



A framework for decision aiding (part 2)

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From part 1

- It is possible to treat the elements of the "decision space" (ω, c, d) in a coordinated way.
- If the elements are independent it is possible to eliminate them one-by-one, thus obtaining a final function or vector M1 of the (continuous or discrete) decision variables.
- On the contrary, if there is a dependence (i.e. the criteria depend on the states of nature) the elimination follows a forced path.
- Finally, if there is a mutual dependence you must proceed "along the diagonals" (by examining the behavior of the alternatives one by one).

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ExA – Palio \rightarrow (MC-RA, ranking) \rightarrow 6 – 2 (3) – 1

ExB – nurses \rightarrow (MC-SC, assign) \rightarrow 5 – 2 or 3 – 1

ExC – saus. \rightarrow (MC, cluster) \rightarrow 3 – 1

ExD – paths \rightarrow (MC, rating-rank)) \rightarrow 3 – 1
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Now let's consider specific tools

Tools for «point 2» problems

- (i) Perception
- (ii) Experiments & dec. tree

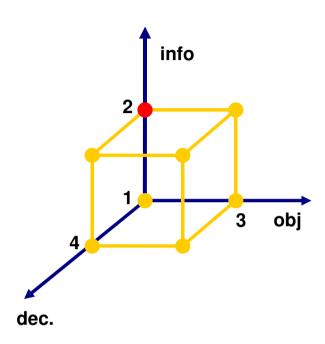
(i) A real decision process: perception

- Uncertainties (non deterministic context, ...)
- Complexity (problem dimension, non linearity, ...)
- Several stakeholders (distributed decision power)
- Different rationalities (criteria and preferences)
- Different time horizons (often)
- Need of simulation models



The DM perception of the problem

Decision processes in a non-deterministic context



Information partial [*]

Objectives one

Dec. makers one

- 1. Math. programming
- 2. Risk analysis
- 3. Multi-objective (criteria)
- 4. Group choice
- 5, 6, 7, 8 **→**

[*] → non-deterministic context



perception & mental models

Two (opposite) theories

(a) Normative theory ———— what the DM should do

(b) Cognitive theory → what the DM
(descriptive) really does → experimental tests

When they are the same ?

if the (**single**) DM has all the information (**in a deterministic way**) and has clearly in mind *the* criterion (**one**) of evaluation



ideal problem → point 1

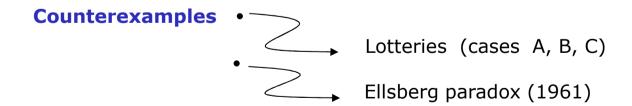
Normative theory: principles & (counter)exemples

N-1° Principle of INVARIANCE

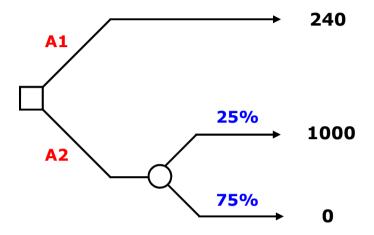
→ Equivalent (from the logical point of view) versions of the same problem must produce the same choice

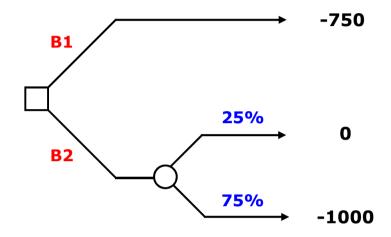
Examples

- Change names or positions for the options
- Change measure units
- > Add a constant value for all the results



Lotteries (case A and case B)





Better A1 or A2?



better ...

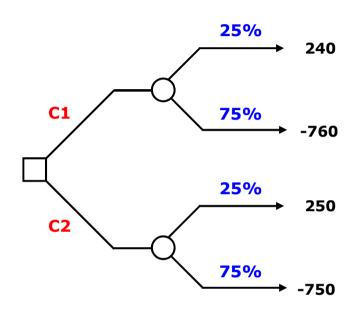
Better B1 or B2?

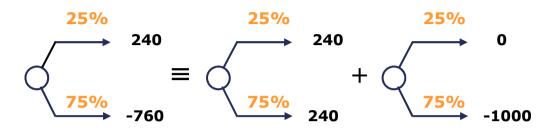


better ...

Lotteries (case C)

But notice that ...







Better C1 or C2?



better ...



 $C1 \rightarrow sum of A1 and B2$

 $C2 \rightarrow sum of A2 and B1$

Ellsberg



50 (b) α (b) **50** (n) **100-** α (n)

White ball win



Better to take from A or B?



better ...

ambiguity aversion

Now you have a second chance (after the ball is re-inserted)



the same ...

Black ball win



Better to take from A or B?



better ...

ambiguity aversion?

Cognitive theory: a first principle



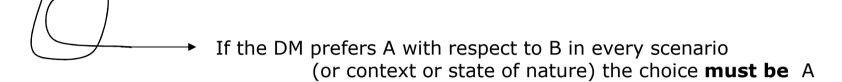


Given the two preferences on A1 and B2, it is **not guaranteed** that their aggregation (C1) is the preferred one

- Caution: do not combine too easily the options
- Normally, the ambiguity is avoided, "even if this is not rational " (Ellsberg)

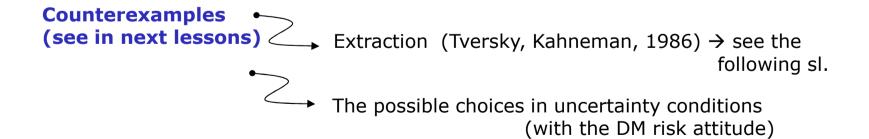
Normative theory: principles & (counter)examples

N-2° Principle of DOMINANCE



- **Examples**
- > I prefer to be missionary (with respect to engineer) in peace and prefer to be missionary (...) in war
- > I prefer chicken with respect to beef (when there is nothing else) and I prefer chicken ... also when there is fish

so the choice ... is better then the choice ...



Extraction (in two conditions)

room 1

,		•
n. of balls	situation A	situation B

90 white	0	0
6 red	45	45
1 green	30	45
1 blue	-15	-10
2 yellow	-15	-15

room 2

n. of balls	situat. C	situat. D	n. of balls
90 white	0	0	90 white
6 red	45	45	7 red
1 green	30	-10	1 green
3 yellow	-15	-15	2 yellow
	'	•	1

Better A or B?



better ...

Better C or D?



but C ≡ A and D ≡ B

Choice (in two conditions)

	w1	w2	w3	w4	w5
Invest	0	45	30	-15	-15
Build	0	45	45	-10	-15
p(w)	.90	.06	.01	.01	.02

presentation 1

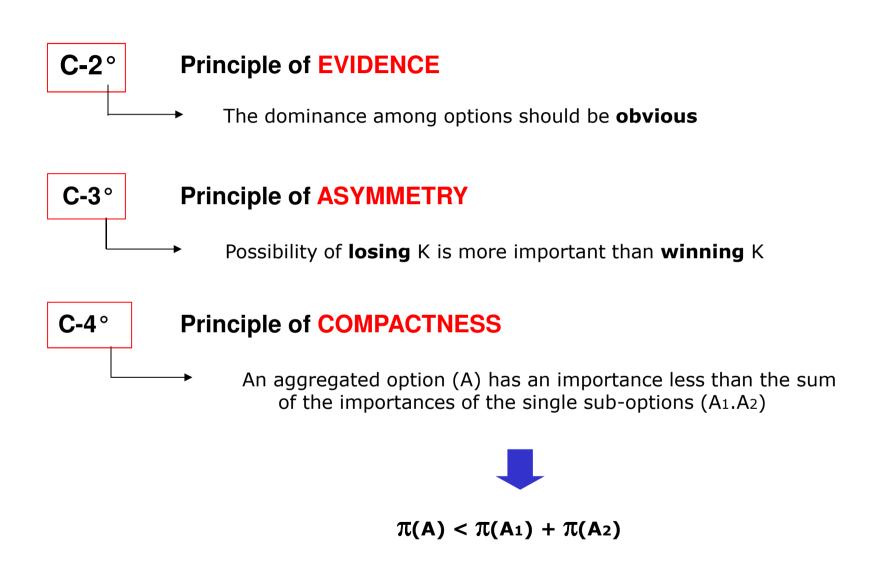


	W1	w2	w3	W4
Invest	0	45	30	-15
p(w)	.90	.06	.01	.03
Build	0	45	-10	-15
p(w)	.90	.07	.01	.02

