

# Positive spanning sets and their connections to polyhedra

Clément Royer

LIPN, 19 mars 2026

**Dauphine**  
UNIVERSITÉ PARIS

PSL 

**LAMSADE**  
UMR 7243





*Denis Cornaz, Sébastien Kerleau, Warren Hare, Gabriel Jarry-Bolduc*



*Denis Cornaz, Sébastien Kerleau, Warren Hare, Gabriel Jarry-Bolduc*

## Disclaimer

- Talk/Plots based on Sébastien's thesis (Nov. 2025).
- Less polyhedra than I planned (sorry)
- But graphs, polytopes, and pictures!

# Motivation: Dauphine's *Nouveau Campus*



- Building renovation, one wing at a time.
- Faculty/Staff to be moved during renovation.

**Our task:** Allocate office space during renovation.

## Our model for the Dauphine problem

- Huge integer LP, solved via Gurobi.
- $\sim 20$  hyperparameters defining the model.
- Parallel runs on the department server.

**Sub-task:** Optimize hyperparameters to get the best LP optimal value.

## Our model for the Dauphine problem

- Huge integer LP, solved via Gurobi.
- $\sim 20$  hyperparameters defining the model.
- Parallel runs on the department server.

**Sub-task:** Optimize hyperparameters to get the best LP optimal value.

## Problem challenges

- Cannot differentiate (easily) within Gurobi.  
→ **Derivative-free algorithms!**
- Cannot solve certain instances (48 hours for a feasible point!)  
→ **Resiliency to straggler evaluations.**

# Blackbox optimization problem

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \quad f(x)$$

## Blackbox/Derivative-free optimization

- **Derivatives unavailable for algorithmic use.**
- Only access to values of  $f$ .
- **Cost** Number of **function evaluations**.
- Those can take a long time to compute!

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \quad f(x)$$

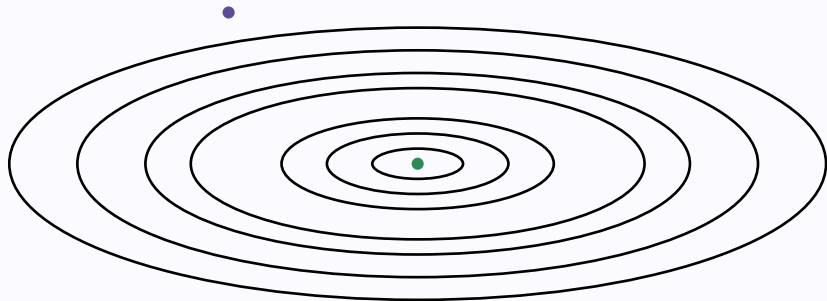
## Blackbox/Derivative-free optimization

- **Derivatives unavailable for algorithmic use.**
- Only access to values of  $f$ .
- **Cost** Number of **function evaluations**.
- Those can take a long time to compute!

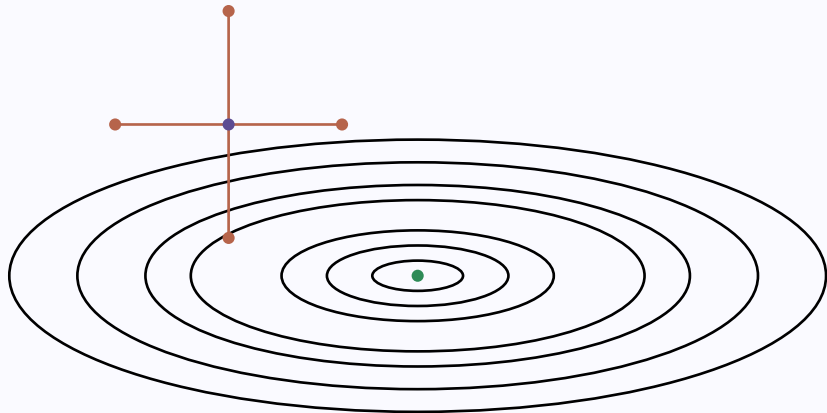
## Direct search methods

- Proceed by polling the space along suitable directions.
- Rich convergence theory (Kolda et al '03, Dzhahini et al. '25).

