach to address this scope discovery problem. It applies to a scenario where the process consists of complex hierarchical components, where different input cases are processed using different version configurations of each component, and where separate provenance traces are collected for the executions of each of the components. We show how a new data structure, called a *restart tree*, is computed and exploited to manage the change scope discovery problem.

Keywords: provenance annotations, process re-computation

1 Introduction

Consider data analytics processes that exhibit the following characteristics. C1: are resource-intensive and thus expensive when repeatedly executed over time, i.e., on a cloud or HPC cluster; C2: require sophisticated implementations to run efficiently, such as workflows with a nested structure; C3: depend on multiple reference datasets and software libraries and tools, some of which are versioned and evolve over time; C4: apply to a possibly large population of input instances.

This is not an uncommon set of characteristics. A prime example is data processing for high throughput genomics, where the genomes (or exomes) of a cohort of patient cases are processed, individually or in batches, to produce lists of variants (genetic mutations) that form the basis for a number of diagnostic purposes. These *variant calling and interpretation* pipelines take batches of 20–40 patient exomes and require hundreds of CPU-hours to complete (C1). Initiatives like the 100K Genome project in the UK (www.genomicsengland.co.uk) provide a perspective on the scale of the problem (C4).

Figure 1, taken from our prior work [5], shows the nested workflow structure (C2) of a typical variant calling pipeline based on the GATK (Genomics Analysis

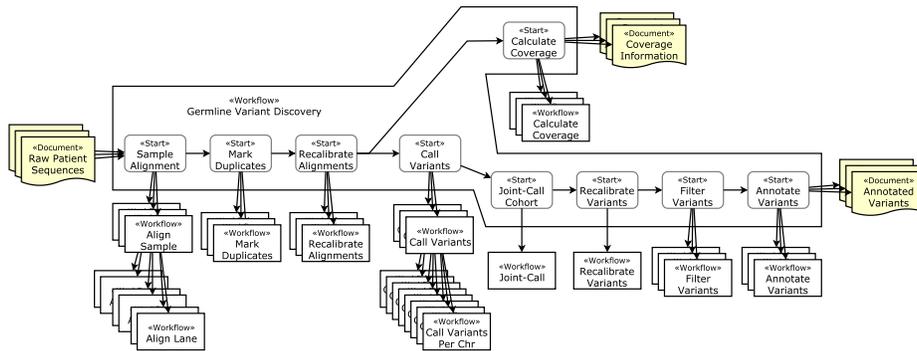


Fig. 1: A typical variant discovery pipeline processing a pool of input samples. Each step is usually implemented as a workflow or script that combines a number of tools run in parallel.

Toolkit) best practices from the Broad Institute.¹ Each task in the pipeline relies on some GATK (or other open source) tool, which in turn requires lookups in public reference datasets. For most of these processes and reference datasets new versions are issued periodically or on an as-needed basis (C3). The entire pipeline may be variously implemented as a HPC cluster script or workflow. Each single run of the pipeline creates a hierarchy of executions which are distributed across worker nodes and coordinated by the orchestrating top-level workflow or script (cf. the “Germline Variant Discovery” workflow depicted in the figure).

Upgrading one or more of the versioned elements risks invalidating previously computed knowledge outcomes, e.g. the sets of variants associated with patient cases. Thus, a natural reaction to a version change in a dependency is to upgrade the pipeline and then re-process all the cases. However, as we show in the example at the end of this section, not all version changes affect each case equally, or in a way that completely invalidates prior outcomes. Also, within each pipeline execution only some of the steps may be affected. We therefore need a system that can perform more selective re-processing in reaction to a change. In [6] we have described our initial results in developing such a system for selective re-computation over a population of cases in reaction to changes, called **ReComp**. **ReComp** is a *meta-process* designed to detect the scope of a single change or of a combination of changes, estimate the impact of those changes on the population in scope, prioritise the cases for re-processing, and determine the minimal amount of re-processing required for each of those cases. Note that, while ideally the process of upgrading P is controlled by **ReComp**, in reality we must also account for upgrades of P that are performed “out-of-band” by developers, as we have assumed in our problem formulation.