presentation 2



Cognitive theory: three more principles



Normative theory: principles & (counter)examples

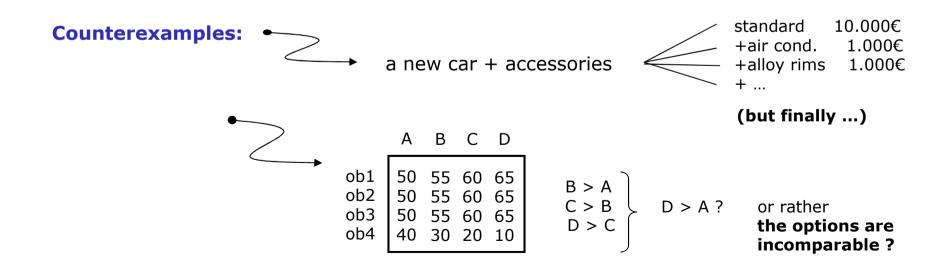
N-3°

Principle of TRANSITIVITY

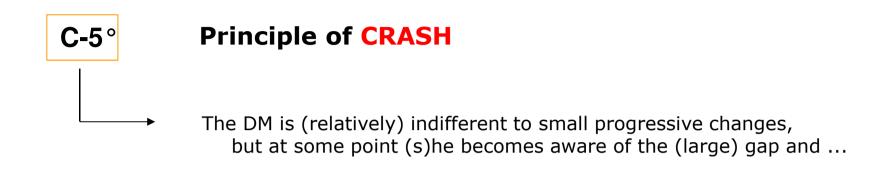
If the decision prefers A over B and B over C, then A **must** be preferred over C

Examples:

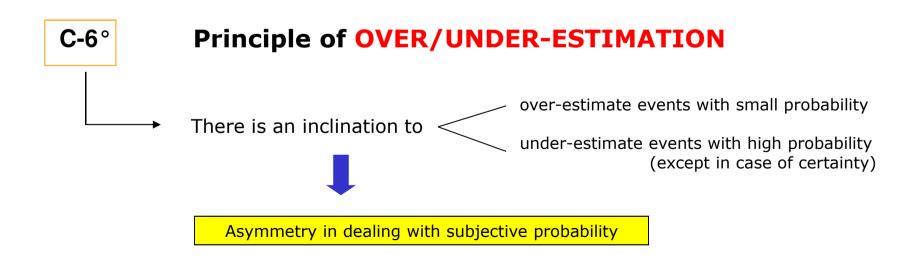
- > V. Rossi is better than Stoner, and Stoner is better than Melandri, so ...
- Buying emission units (Kyoto prot.) is better than cutting the production, and cutting the production is better than not respecting the emission constraints, so ...



Cognitive theory: progression vs. crash



Cognitive theory: estimation



A famous example: the frame effect

- **Avian influenza (possible death)**
- Group at risk: 600 people

Protocol A 200 people will survive $\begin{cases} \text{with } p = 1/3 & 600 \text{ will survive} \\ \text{with } p = 2/3 & \text{nobody will survive} \end{cases}$

Better A or B?

Protocol A 400 people will die

Protocol B $\begin{cases} with p=1/3 \text{ nobody will die} \\ with p=2/3 600 \text{ will die} \end{cases}$

Better A or B?

- Aversion to the risk in case of winnings (better A)
- **Propensity for risk in case of losses (better B)**

(ii) Experiments: axioms of probability theory

- **A1** Probability $\mathbf{p(e)}$ of an event (e): value between < $\stackrel{0}{<}$ (impossible) 1 (certain)
- A2 Complementary probability (the event does not occur): 1-p(e)
- A3 For events (e₁, e₂, ..., e_k) that are mutually exclusive : $p(e_1 ext{ or } ... ext{ or } e_k) = p(e_1) + ... + p(e_k)$
- A4 For 2 independent events (e_1, e_2) : $p(e_1 \text{ AND } e_2) = p(e_1) * p(e_2)$

$$p(e1/e2) = p(e1 \text{ AND } e2)$$

$$p(e2)$$

$$p(e2)$$

$$p(e2/e1) * p(e1)$$

$$p(e2)$$

Example follows

Probabilities before and after the experiment (Bayes)

 $\omega 1 = good weather$

 ω_2 = bad weather

ω 1	ω2	
.80	.20	p(w) before

y1 .55

y2 **.25**

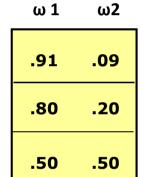
y3 **.20**

p(y)

ω1

ω2

 $p(\mathbf{W},y)$



 $p(\mathbf{W}/y)$

y1 = clear

y2 = variable

y3 = rain

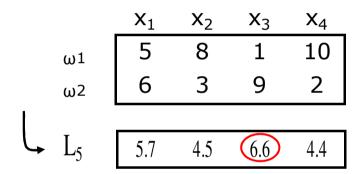
y1	.63	.25
y2	.25	.25
у3	.12	.50

 $p(y/\omega)$ \longrightarrow this case does not make much sense

after

Uncertainty: the expected value

- If the probability distribution of ω is available ...
- ... consider the logic of the expected value (to be maximized)
- In the example \rightarrow p(ω_1) = 0.3, p(ω_2) = 0.7



 $\bar{f}(x_j)$ = the expected value is calculated multiplying the values $f(x_j, \omega_i)$ by the probabilities $p(\omega_i)$ and then summing them.

 Sometimes also variance is considered (to be minimized)

The expected value logic removes the dependence from the state of nature (if probabilities are available)



$$\sigma_{j}^{2} = \sum_{i} \left[f(\boldsymbol{\sigma}_{i}, x_{j}) - \overline{f}(x_{j}) \right]^{2} \cdot p(\boldsymbol{\sigma}_{i})$$

i:stateof nature

j∶alternati**v**

 $\overline{f}(x_j)$: expected value of alternative j



0.21 5.25 13.44 13.44

An example: oil extraction

- A potentially rich area
- States of nature $\rightarrow \omega 1$: oil; $\omega 2 = \text{no oil}$
- Possible actions → x1: buy taking full advantage

x2: rent for 50 years

x3: rent for 10 years

x4: do nothing

	x 1	x2	х3	x 4
ω_1	100	80	20	0
ω_2	-30	-6	-4	0

Experiment (a sample drill):

- y1 = probably there is oil
- y2 = analysis not clear
- y3 = probably there is no oil