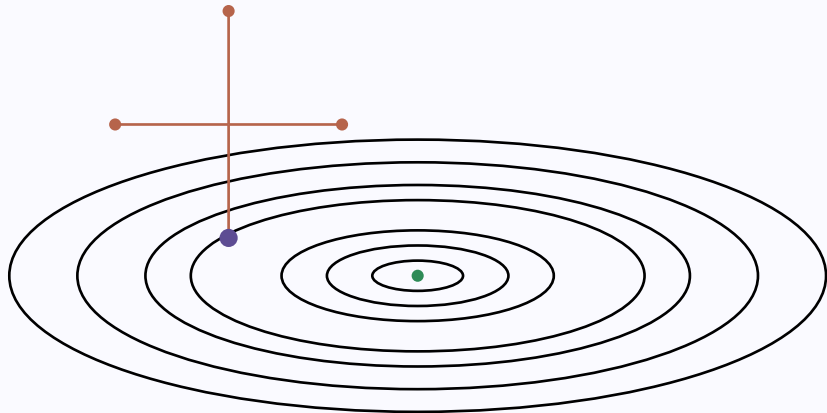
# How direct search works



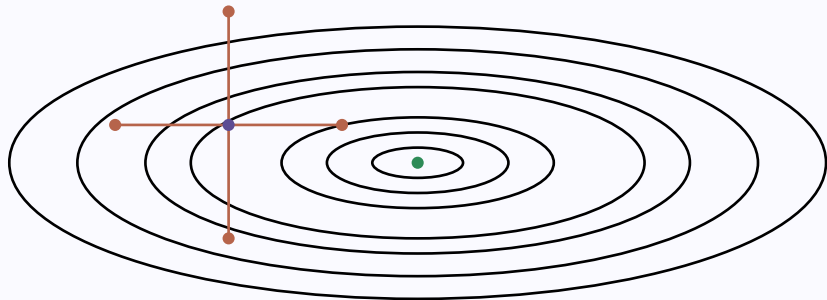
# How direct search works



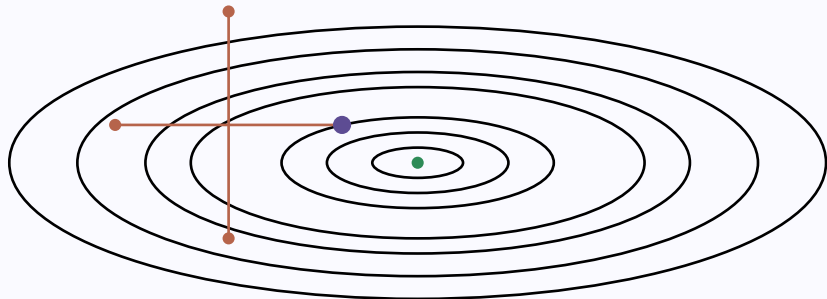
# How direct search works



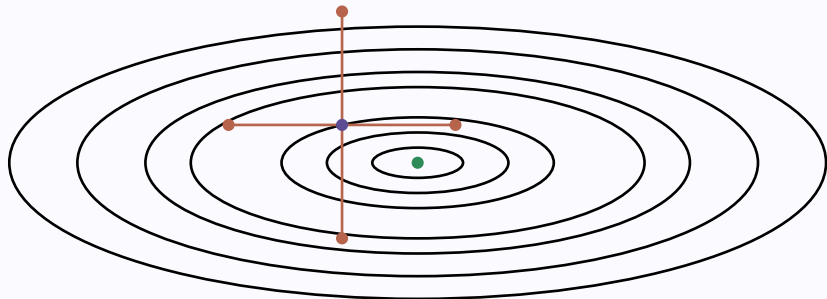
# How direct search works



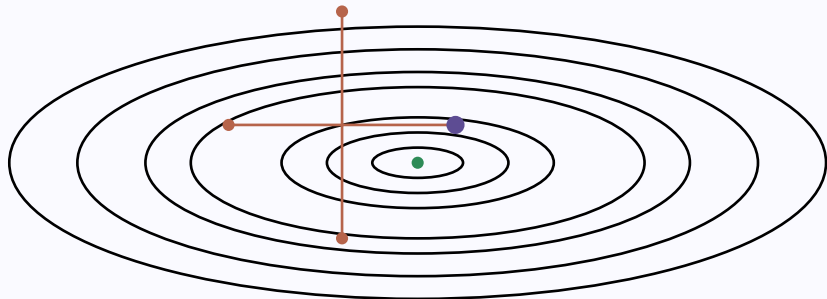
# How direct search works



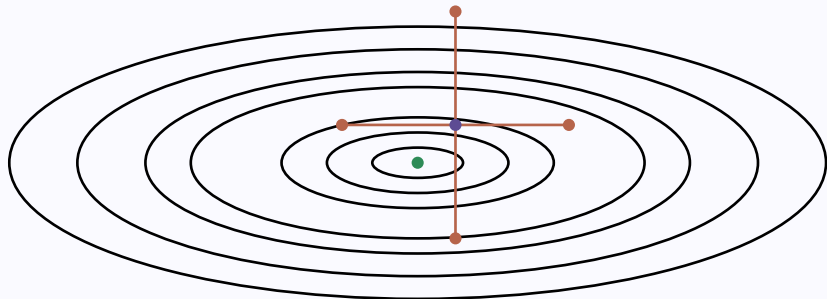
# How direct search works



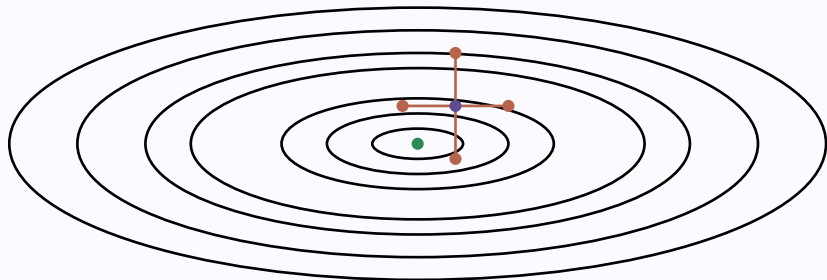
# How direct search works



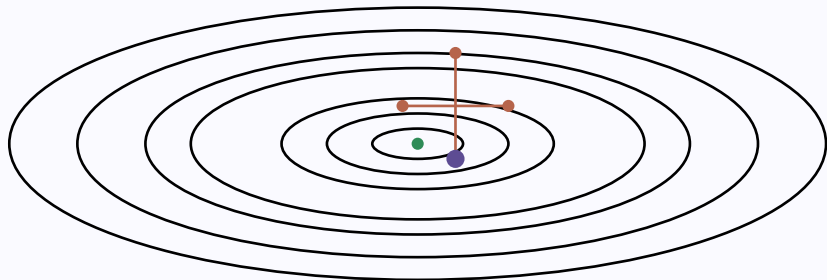
# How direct search works



# How direct search works



# How direct search works



# A direct-search method

**Inputs:**  $x_0 \in \mathbb{R}^n$ ,  $\alpha_0 > 0$ ,  $D$  nonzero vectors in  $\mathbb{R}^n$ .

**Iteration  $i$ :** Given  $(x_i, \alpha_i)$ ,

- If  $\exists d_j \in D$  such that

$$f(x_i + \alpha_j d_j) < f(x_i) - \alpha_j^2$$

set  $x_{i+1} := x_i + \alpha_j d_j$ ,  $\alpha_{i+1} := 2\alpha_j$ .

- Otherwise, set  $x_{i+1} := x_i$ ,  $\alpha_{i+1} := \alpha_i/2$ .

# A direct-search method

**Inputs:**  $x_0 \in \mathbb{R}^n$ ,  $\alpha_0 > 0$ ,  $D$  nonzero vectors in  $\mathbb{R}^n$ .

**Iteration  $i$ :** Given  $(x_i, \alpha_i)$ ,

- If  $\exists d_j \in D$  such that

$$f(x_i + \alpha_i d_j) < f(x_i) - \alpha_i^2$$

set  $x_{i+1} := x_i + \alpha_i d_j$ ,  $\alpha_{i+1} := 2\alpha_i$ .

- Otherwise, set  $x_{i+1} := x_i$ ,  $\alpha_{i+1} := \alpha_i/2$ .

## Choosing directions

- Need good geometry within  $\mathbb{R}^n$ .
- Cost: Want as few directions as possible.

## Choosing directions

- Positive spanning sets are a good choice!
- Some are better than others.

## Choosing directions

- Positive spanning sets are a good choice!
- Some are better than others.

## Surprising discrete connection

- Can generate directions from graphs...
- ...and improve structural understanding of positive spanning sets.