Briefly, **ReComp** consists of the macro-steps shown in Fig. 2. The work presented in this paper is instrumental to the **ReComp** design, as it addresses the

¹ <https://software.broadinstitute.org/gatk/best-practices>

very first step (S1) indicated in the figure, in a way that is generic and agnostic to the type of process and data.

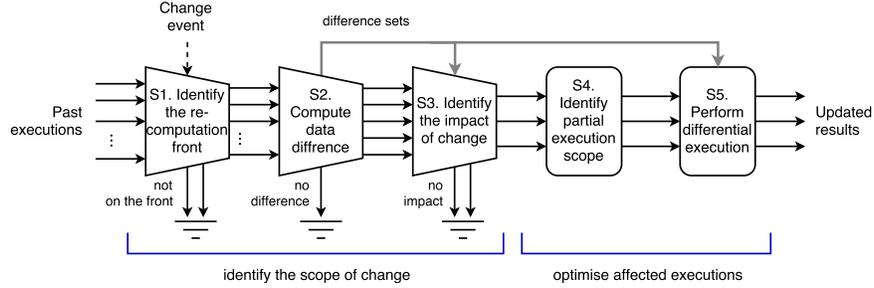


Fig. 2: Schematic of the ReComp meta-process.

1.1 Version Changes and Their Scope

To frame the problem addressed in the rest of the paper, we introduce a simple model for version changes as triggers for re-computation. Consider an abstract process P and a population $X = \{x_1 \dots x_N\}$ of inputs to P , referred to as *cases*. Let $\mathcal{D} = [D_1 \dots D_m]$ be an ordered list of *versioned* dependencies. These are components, typically software libraries or reference data sets, which are used by P to process a case. Each D has a version, denoted $D.v$, with a total order on the sequence of versions $D.v < D.v' < D.v'' < \dots$ for each D .

An *execution configuration* for P is the vector $V = [v_1 \dots v_m]$ of version numbers for $[D_1 \dots D_m]$. Typically, these are the latest versions for each D , but configurations where some D is “rolled back” to an older version are possible. The set of total orders on the versions of each $D \in \mathcal{D}$ induce a partial order on the set of configurations:

$$[v_1 \dots v_m] \prec [v'_1 \dots v'_m] \text{ iff } \{v_i \leq v'_i\}_{i:1\dots m} \text{ and } v_i < v'_i \text{ for at least one } v_i.$$

We denote an *execution* of P on input $x_i \in X$ using configuration V by $E = P(x, V)$, where P may consist of multiple components $\{P_1 \dots P_k\}$, such as those in our example pipeline. When this is the case, we assume for generality that one execution $P(x, V)$ given x and V is realised as a collection $\{E_i = P_i(x, V)\}_{i:1\dots k}$ of separate executions, one for each P_i . We use the W3C PROV [13] and ProvONE [7] abstract vocabularies to capture this model in which: $P, P_1 \dots P_k$ are all instances of `provone:Program`, their relationships is expressed as

$$\{\text{provone:hasSubProgram}(P, P_i)\}_{i:1\dots k}$$

and each execution E_i is associated with its program P_i using:

$$\{\text{wasAssociatedWith}(E_i, -, P_i)\}_{i:1\dots k}$$

Version change events. We use PROV derivation statements `prov:wasDerivedFrom` to denote a *version change event* C for some D_i , from v_i to v'_i : $C = \{D.v'_i \xrightarrow{\text{wDF}} D.v_i\}$. Given $V = [v_1 \dots v_i \dots v_m]$, C enables the new configuration $V' = [v_1 \dots v'_i \dots v_m]$, meaning that V' can be *applied* to P , so that its future executions are of form $E = P(x, V')$.

We model sequences of changes by assuming that an unbound stream of change events C_1, C_2, \dots can be observed over time, either for different or the same D_i . A re-processing system may react to each change individually. However, we assume the more general model where a set of changes accumulates into a window (according to some criteria, for instance fixed-time) and is processed as a batch. Thus, by extension, we define a composite change to be a set of elementary changes that are part of the same window. Given $V = [v_1 \dots v_i \dots v_j \dots v_m]$, we say that $C = \{D.v'_i \xrightarrow{\text{wDF}} D.v_i, D.v'_j \xrightarrow{\text{wDF}} D.v_j, \dots\}$ enables configuration $V' = [v_1 \dots v'_i \dots v'_j \dots v_m]$. Importantly, all change events, whether individual or accumulated into windows, are merged together into the single *change front* CF which is the configuration of the latest versions of all changed artefacts.