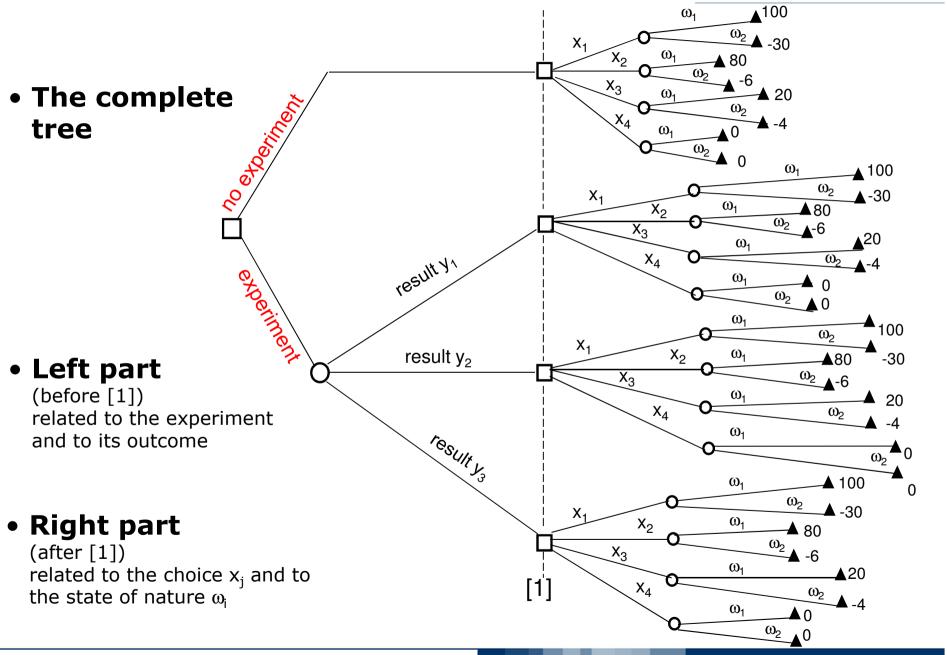
$$p(\omega) = \begin{bmatrix} 0.50 \\ 0.50 \end{bmatrix} \leftarrow \begin{bmatrix} \omega_1 \\ \omega_2 \end{bmatrix} \begin{bmatrix} 0.18 & 0.24 & 0.08 \\ 0.02 & 0.16 & 0.32 \end{bmatrix} \longrightarrow \begin{bmatrix} 0.90 & 0.60 & 0.20 \\ 0.10 & 0.40 & 0.80 \end{bmatrix}$$

$$p(\psi) = \begin{bmatrix} 0.20 & 0.40 & 0.40 \end{bmatrix}$$

$$p(\psi) = \begin{bmatrix} 0.20 & 0.40 & 0.40 \end{bmatrix}$$

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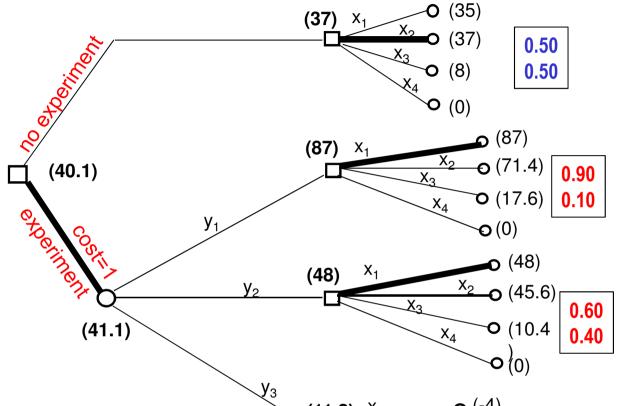
Decision tree: construction



The final outcome: a strategy

Node labels

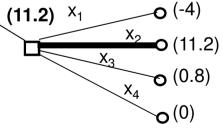
- O → expected value
- □ → best option



Conclusion:

- do the experiment
- select the following **strategy**

$$\begin{array}{c|c}
 & \text{if } y_1 \rightarrow x_1 \\
 & \text{if } y_2 \rightarrow x_1 \\
 & \text{If } y_3 \rightarrow x_2
\end{array}$$



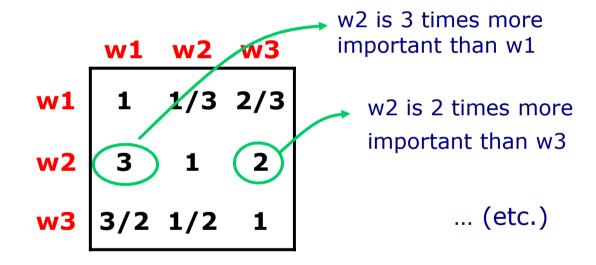
Tools for «point 3» problems

- (i) Pairwise comparison
- (ii) Choquet integral

(i) Pairwise comparison

To obtain the vector w of the weights it is possible to do a set of pairwise comparisons, thus obtaining a matrix A

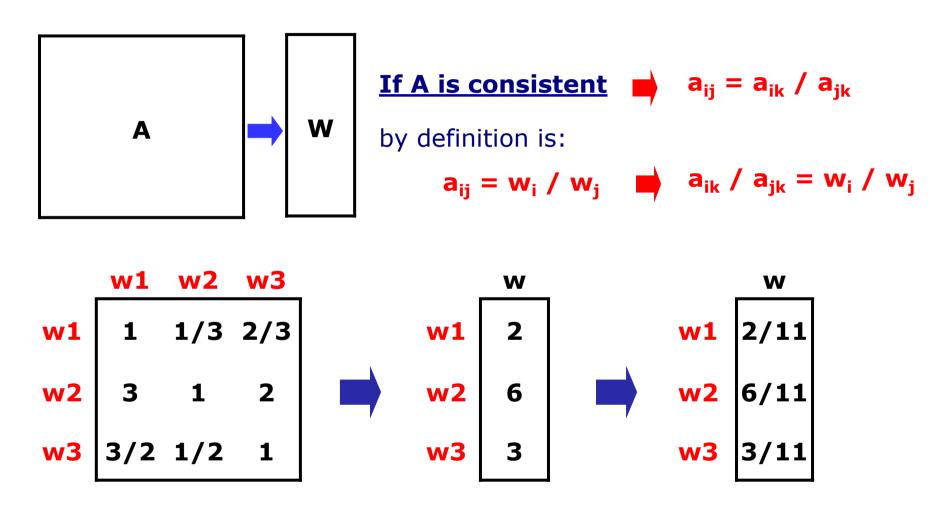
Example



Matrix A is:

- positive \rightarrow $a_{ij} > 0$
- reciprocal \rightarrow $a_{ij} = 1/a_{ji}$
- consistent \rightarrow $a_{ik} = a_{ij} \cdot a_{jk}$

From matrix A to vector w



All the columns represent (with a coeff. of proportionality)
the vector w easy case!

Eigenvalues

> Matrix A consistent



- columns proportional



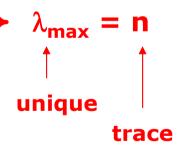
- rank of the matrix = 1
 - only one eigenvalue $\lambda_{max} \neq 0$
- Matrix A positive



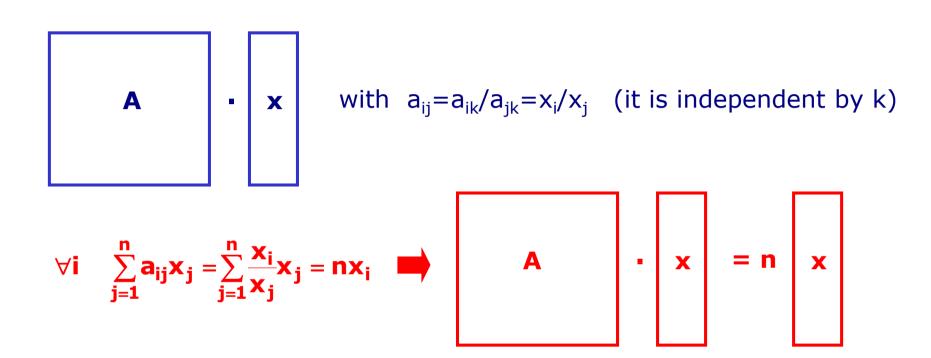
- trace = sum of eigenvalues
- Elements of the diagonal = 1 (all)



- trace = n



Vector of the weights



x is the main eigenvector



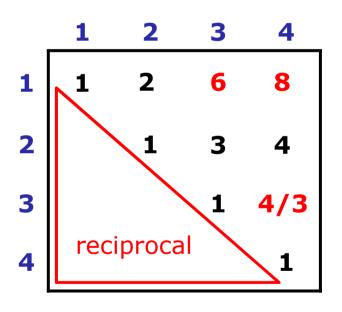
each column is proportional to the eigenvector

vector w of the weights:

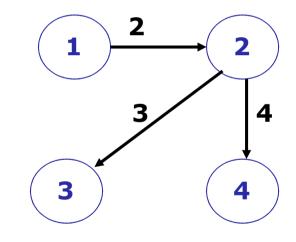
w is the main eigenvector normalized (sum = 1)