# The rest of the talk

## Choosing directions

- Positive spanning sets are a good choice!
- Some are better than others.

## Surprising discrete connection

- Can generate directions from graphs...
- ...and improve structural understanding of positive spanning sets.

## Resilient positive spanning sets

- Polytope theory more informative than graphs.
- There are open questions!

- 1 Positive spanning sets
- 2 A graphical view of PSS
- 3 Resilient positive spanning sets
- 4 Polyhedral approaches to resilient positive bases

- 1 Positive spanning sets
- 2 A graphical view of PSS
- 3 Resilient positive spanning sets
- 4 Polyhedral approaches to resilient positive bases

## Definitions

- $D = [d_1 \ \cdots \ d_p] \in \mathbb{R}^{n \times p}$  is a **positive spanning set (PSS)** if

$$\mathbb{R}^n = \text{cone}(D) = \left\{ \sum_{i=1}^p \lambda_i d_i \mid \lambda_i \geq 0 \right\}.$$

## Definitions

- $D = [d_1 \ \cdots \ d_p] \in \mathbb{R}^{n \times p}$  is a **positive spanning set (PSS)** if

$$\mathbb{R}^n = \text{cone}(D) = \left\{ \sum_{i=1}^p \lambda_i d_i \mid \lambda_i \geq 0 \right\}.$$

- $D$  PSS is a **positive basis** if no proper subset is a PSS.

## Definitions

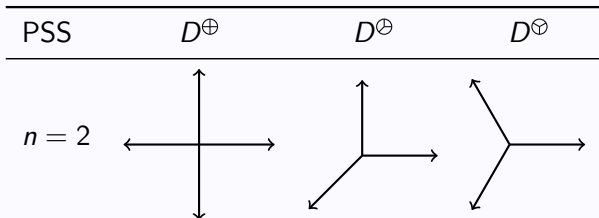
- $D = [d_1 \ \cdots \ d_p] \in \mathbb{R}^{n \times p}$  is a **positive spanning set (PSS)** if

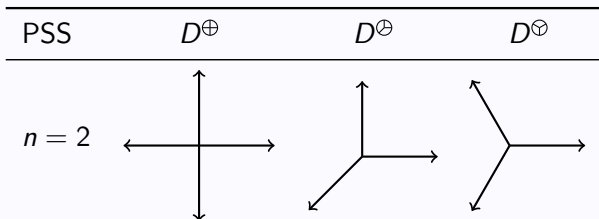
$$\mathbb{R}^n = \text{cone}(D) = \left\{ \sum_{i=1}^p \lambda_i d_i \mid \lambda_i \geq 0 \right\}.$$

- $D$  PSS is a **positive basis** if no proper subset is a PSS.

## Cardinality

- $D$  PSS  $\Rightarrow |D| \geq n + 1$ .
- $D$  positive basis  $\Rightarrow n + 1 \leq |D| \leq 2n$ .  
→ Can be proven via linear programming (Audet '11).





$\mathbf{e}_1, \dots, \mathbf{e}_n$  canonical basis of  $\mathbb{R}^n$ .

- $D^\oplus$ : Coordinate vectors and their negatives in  $\mathbb{R}^n$ .
- $D^\ominus$ :  $n + 1$  vectors with uniform angles, including  $\mathbf{e}_1$ .
- $D^\circledast$ : Coordinate vectors and  $\mathbf{e}_{n+1} = -\sum_{i=1}^n \mathbf{e}_i$ .

**Inputs:**  $x_0 \in \mathbb{R}^n$ ,  $\alpha_0 > 0$ ,  $D$  nonzero vectors in  $\mathbb{R}^n$ .

**Iteration  $i$ :** Given  $(x_i, \alpha_i)$ ,

- If  $\exists d_j \in D$  such that

$$f(x_i + \alpha_i d_j) < f(x_i) - \alpha_i^2$$

set  $x_{i+1} := x_i + \alpha_i d_j$ ,  $\alpha_{i+1} := 2\alpha_i$ .

- Otherwise, set  $x_{i+1} := x_i$ ,  $\alpha_{i+1} := \alpha_i/2$ .