Applying CF to $E = P(x, V)$ involves re-processing x using P to bring the outcomes up-to-date with respect to all versions in the change front. For instance, given $V = [v_1, v_2, v_3]$ and the change front $CF = \{v'_1, v'_2\}$, the re-execution of $E = P(x, [v_1, v_2, v_3])$ is $E' = P(x, [v'_1, v'_2, v_3])$. It is important to keep track of how elements of the change front are updated as it may be possible to avoid rerunning some of P 's components for which the configuration has not changed. Without this fine-grained derivation information, each new execution may use the latest versions but cannot be easily optimised using partial re-processing.

Clearly, processing change events as a batch is more efficient than processing each change separately, cf. $E' = P(x, [v'_1, v_2, v_3])$ followed by $E'' = P(x, [v'_1, v'_2, v_3])$ with the example above. But a model that manages change events as a batch is also general in that it accommodates a variety of refresh strategies. For example, applying changes that are known to have limited impact on the outcomes can be delayed until a sufficient number of other changes have accumulated into CF , or until a specific high-impact change event has occurred. A discussion of specific strategies that are enabled by our scope discovery algorithm is out of the scope of this paper.

1.2 Problem Formulation and Contributions

Suppose P has been executed h times for some $x \in X$, each time with a different configuration $V_1 \dots V_h$. The collection of past executions, for each $x \in X$, is:

$$\{E(P_i, x, V_j)_{i:1\dots k, j:1\dots h, x \in X}\} \quad (1)$$

The problem we address in this paper is to identify, for each change front CF , the smallest set of those executions that are affected by CF . We call this the *re-computation front* C relative to CF . We address this problem in a complex general setting where many types of time-interleaved changes are allowed, where many configurations are enabled by any of these changes, and where executions

may reflect any of these configurations, and in particular individual cases x may be processed using any such different configurations. The example from the next section illustrates how this setting can manifest itself in practice.

Our main contribution is a generic algorithm for discovering re-computation front that applies to a range of processes, from simple black-box, single component programs where P is indivisible, to complex hierarchical workflows where P consists of subprograms P_i which may itself be defined in terms of subprograms.

Following a tradition from the literature to use provenance as a means to address re-computation [2,12,6], our approach also involves collecting and exploiting both execution provenance for each E , as well as elements of process-subprocess dependencies as mentioned above. To the best of our knowledge this particular use of provenance and the algorithm have not been proposed before.

1.3 Example: Versioning in Genomics

The problem of version change emerges concretely in Genomics pipelines in which changes have different scope, both within each process instance and across the population of cases. For example, an upgrade to the `bwa` aligner tool directly affects merely the alignment task but its impact may propagate to most of the tasks downstream. Conversely, an upgrade in the human reference genome directly affects the majority of the tasks. In both cases, however, the entire population of executions is affected because current alignment algorithms are viewed as “black boxes” that use the entire reference genome.

However, a change in one of the other reference databases that are queried for specific information only affects those cases where some of the changed records are part of a query result. One example is ClinVar, a popular variant database queried to retrieve information about specific diseases (phenotypes). In this case, changes that affect one phenotype will not impact cases that exhibit a completely different phenotype. But to detect the impact `ReComp` uses steps (S2) and (S3), which is out of scope of this paper.

Additionally, note that version changes in this Genomics example occur with diverse frequency. For instance, the reference genome is updated twice a years, alignment libraries every few months, and ClinVar every month.

2 Recomputation fronts and restart trees

2.1 Recomputation fronts

In Sec. 1.1 we have introduced a partial order $V \prec V'$ between process configurations. In particular, given V , if a change C enables V' then by definition $V \prec V'$. Note that this order induces a corresponding partial order between any two executions that operate on the same $x \in X$.

$$P(x, V) = E \ll E' = P(x, V') \text{ iff } V \prec V' \quad (2)$$

This order is important, because optimising re-execution, i.e. executing $P(x, V')$, may benefit most from the provenance associated with the latest execution according to the sequence of version changes, which is $E = P(x, V)$ (a discussion on the precise types of such optimisations can be found in [6]). For this reason in our implementation we keep track of the execution order explicitly using the `wasInformedBy` PROV relationship, i.e. we record PROV statement $E' \xrightarrow{\text{wIB}} E$ whenever re-executing E such that $E \ll E'$.