Supporting (spanning) tree

The minimum number of pairwise comparisons is n-1 but only if they are «spanning» the graph



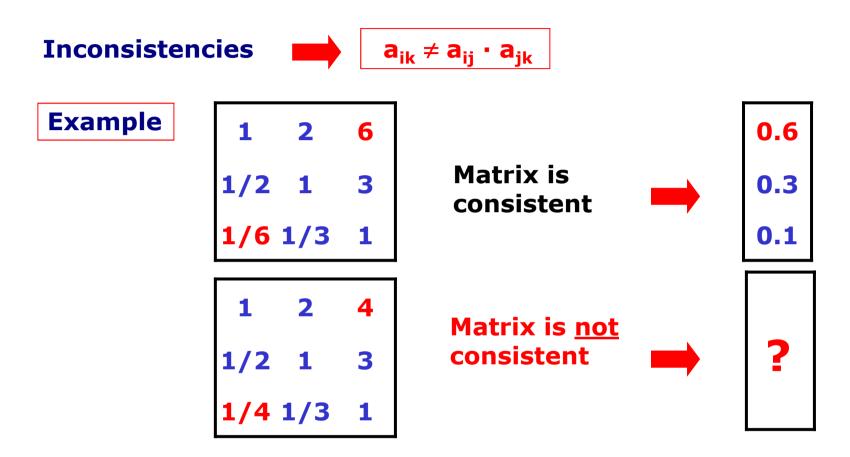




No isolated nodes

$$a_{13} = a_{12} \cdot a_{23}$$
 $a_{14} = a_{12} \cdot a_{24}$
 $a_{34} = a_{32} \cdot a_{24} = (1/a_{23}) \cdot a_{24}$

If matrix A is not consistent?



We must estimate the main eigenvector (and the error)

If the consistency error is "small" OK (if no ...)

What about the cons. error μ ?

$$\begin{array}{lll} \textbf{A*x} = \lambda_{max} * \textbf{x} & \forall i & \sum\limits_{j=1}^{n} a_{ij} \textbf{x}_{j} = \lambda_{max} \textbf{x}_{i} & (\text{row i-th of the matrix}) \\ & \forall i & \lambda_{max} = \sum\limits_{j=1}^{n} a_{ij} & \Longrightarrow & \lambda_{max} = \sum\limits_{j=1}^{n} \sigma_{ij} \\ & & \sum\limits_{i=1}^{n} \lambda_{max} = \sum\limits_{i=1}^{n} \sum\limits_{j=1}^{n} \sigma_{ij} \\ & & & n\lambda_{max} = n + \sum\limits_{1 \leq i < j \leq n}^{n} \left(\sigma_{ij} + \frac{1}{\sigma_{ij}}\right) \\ & & & \sum\limits_{1 \leq i < j \leq n}^{n} \left(\sigma_{ij} + \frac{1}{\sigma_{ij}}\right) = \textbf{n}(\lambda_{max} - \textbf{1}) \end{array}$$

Divide the result by n(n-1) and subtract 1

$$\mu \implies \frac{\sum\limits_{1 \leq i < j \leq n}^{n} \left(\sigma_{ij} + \frac{1}{\sigma_{ij}}\right)}{n(n-1)} - 1 = \frac{n(\lambda_{max} - 1)}{n(n-1)} - 1 \implies \mu = \frac{\lambda_{max} - n}{n-1}$$

If **A** consistent: $\lambda_{max} = \mathbf{n} \rightarrow \mu = \mathbf{0}$

(ii) Going back to the MAUT ... Choquet

What happens if the attributes (objectives or criteria) are not mutually independent?

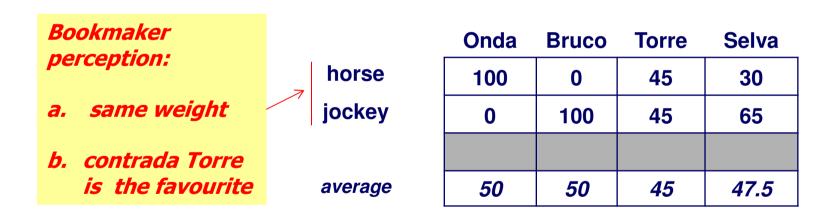
OR

if it is not possible to demonstrate their independence?

The Choquet integral

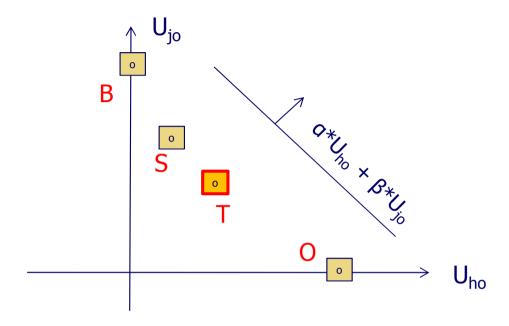
Palio di Siena (ExA)

You have to help a Palio bookmaker. His evaluation concerning the contrada's chance to win are based on two attributes: values (utilities) of horse and jockey. The situation (utilities) of the four contrada are in the following table.



Which weight is it possible to assign to the two attributes?

In the utility space ...



- No couple of weights (a,β) determines the victory of Torre, the contrada indicated by the bookmaker as the best one.
- It's necessary to change the model ...

MAUT modifications

- Association of a unique value U (utility) to each alternative (among the n, finite or infinite, possible alternatives):
 U expresses the overall satisfaction with respect to the m attributes t₁, t₂, ... t_m considered.
- It is necessary to obtain the utility function U on the base of the utilities of each attribute.
- Both comments are true, but it is necessary to take care of:
 - (i) synergies,
 - (ii) redundance

Example: a student grant

You have to help the commission for an Erasmus grant. The evaluation is based on three attributes, the results of the student in **M** (mathematics), **F** (physics), **L** (literature). The situation is the following.

M –	mat	hem	atics	\rightarrow

F – physics →

L – literature →

Average

Minimum

Maximum

Colorni	Luè	Noce	Lia
9	5	7	8
8	6	7	5
5	10	7.5	8
7.33	7	7.16	7
5	5	7	5
9	10	7.5	8

The commission (decision maker) says that:

- 1. criteria **M** and **F** have the same importance (weight)
- 2. criteria **M** and **F** are more relevant than **L** (1.5 time)
- 3. criteria **M** and **F** are redundant (a student good in **M** is also ...)
- 4. students are favorite if they are balanced (synergy M-L and F-L)

Case of criteria not mutually independent

- It is based on the definition of two elements:
 - a capacity (fuzzy measure)
 - a sum (Choquet integral)

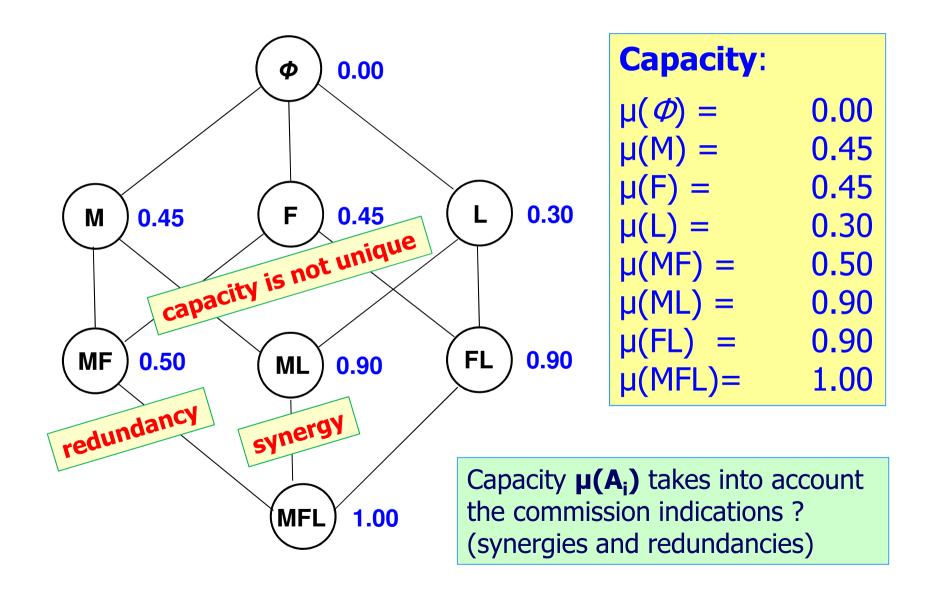
Capacity:

- if $M = \{1, ..., m\}$ is the attributes (criteria) set
- **capacity** is a function $\mu: 2^M \rightarrow [0, 1]$ such that $\mu(\Phi) = 0$; $\mu(M) = 1$; $\mu(A) \leq \mu(B)$ if A is included in B

Choquet integral:

- the Choquet integral C_{μ} is the sum (with i=1,...,m) $C_{\mu} = [f(\sigma_1) f(\sigma_0)] * \mu(A_1) + ... + [f(\sigma_m) f(\sigma_{m-1})] * \mu(A_m)$ with $A_i = {\sigma_i, \sigma_{i+1}, ..., \sigma_m}$ and σ_i permutation with $f(\sigma_i)$ ascending

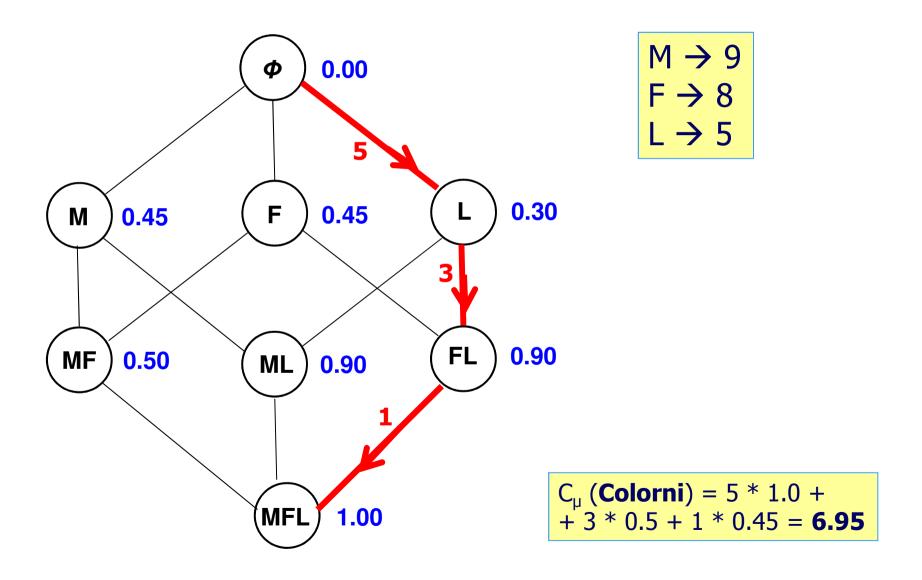
Representation (lattice)



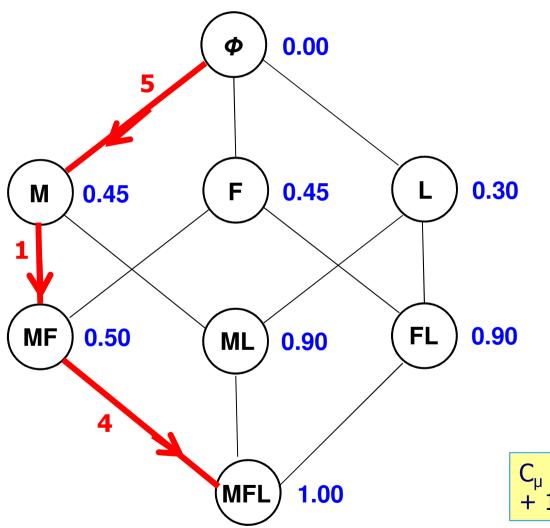
Results

- There are n candidates (n=4: Colorni, Luè, Noce, Lia)
- For each it is necessary to calculate C_u (Choquet integral)
- For each it should be necessary to define a permutation
- It is better to use a graphic scheme (see next slide)
- Each candidate has an ascending order of results
- It is possible to represent it as a path between ϕ and MFL
- To each node an increment Δ is associated (added value)
- To each node a weight is associated (weight is the capacity)
- C_µ value is calculated with a weighed sum

Student Colorni



Student Luè



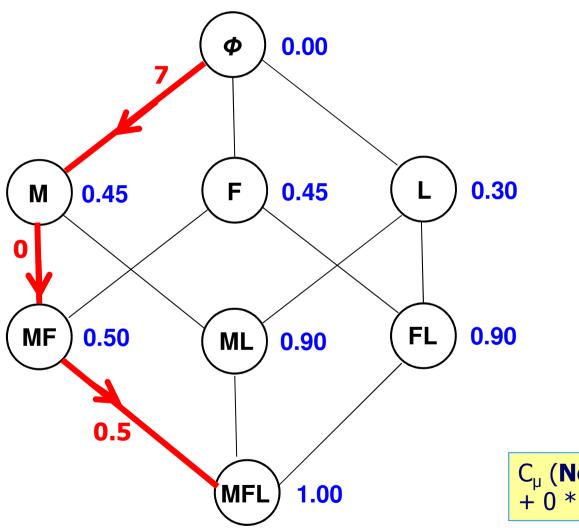
$$M \rightarrow 5$$

$$F \rightarrow 6$$

$$L \rightarrow 10$$

$$C_{\mu}$$
 (**Luè**) = 5 * 1.0 + + 1 * 0.9 + 4 * 0.30 = **7.10**

Student Noce



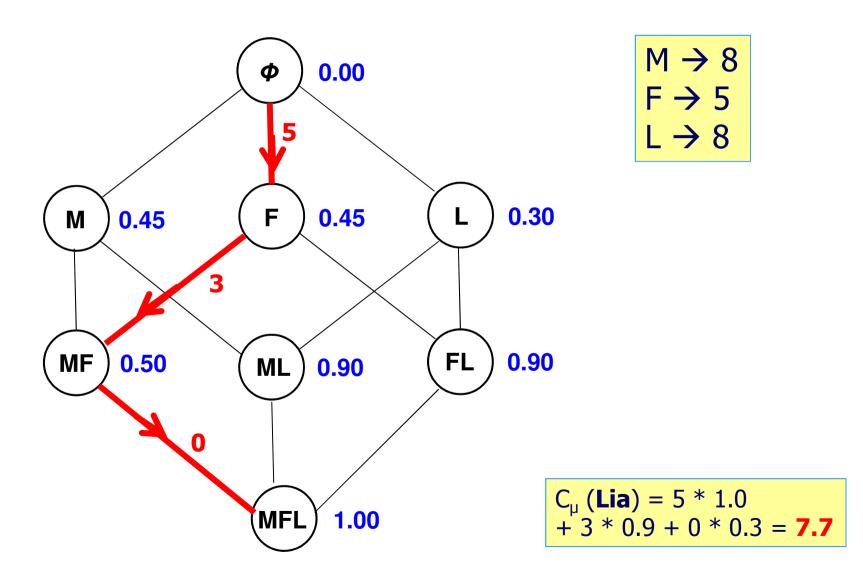
$$M \rightarrow 7$$

$$F \rightarrow 7$$

$$L \rightarrow 7.5$$

$$C_{\mu}$$
 (**Noce**) = 7 * 1.0 + 0 * 0.9 + 0.5 * 0.3 = **7.15**

Student Lia



Final result

- Colorni seemed to be the best candidate
- But we weren't considering the redundancies
- The best one is Lia, thanks to the synergy
- A graph is used for calculating (lattice 2^M)
- Increment represents the added value

In this way it is possible to take into account:

- \square synergies \rightarrow given $\mu_{ii} > \mu_i + \mu_i$
- \square redundancies \rightarrow given $\mu_{ij} < \mu_i + \mu_j$

Palio di Siena (more)

Bookmaker's perception:

- (i) same weights to the attributes
- (ii) Torre is the favourite

The couple horse-jockey makes contrada Torre the favorite for the bookmaker. The weights have to be given: to the 2 attributes and to the combination of these > how?