**Inputs:**  $x_0 \in \mathbb{R}^n$ ,  $\alpha_0 > 0$ ,  $D$  nonzero vectors in  $\mathbb{R}^n$ .

**Iteration  $i$ :** Given  $(x_i, \alpha_i)$ ,

- If  $\exists d_j \in D$  such that

$$f(x_i + \alpha_i d_j) < f(x_i) - \alpha_i^2$$

set  $x_{i+1} := x_i + \alpha_i d_j$ ,  $\alpha_{i+1} := 2\alpha_i$ .

- Otherwise, set  $x_{i+1} := x_i$ ,  $\alpha_{i+1} := \alpha_i/2$ .




- What is the best possible  $D$ ?
- In theory, expressed via *complexity measure*.

- Cosine measure:  $\text{cm}(D) = \max_{d \in D} \min_{\|v\|=1} \frac{d^T v}{\|d\|}$ .
- Complexity measure:  $\chi(D) = |D| \text{cm}(D)^{-2}$ .

# Complexity measure

- Cosine measure:  $\text{cm}(D) = \max_{d \in D} \min_{\|v\|=1} \frac{d^T v}{\|d\|}$ .
- Complexity measure:  $\chi(D) = |D| \text{cm}(D)^{-2}$ .

## Examples

PSS	$D^\oplus$	$D^\ominus$	$D^\circledast$
$n = 2$			
$ D $	$2n$	$n + 1$	$n + 1$
$\text{cm}(D)$	$\frac{1}{\sqrt{n}}$	$\frac{1}{\sqrt{n^2 + 2(n-1)\sqrt{n}}}$	$\frac{1}{n}$
$\chi(D)$	$2n^2$	$n^3 + O(n^{3/2})$	$n^3 + O(n^2)$

# Why consider multiple PSS?

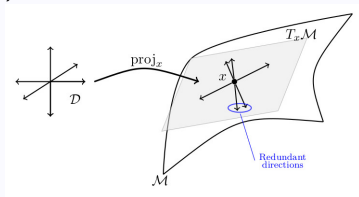
- Best set in theory conjectured to be  $D^\oplus$  (Dodangeh et al '16)  
→ Other PSS can work better in practice (Audet et al '14).

# Why consider multiple PSS?

- Best set in theory conjectured to be  $D^\oplus$  (Dodangeh et al '16)  
→ Other PSS can work better in practice (Audet et al '14).
- Many blackbox optimization problems have constraints

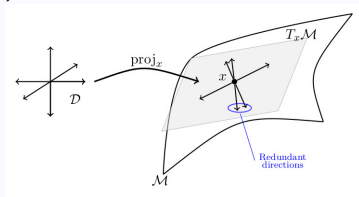
# Why consider multiple PSS?

- Best set in theory conjectured to be  $D^\oplus$  (Dodangeh et al '16)  
→ Other PSS can work better in practice (Audet et al '14).
- Many blackbox optimization problems have constraints  
→ A given PSS may have a bad geometry in constraint manifold (Cavarretta et al '25)

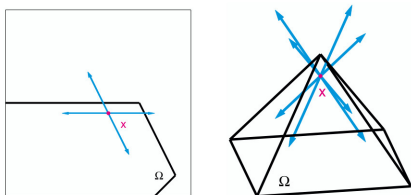


# Why consider multiple PSS?

- Best set in theory conjectured to be  $D^\oplus$  (Dodangeh et al '16)  
→ Other PSS can work better in practice (Audet et al '14).
- Many blackbox optimization problems have constraints  
→ A given PSS may have a bad geometry in constraint manifold (Cavarretta et al '25)

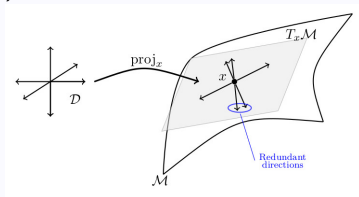


→ Need PSS that conform to constraint boundary (Kolda et al '03)

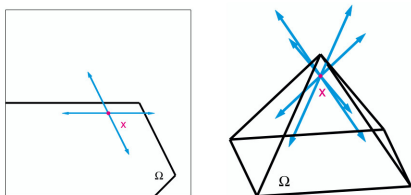


# Why consider multiple PSS?

- Best set in theory conjectured to be  $D^\oplus$  (Dodangeh et al '16)  
→ Other PSS can work better in practice (Audet et al '14).
- Many blackbox optimization problems have constraints  
→ A given PSS may have a bad geometry in constraint manifold (Cavarretta et al '25)



→ Need PSS that conform to constraint boundary (Kolda et al '03)



## Positive spanning sets

- Span the space by conic combinations ( $\geq n + 1$  vectors).
- If minimal: Positive bases ( $\leq 2n$  vectors).