To see how these chains of ordered executions may evolve consider, for instance, $E_0 = P(x_1, [a_1, b_1]), E_1 = P(x_2, [a_1, b_1])$ for inputs x_1, x_2 respectively, where the a and b are versions for two dependencies D_1, D_2 . The situation is depicted in Fig. 3/left. When change $C_1 = \{a_2 \xrightarrow{\text{wDF}} a_1\}$ occurs, it is possible that only x_1 is re-processed, but not x_2 . This may happen, for example, when D_1 is a data dependency and the change affects parts of the data which were not used by E_1 in the processing of input x_2 . In this case, C would trigger one single new execution: $E_2 = P(x_1, [a_2, b_1])$ where we record the ordering $E_0 \ll E_2$. The new state is depicted in Fig. 3/middle.

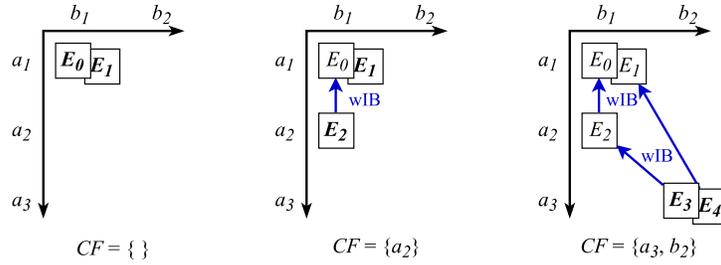


Fig. 3: The process of annotating re-execution following a sequence of events; in bold are executions on the re-computation front; a - and b -axis represent the artefact derivation; arrows in blue denote the `wasInformedBy` relation.

Now consider the new change $C_2 = \{a_3 \xrightarrow{\text{wDF}} a_2, b_2 \xrightarrow{\text{wDF}} b_1\}$, affecting both D_1 and D_2 , and suppose both x_1 and x_2 are going to be re-processed. Then, for each x we retrieve the latest executions that are affected by the change, in this case E_2, E_1 , as their provenance may help optimising the re-processing of x_1, x_2 using the new *change front* $\{a_3, b_2\}$. After re-processing we have two new executions: $E_3 = P(x_1, [a_3, b_2]), E_4 = P(x_2, [a_3, b_2])$ which may have been optimised using E_2, E_1 , respectively, as indicated by their ordering: $E_3 \ll E_2, E_4 \ll E_1$ (see Fig. 3/right).

To continue with the example, let us now assume that the provenance for a new execution: $E_5 = P(x_1, [a_1, b_2])$ appears in the system. This may have been triggered by an explicit user action independently from our re-processing system. Note that the user has disregarded the fact that the latest version of a_i is a_3 . The corresponding scenario is depicted in Fig. 4/left. We now have two

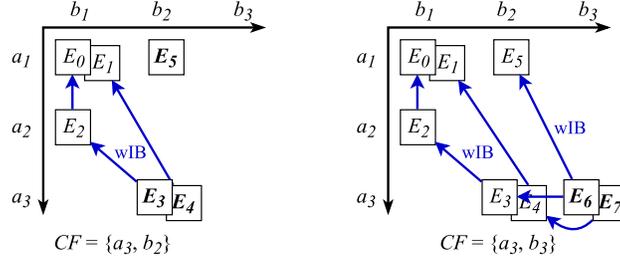


Fig. 4: Continuation of Fig. 3; in bold are executions on the re-computation front; a- and b-axis represent the artefact derivation; arrows in blue denote the `wasInformedBy` relation.

executions for x_1 with two configurations. Note that despite $E_0 \ll E_5$ holds it is not reflected by a corresponding $E_5 \xrightarrow{wIB} E_0$ in our re-computation system because E_5 was an explicit user action. However, consider another change event: $\{b_3 \xrightarrow{wDF} b_2\}$. For x_2 , the affected executions is E_4 , as this is the single latest execution in the ordering recorded so far for x_2 . But for x_1 there are now two executions that need to be brought up-to-date, E_3 and E_5 , as these are the maximal elements in the set of executions for x_1 relative according to the order: $E_0 \ll E_2 \ll E_3, E_0 \ll E_5$. We call these executions the *re-computation front* for x_1 relative to change front $\{a_3, b_3\}$, in this case.