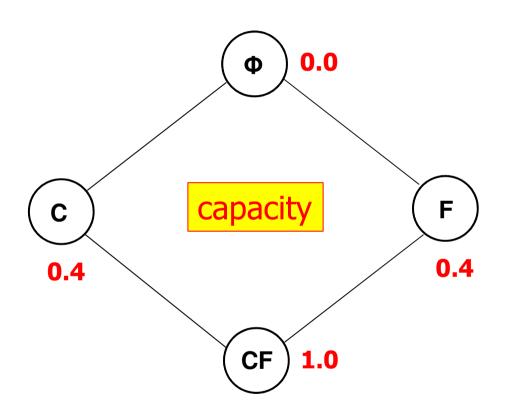
Horse Jockey

μ_i	=	
μ_j	=	
μ_{ii}	=	

Onda	Bruco	Torre	Selva
100	0	45	30
0	100	45	65

Synergy \rightarrow $\mu_i + \mu_j < \mu_{ij}$

The "horse/jockey" factor



Onda

C = 100

F = 0

Bruco

C = 0

F = 100

Torre

C = 45

F = 45

Selva

C = 30

F = 65

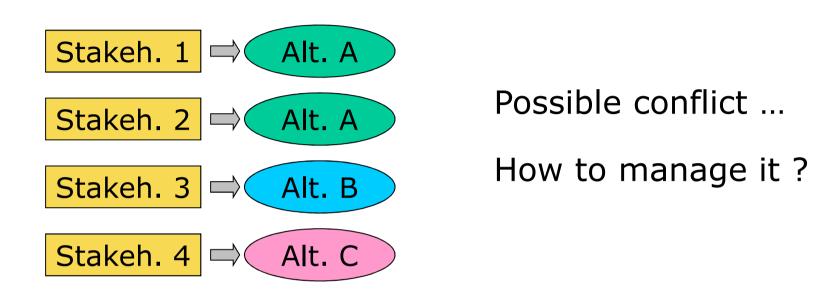
$$C_{\mu}$$
 (**O**) = ..., C_{μ} (**B**) = ..., C_{μ} (**T**) = ..., C_{μ} (**S**) = ...

Tools for «point 4» problems

- (i) Two approaches
- (ii) Peer evaluation

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(i) The two approaches to group decision



- Research of the critical points
- Proposing new/mitigating/compensative measures (from "dividing" to "enlarging the cake")
- Do "win-win» solutions exist? (game can be not a zero-sum game)

Create information / 1

Analytic support: calculation of the indices of conflict,
based on the distances between decision makers.

- ↓ Impacts (numbers of impacts may not coincide):
 - o distance of each player from the average value of each impact
- Utility funct. → examination of those which do not coincide
- **Weights**: construction of distance D matrix

$$D = [d_{ij}], \quad \text{with } d_{ij} \ge 0 \quad \text{(symmetric ?)}$$



Distance matrix among [weights vectors of] decision makers

Create information / 2



Individual indeces of conflict:

- sum for rows = distance of the row player from the others
- sum for columns = distance of others from the column player

Global indeces of conflict:

- \square number $d_{ii} \neq 0 \rightarrow$ number of different vectors of weights
- \square average distance among weight vectors
- \square max $d_{ij} \rightarrow$ maximum level of conflict among two players

♥ Barycentric solution:

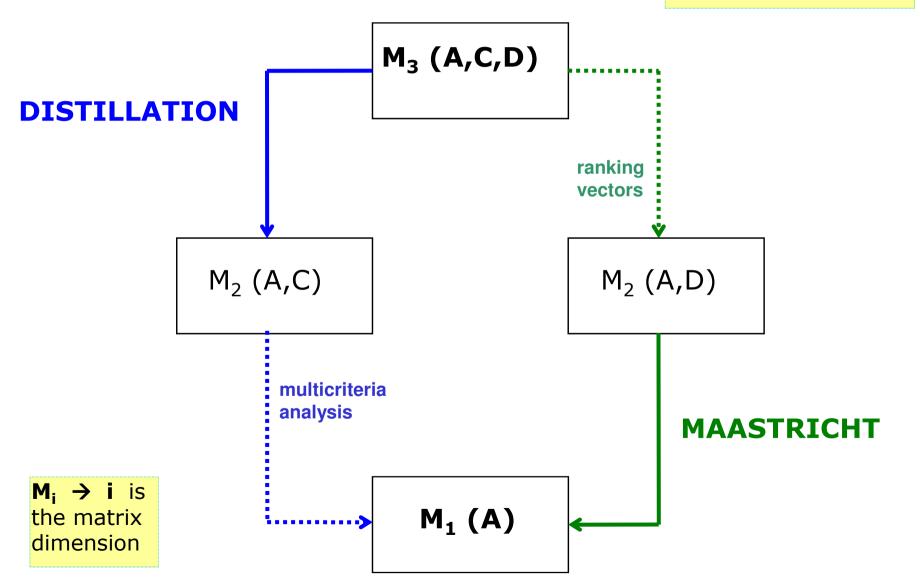
vector at the minimum distance from the vectors of the others

The two approaches

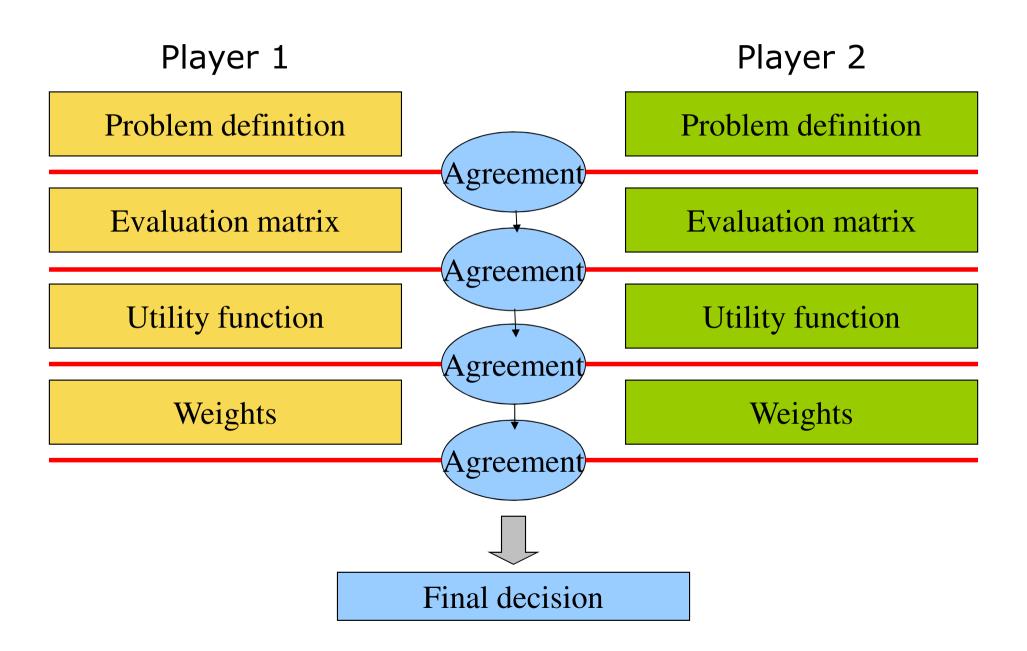
A = alternatives

C = criteria

D = dec. makers



Distillation



Distillation: compromise research

- ♥ Cooperative approach: trust building
- Decision makers move to barycentric position
 - synchronous method → together
 - □ a-synchronous method → the first is the most critical decision maker
- ♦ For each step:
 - information about global conflict (global conflict index)
 - information about the most critical decision maker (individual conflict index)