## Key aspects

- **Cardinality.**
- Structure/geometry of a PSS.

## Positive spanning sets

- Span the space by conic combinations ( $\geq n + 1$  vectors).
- If minimal: Positive bases ( $\leq 2n$  vectors).

## Key aspects

- **Cardinality.**
- Structure/geometry of a PSS.

## Bringing PSSs to Dauphine

- *“These PSSs look like graphs”* (D. Cornaz, 2020).
- *“What are you talking about?”* (C. Royer, 2020).

- 1 Positive spanning sets
- 2 A graphical view of PSS
- 3 Resilient positive spanning sets
- 4 Polyhedral approaches to resilient positive bases

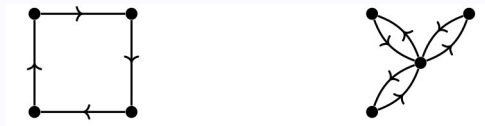
$G = (V, E)$  directed graph (digraph).

- $G$  **strongly connected** if there is a directed path between each pair  $(i, j) \in V^2$ .
- $G$  **minimally strongly connected** if no proper subgraph of  $G$  is strongly connected.

# Some (unrelated?) graph theory

$G = (V, E)$  directed graph (digraph).

- $G$  **strongly connected** if there is a directed path between each pair  $(i, j) \in V^2$ .
- $G$  **minimally strongly connected** if no proper subgraph of  $G$  is strongly connected.



## Network matrix

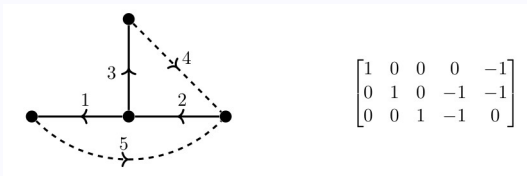
Given  $G = (V, A)$  and a spanning tree  $T = (V, \hat{A})$ , the **network matrix**  $M \in \{-1, 0, 1\}^{|\hat{A}| \times |A|}$  expresses how the path from each edge in  $A$  uses edges from  $\hat{A}$ .

# Link between graphs and PSSs

## Network matrix

Given  $G = (V, A)$  and a spanning tree  $T = (V, \hat{A})$ , the **network matrix**  $M \in \{-1, 0, 1\}^{|\hat{A}| \times |A|}$  expresses how the path from each edge in  $A$  uses edges from  $\hat{A}$ .

## Example



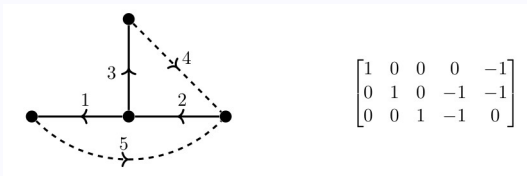
*Spanning tree (1,2,3), columns of  $M$  are arcs in order.*

# Link between graphs and PSSs

## Network matrix

Given  $G = (V, A)$  and a spanning tree  $T = (V, \hat{A})$ , the **network matrix**  $M \in \{-1, 0, 1\}^{|\hat{A}| \times |A|}$  expresses how the path from each edge in  $A$  uses edges from  $\hat{A}$ .

## Example



*Spanning tree (1,2,3), columns of  $M$  are arcs in order.*

**This network matrix is a PSS!**

Theorem (New algebraic proof - Cornaz, Kerleau, R. '25)

Let  $G$  be a digraph with network matrix  $M$ . Then,

- $G$  is strongly connected  $\Leftrightarrow M$  is a positive spanning set.
- $G$  is **minimally** strongly connected  $\Leftrightarrow M$  is a positive basis.

## Theorem (New algebraic proof - Cornaz, Kerleau, R. '25)

Let  $G$  be a digraph with network matrix  $M$ . Then,

- $G$  is strongly connected  $\Leftrightarrow M$  is a positive spanning set.
- $G$  is **minimally** strongly connected  $\Leftrightarrow M$  is a positive basis.