This situation, depicted in Fig. 4/right, illustrates the most general case where the entire set of previous executions need to be considered when re-processing an input with a new configuration. Note that the two independent executions E_3 and E_5 have merged into the new E_6 .

Formally, the *re-computation front* for $x \in X$ and for a change front $CF = \{w_1 \dots w_k\}, k \leq m$ is the set of maximal executions $E = P(x, [v_1 \dots v_m])$ where $v_i \leq w_i$ for $1 \leq i \leq m$.

2.2 Building a Restart Tree

Following our goal to develop a generic re-computation meta-process, the front finding algorithm needs to support processes of various complexity – from the simplest black-box processes to complex hierarchical workflows mentioned earlier. This requirement adds another dimension to the problem of the identification of the re-computation front.

If process P has a hierarchical structure, e.g. expressed using the `provone:hasSubProgram` statement (cf. Sec. 1.1), one run of P will usually result in a collection of executions. These are logically organised into a hierarchy, where the top-level represents the execution of the program itself, and sub-executions (connected via `provone:wasPartOf`) represent the executions of the sub-programs. Following the principle of the separation of concerns, we assume the general case where the top-level program is not aware of the data and software dependen-

cies of its parts. Thus, discovering which parts of the program used a particular dependency requires traversing the entire hierarchy of executions.

To illustrate this problem let us focus on a small part of our pipeline – the alignment step (Align Sample and Align Lane). Fig. 5 shows this step modelled using ProvONE. P_0 denotes the top program – the Align Sample workflow, SP_0 is the Align Lane subprogram, SSP_0 – SSP_3 represent the subsub-programs of bioinformatic tools like `bwa` and `samtools`, while SP_1 – SP_3 are the invocations of the `samtools` program. Programs have input and output ports (the dotted grey arrows) and ports p_1 – p_8 are related with default artefacts a_0 , b_0 , etc. specified using the `provone:hasDefaultParam` statement. The artefacts refer to the code of the executable file and data dependencies; e.g. e_0 represents the code of `samtools`. Programs are connected to each other via ports and channels, which in the figure are identified using reversed double arrows.

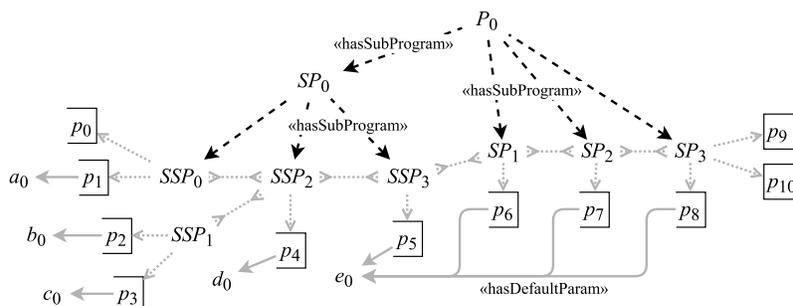


Fig. 5: A small part of the Genomics pipeline shown in Fig. 1 encoded in ProvONE. ($--\blacktriangleright$) denotes the `hasSubProgram` relation; (\longrightarrow) the `hasDefaultParam` statements; ($\cdots\blacktriangleright$) `hasInPort/hasOutPort`; ($\blacktriangleright\cdots\blacktriangleleft$) the sequence of the $\{P_i \text{ hasOutPort } p_m \text{ connectsTo } Ch_x, P_j \text{ hasInPort } p_n \text{ connectsTo } Ch_x\}$ statements.

Running this part of the pipeline would generate the runtime provenance information with the structure resembling the program specification (cf. Fig. 6). The main difference between the static program model and runtime information is that during execution all ports transfer some data – either default artefacts indicated in the program specification, data provided by the user, e.g. input sample or the output data product. When introducing a change in this context, e.g. $\{b_1 \xrightarrow{\text{wDF}} b_0, e_1 \xrightarrow{\text{wDF}} e_0\}$, two things are important. Firstly, the usage of the artefacts is captured at the sub-execution level (SSE_1 , SSE_3 and SE_1 – SE_3) while E_0 uses these artefacts indirectly. Secondly, to rerun the alignment step it is useful to consider the sub-executions grouped together under E_0 , which determines the end of processing and delivers data y_0 and z_0 meaningful for the user. We can capture both these elements using the tree structure that naturally fits the hierarchy of executions encoded with ProvONE. We call this tree the

restart tree as it indicates the initial set of executions that need to be rerun. The tree also provides references to the changed artefacts, which is useful to perform further steps of the ReComp meta-process. Fig. 6 shows in blue the restart tree generated as a result of change in artefacts b and e .