Distillation: to the barycenter

Weighted barycentric vector

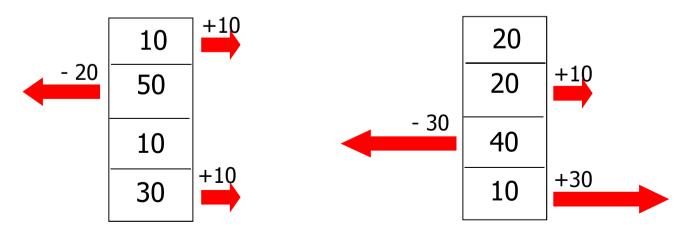
20
30
10
40

We calculate the distances between the components of the vectors of the weights of each decision maker and the components of the weighted barycentric vector

Weights dec. maker 1

Weights dec. maker 2

... (others)



Maastricht

Decision maker 1

Decision maker 2

Decision maker n

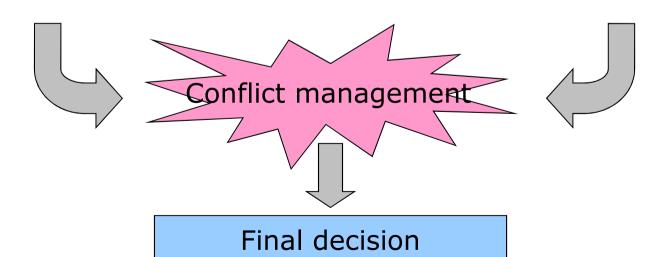
Multi criteria analysis (or other ...):

Sorting creation 1

....

Multi criteria analysis (or other ...):

Sorting creation n



(ii) Peer evaluation

Have all the decision makers the same importance?

- **♦ Weights determined a priori:**
 - a meta-decision maker exists;
 - he has a weight proportional to the number of people that he represents.
- Weights determinated by the group itself → cross-check, peer evaluation:
 - □ (1) average method
 - □ (2) eigenvector method
 - ✓ player can assign a weight to himself,
 - ✓ player must assign weights just to other players.

1. Average method

Player **Di** can vote to himself

	D1	D2	D3
D1	0.80	0.10	0.10
D2	0.05	0.70	0.30
D3	0.15	0.20	0.60

w 0.333 0.350 0.317

Vectors of the weights expressed by each player (column sum = 1)

Average vectors of the weights of the players

Inconsistent → players have the same relevance!

2. Eigenvector method

Player **Di** can vote to himself

	D1	D2	D3
D1	0.80	0.10	0.10
D2	0.05	0.70	0.30
D3	0.15	0.20	0.60

Vectors of the weights expressed by each player (column sum = 1)

$$Sw = w$$



Sw = λ **w** (principal eigenvalue = 1)

Vectors of the weights of the players

W

0.330

0.363

0.307

A paradox

Rule (now) → player **Di** can not give a weight to himself

http://en.wikipedia.org/wiki/Perron-Frobenius theorem L'assioma del cazzone **D2 D3 D1 D4** W 0 **D1** $\mathbf{0}$ ()**D2** ()() \mathbf{O} 0.5 D1 and D3 have no **preferences** (> 0), so **D3** ()()()D1 and D3 p. of view are **D4** 0.5 not relevant !!!

Possible solutions:

- each player has to vote at least for two players;
- ⋄ 0 can not be used (weights ≥ predeterminated ε).

Veto → United Nations Security Council

15 members, 5 can veto (USA, Russia, China, France, Great Britain)

Rule → a resolution is approved if:

- (i) gets at least 9 votes,
- (ii) there is no veto (from 1 of the 5).



How to determinate the weight of the members (USA, Russia, China, ..., D1, D2, ..., D9, D10) and coalition threshold in order to simulate UN Security Council working process ???

Service design

Green Move

Objective: design & test an electric car-sharing system in Milan

Coordinating a 2½ years project financed by the Lombardia Region (5 millions €), involving 8 research centers of Politecnico di Milano

Outcome:

- the design of a full scale service
- a trial with a limited number of docking stations in Milan

Switch from "buy a vehicle" paradigm to "buy mobility services"

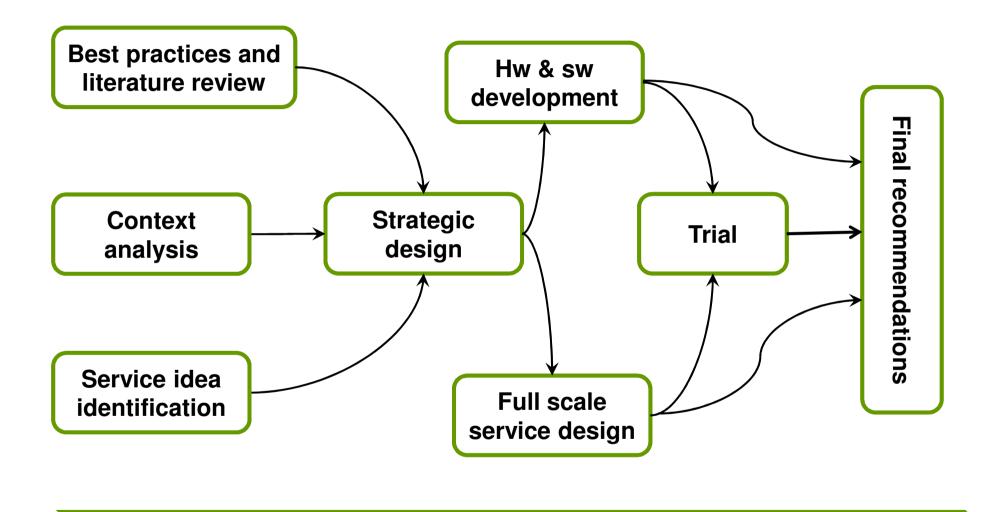






The scheme

Mar 2011



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Oct 2012

POLITECNICO DI MILANO

Sept 2013

How to design/formalize the service?

Problem characteristics:

- different actors and stratification of governance levels,
 e.g. public administration (municipality, region), associations, ...
- uncertainty in the definition of the variables,
 e.g. future policies for urban mobility, travel demand estimation for a non-existing service
- conflicting criteria,
 e.g. costs vs territorial coverage (such as in BikeMI)
- structuring the problem itself is an issue,
 e.g. definition of the configuration options to be evaluated is a key issue (Hull and Tricker, 2005; Kelly et al., 2008; Jones et al., 2009)

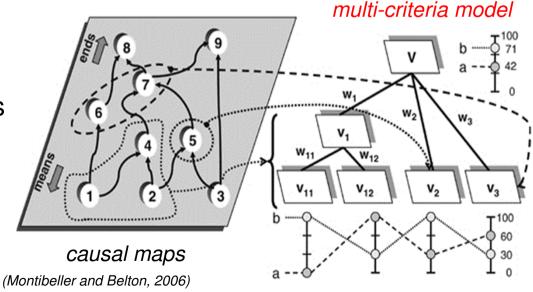
How to formalize the complexity?