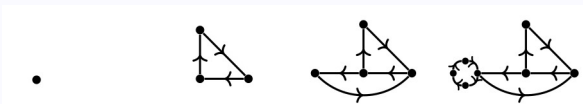
## Corollary: Cardinality of positive bases

- Cardinality of minimally strongly connected digraphs (García-López and Marijuán '12)

$$G = (V, A) \text{ strongly connected} \quad \Leftrightarrow \quad |V| \leq |A| \leq 2(|V| - 1)$$

- Yields the bound for positive bases in  $\mathbb{R}^{|V|-1}$   
→ Key: Invariance of positive basis property through transformations (scaling, permutation).

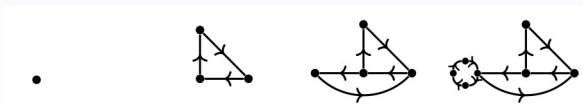
- **Ear decomposition** Characterizes strongly connected digraphs



→ Applies to PSSs as well!

→ More explicit than existing decompositions (Romanowicz '87).

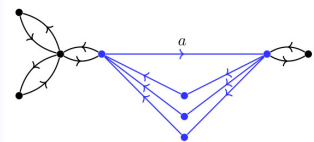
- **Ear decomposition** Characterizes strongly connected digraphs



→ Applies to PSSs as well!

→ More explicit than existing decompositions (Romanowicz '87).

- **New PSS/PB generation** for non-extreme sizes



→ Minimally strongly connected digraph with 9 vertices and 15 edges.

→ Defines a positive basis of size 15 in  $\mathbb{R}^8$ !

- Strongly connected digraphs  $\rightarrow$  PSS.
- Minimality  $\rightarrow$  Positive bases.

- Strongly connected digraphs  $\rightarrow$  PSS.
- Minimality  $\rightarrow$  Positive bases.

## What this enables

- Generates PSSs from graphs!
- Characterize positive bases of certain cardinality.

- Strongly connected digraphs  $\rightarrow$  PSS.
- Minimality  $\rightarrow$  Positive bases.

## What this enables

- Generates PSSs from graphs!
- Characterize positive bases of certain cardinality.

## Main problem

- Sometimes PSSs are not enough.
- Can graphs help there?

- 1 Positive spanning sets
- 2 A graphical view of PSS
- 3 Resilient positive spanning sets**
- 4 Polyhedral approaches to resilient positive bases

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \quad f(x)$$

## Blackbox/Derivative-free optimization

- Only access to values of  $f$ .
- **Cost** Number of function evaluations.
- **Those can take a long time to compute.**

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \quad f(x)$$

## Blackbox/Derivative-free optimization

- Only access to values of  $f$ .
- **Cost** Number of function evaluations.
- **Those can take a long time to compute.**

## Straggler and direct search

- Some evaluations (stragglers) must be ignored at each iteration.
- Motivation: Long solving times on a cluster.

**Inputs:**  $x_0 \in \mathbb{R}^n$ ,  $\alpha_0 > 0$ ,  $D$  nonzero vectors.

**Iteration  $i$ :** Given  $(x_i, \alpha_i)$ ,

- If  $\exists d_i \in D \setminus \mathcal{S}_i$  such that

$$f(x_i + \alpha_i d_i) < f(x_i) - \alpha_i^2 \|d_i\|^2$$

set  $x_{i+1} := x_i + \alpha_i d_i$ ,  $\alpha_{i+1} := 2\alpha_i$ .

- Otherwise, set  $x_{i+1} := x_i$ ,  $\alpha_{i+1} := \alpha_i/2$ .

**Inputs:**  $x_0 \in \mathbb{R}^n$ ,  $\alpha_0 > 0$ ,  $D$  nonzero vectors.

**Iteration  $i$ :** Given  $(x_i, \alpha_i)$ ,

- If  $\exists d_i \in D \setminus \mathcal{S}_i$  such that

$$f(x_i + \alpha_i d_i) < f(x_i) - \alpha_i^2 \|d_i\|^2$$

set  $x_{i+1} := x_i + \alpha_i d_i$ ,  $\alpha_{i+1} := 2\alpha_i$ .

- Otherwise, set  $x_{i+1} := x_i$ ,  $\alpha_{i+1} := \alpha_i/2$ .