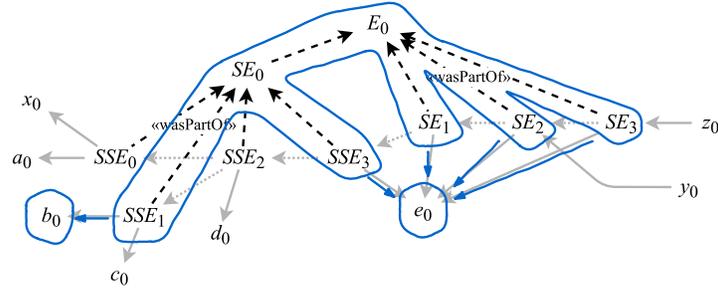


Fig. 6: An execution trace for the program shown in Fig. 5 with the restart tree and artefact references highlighted in blue. (\dashrightarrow) – the `wasPartOf` relation between executions; (\longrightarrow) – the `used statements`; ($\cdots\rightarrow$) – the `sequence of the E_j used z wasGeneratedBy E_i statements`.

Finding the restart tree involves building paths from the executions that used changed artefacts, all the way up to the top-level execution following the `wasPartOf` relation. The tree is formed by merging all paths with the same top-level execution.

3 Computing the Re-computation Front

Combining together all three parts discussed above, we present in Listing 1.1 the pseudocode of our algorithm to identify the re-computation front. The input of the algorithm is the change front CF that the ReComp framework keeps updating with every change observed. The output is a list of restart trees, each rooted with the top-level execution. Every node of the tree is a triple: $(E, [changedData], [children])$ that combines an execution with optional lists of changed data artefacts it used and sub-executions it coordinated. For executions that represent a simple black-box process the output of the algorithm reduces to the list of triples like: $[(E_i, [a_k, a_l, \dots], []), (E_j, [a_m, a_n, \dots], []), \dots]$ in which the third element of each node is always empty. For the example of a hierarchical process shown above in Fig. 6 the output would be $[(E_0, [], [(SE_0, [], [(SSE_1, [b_0], []), (SSE_3, [e_0], [])]), (SE_1, [e_0], []), (SE_2, [e_0], []), (SE_3, [e_0], [])])]$

The algorithm starts by creating the root node, `OutTree`, of an imaginary tree that will combine all independent executions affected by the change front. Then, it iterates over all artefacts in the `ChangeFront` set and for each artefact it traverses the chain of versions: `Item $\xrightarrow{\text{wDF}}$ Predl $\xrightarrow{\text{wDF}}$...` (line 4). For each

version it looks up all the executions that used particular version of the data (line 5). The core of the algorithm (lines 6–7) is used to build trees out of the affected executions. In line 6 a path from the affected execution to its top-level parent execution is built. Then, the path is merged with the `OutTree` such that two paths with the same top-level execution are joined into the same subtree, whereas paths with different root become two different subtrees on the `OutTree.children` list.

Listing 1.1: An algorithm to find the re-computation front.

```

1 function find_recomp_front(ChangeFront) : TreeList
2   OutTree := (root, data := [], children := [])
3   for Item in ChangeFront do
4     for PredI in traverse_derivations(Item) do
5       for Exec in iter_used(PredI) do
6         Path := path_to_root(PredI, Exec)
7         OutTree.merge_path(Path)
8   return OutTree.children

```

Listing 1.2 shows the `path_to_root` function that creates the path from the given execution to its top-level parent execution. First it checks if the given execution `Exec` has already been re-executed (lines 4–6). It does so by iterating over all `wasInformedBy` statements in which `Exec` is the informant checking if the statement is typed as `recomp:re-execution`. If such statement exists, `path_to_root` returns the empty path to indicate that `Exec` is not on the front (line 6). Otherwise, if none of the communication statements indicates re-execution by `ReComp`, `Exec` is added to the path (line 7) and algorithm moves one level up to check the parent execution (line 8). This is repeated until `Exec` is the top-level parent in which case `get_parent(Exec)` returns null and the loop ends. Note, `get_parent(X)` returns execution `Y` for which statement `X` `wasPartOf` `Y` holds.