Casual maps & MCDA

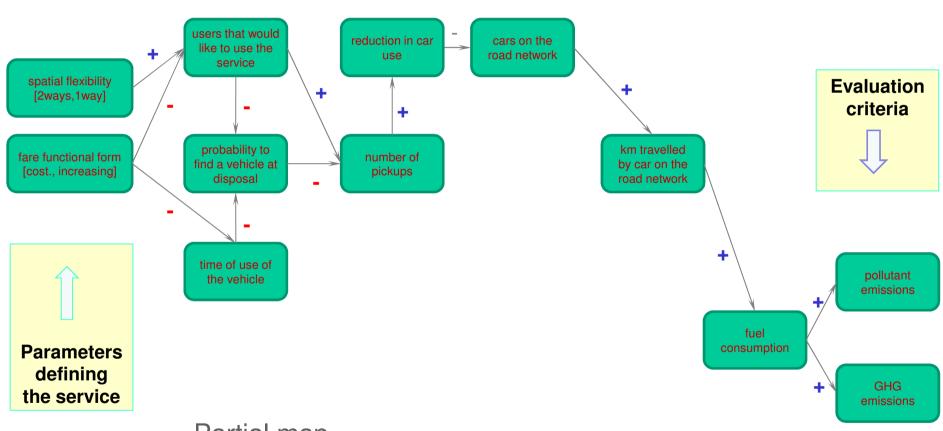
Integration of causal maps with multi-criteria analysis:

- a powerful way of capturing decision-makers' views
- widely used in problem-structuring (Rosenhead and Mingers, 2004)
- model the effects of a link (qualitative or quantitative methods)

definition of
 aggregation rules
 qualitative → experts
 quantitative
 models (e.g.
 demand analysis)



A (partial) map for GM



Partial map for the design of a vehicle sharing service

Parameters

- 1. Type of vehicle (EV, hybrid, ICE)
- 2 Service area
- 3. Capillarity and intermodality
- 4. Spatial flexibility → 1w-2w
- 5. Flexibility of service → temporal flexibility of booking
- 6. Fare:
 - 6.1. modes (hourly, km)
 - 6.2. function type (concave, convex, linear)
 - 6.3. level (high, medium, low)
- 7. Economic incentives (parking, congestion tax, LPT)
- 8. Incentives for service (areas with traffic restrictions, lanes ...)
- 9. Re-allocation model
- 10. Mechanisms for promotion and marketing

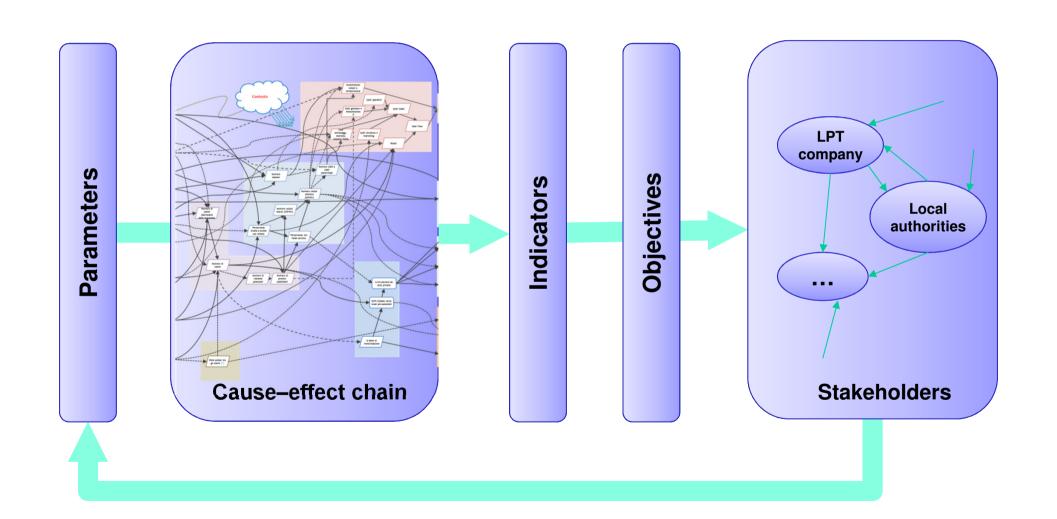
Indicators

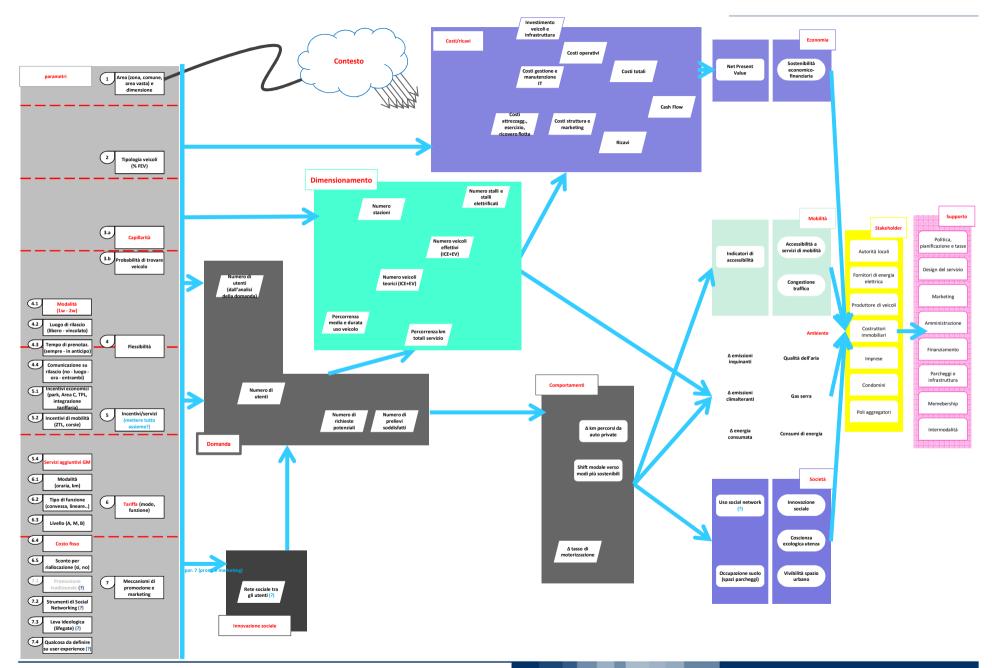
After the setting up of different options (alternatives), they can be evaluated and compared thanks to adequate indicators.

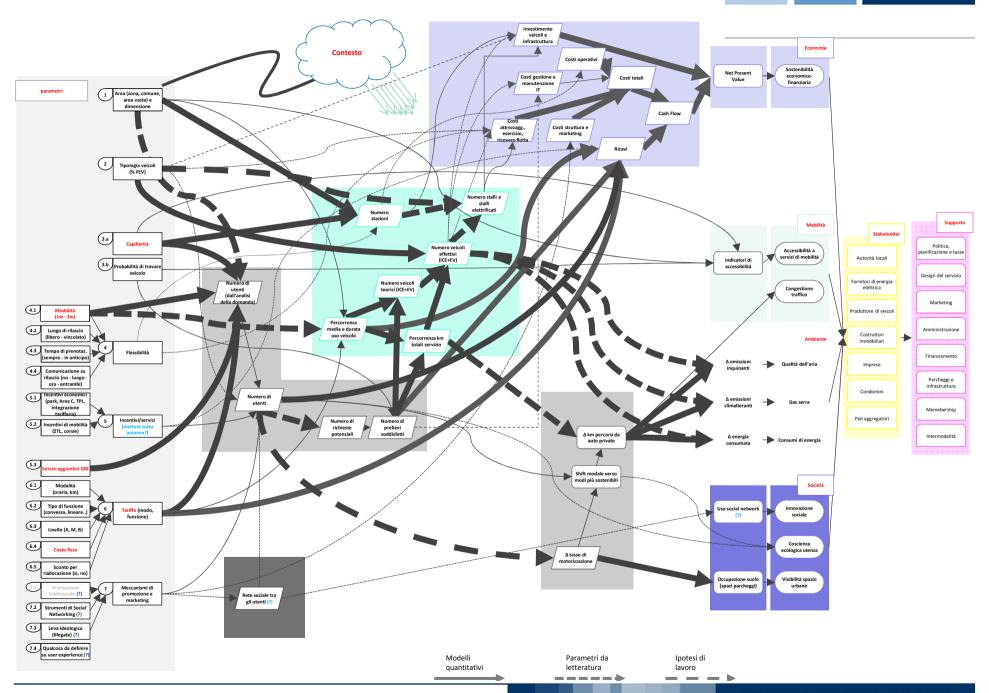
Evaluation and performance indicators (to measure the achievement of the objectives of stakeholders):

- Net Present Value
- Δ km traveled on the network
- Δ greenhouses gases
- Δ polluting emission
- Modal shift to sustainable mobility
- Number of users
- Connection in the social network
- Space occupied by parking
- Accessibility indicators
-

Flow chart







Conclusions (part 2)

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Thank you