Listing 1.2: Function to generate the path from the given execution to its top-level parent.

```

1 function path_to_root(ChangedItem, Exec) : Path
2   OutPath := [ChangedItem]
3   repeat
4     for wIB in iter_was_informed_by(Exec)
5       if typeof(wIB) is "recomp:re-execution" then
6         return []
7     OutPath.append(Exec)
8     Exec := get_parent(Exec)
9   until Exec = null
10  return OutPath

```

The discussion on other functions used in the proposed algorithm, such as `traverse_derivations` and `iter_used`, is omitted from the paper as they are simple to implement. Interested readers can download the complete algorithm written in Prolog from our GitHub repository.² Preliminary performance tests showed us

² <https://github.com/ReComp-team/IPAW2018>

execution times in the order of milliseconds when run on a 250 MB database of provenance facts for about 56k composite executions and a set of artefact documents of which two had 15 and 19 version changes. As expected, the response time was increasing with the growing length of the derivation chain.

4 Related Work

A recent survey by Herschel et al. [9] lists a number of applications of provenance like improving collaboration, reproducibility and data quality. It does not highlight, however, the importance of process re-computation which we believe needs much more attention nowadays. Large, data-intensive and complex analytics requires effective means to refresh its outcomes while keeping the re-computation costs under control. This is the goal of the **ReComp** meta-process [6]. To the best of our knowledge no prior work addresses this or a similar problem.

Previous research on the use of provenance in re-computation focused on the final steps of our meta-process: partial or differential re-execution. In [4] Bavoil et al. optimised re-execution of VisTrails dataflows. Similarly, Altintas et al. [2] proposed the “smart” rerun of workflows in Kepler. Both consider data dependencies between workflow tasks such that only the parts of the workflow affected by a change are rerun. Starflow [3] allowed the structure of a workflow and subworkflow downstream a change to be discovered using static, dynamic and user annotations. Ikeda et al. [10] proposed a solution to determine the fragment of a data-intensive program that needs rerun to refresh stale results. Also, Lakhani et al. [12] discussed rollback and re-execution of a process.

We note two key differences between the previous and our work. First, we consider re-computation in the view of a whole population of past executions; executions that may not even belong to the same data analysis. From the population, we select only those which are affected by a change, and for each we find the restart tree. Second, restart tree is a concise and effective way to represent the change in the context of a past, possibly complex hierarchical execution. The tree may be very effectively computed and also used to start partial rerun. And using the restart tree, partial re-execution does not need to rely on data cache that may involve high storage costs for data-intensive analyses [15].

Another use of provenance to track changes has been proposed in [8,11] and recently in [14]. They address the evolution of workflows/scripts, i.e. the changes in the process structure that affect the outcomes. Their work is complementary to our view, though. They use provenance to understand what has changed in the process e.g. to link the execution results together or decide which execution provides the best results. We, instead, observe changes in the environment and then react to them by finding the minimal set of executions that require refresh.

5 Discussion and Conclusions

In this paper we have presented a generic approach to use provenance annotations to inform a re-computation framework about the selection of past execution

that require refresh upon a change in their data and software dependencies. We call this selection the re-computation front. We have presented an effective algorithm to compute the front, which relies on the information about changes and annotations of re-executions. The algorithm can handle composite hierarchical structure of processes and help maintain the most up-to-date version of the dependencies. Overall, it is a lightweight step leading to the identification of the scope of changes, i.e. computing difference and estimating the impact of the changes, and then to partial re-execution.

In line with [1], we note that a generic provenance capture facility which stores basic information about processes and data is often not enough to support the needs of applications. For our algorithm to work properly, we have to additionally annotate every re-execution with the `wasInformedBy` statement, so the past executions are not executed again multiple times. This indicates that the ProvONE model defines only a blueprint with minimal set of meta-information to be captured which needs to be extended within each application domain.

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