**Inputs:**  $x_0 \in \mathbb{R}^n$ ,  $\alpha_0 > 0$ ,  $D$  nonzero vectors.

**Iteration  $i$ :** Given  $(x_i, \alpha_i)$ ,

- If  $\exists d_i \in D \setminus \mathcal{S}_i$  such that

$$f(x_i + \alpha_i d_i) < f(x_i) - \alpha_i^2 \|d_i\|^2$$

set  $x_{i+1} := x_i + \alpha_i d_i$ ,  $\alpha_{i+1} := 2\alpha_i$ .

- Otherwise, set  $x_{i+1} := x_i$ ,  $\alpha_{i+1} := \alpha_i/2$ .

- $\mathcal{S}_i$ : Straggler evaluations (not known ahead of time!)
- Need to choose  $D$  so as to be robust to missing evaluations.

## Definition (Marcus '81-'84)

$D \subset \mathbb{R}^n$  is a **PkSS** with  $k \geq 1$  if

- Any  $\mathcal{N} \subset D$  with  $|\mathcal{N}| = |D| - k + 1$  is a PSS.
- Removing  $k - 1$  vectors from  $D$  does not change its PSS nature.

# Positive $k$ -spanning sets (PkSS)

## Definition (Marcus '81-'84)

$D \subset \mathbb{R}^n$  is a **PkSS** with  $k \geq 1$  if

- Any  $\mathcal{N} \subset D$  with  $|\mathcal{N}| = |D| - k + 1$  is a PSS.
- Removing  $k - 1$  vectors from  $D$  does not change its PSS nature.

→  $k = 1$ : Regular definition of PSS.

# Positive $k$ -spanning sets (PkSS)

## Definition (Marcus '81-'84)

$D \subset \mathbb{R}^n$  is a **PkSS** with  $k \geq 1$  if

- Any  $\mathcal{N} \subset D$  with  $|\mathcal{N}| = |D| - k + 1$  is a PSS.
- Removing  $k - 1$  vectors from  $D$  does not change its PSS nature.

→  $k = 1$ : Regular definition of PSS.

## The $k$ -cosine measure (Hare, Jarry-Bolduc, Kerleau, R. '24)

- For any  $D \subset \mathbb{R}^n$ , the  **$k$ -cosine measure** of  $D$  is

$$\text{cm}_k(D) = \min_{\substack{\mathcal{N} \subset D \\ |\mathcal{N}| = |D| - k + 1}} \text{cm}(\mathcal{N}).$$

- $D$  PkSS  $\iff \text{cm}_k(D) > 0$ .

# Building a $PkSS$ from a PSS: First approach

- $D^\oplus := \{e_1, \dots, e_n, -e_1, \dots, -e_n\}$ , with  $\{e_\ell\}$  coordinate basis vectors.
- $\beta D^\oplus$ : multiply all vectors by real  $\beta$ .

# Building a PkSS from a PSS: First approach

- $D^\oplus := \{e_1, \dots, e_n, -e_1, \dots, -e_n\}$ , with  $\{e_\ell\}$  coordinate basis vectors.
- $\beta D^\oplus$ : multiply all vectors by real  $\beta$ .

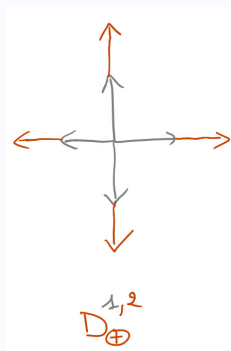
## Duplicate vectors

If  $\beta_1, \dots, \beta_k > 0$  are distinct,

$$D_{\beta_{1:k}}^\oplus := \bigcup_{j=1}^k \beta_j D^\oplus$$

is a PkSS with

$$\text{cm}_k(D_{\beta_{1:k}}^\oplus) = \text{cm}(D^\oplus) = \frac{1}{\sqrt{n}}.$$



# Building a PKSS from a PSS: Second approach

- $D^\oplus := \{e_1, \dots, e_n, -\sum_{l=1}^n e_l\}$ , with  $\{e_\ell\}$  coordinate basis vectors.
- $RD^\oplus$ : Apply **Rotation matrix**  $R \in \mathbb{R}^{n \times n}$  to all vectors.

# Building a PkSS from a PSS: Second approach

- $D^\oplus := \{e_1, \dots, e_n, -\sum_{l=1}^n e_l\}$ , with  $\{e_l\}$  coordinate basis vectors.
- $RD^\oplus$ : Apply **Rotation matrix**  $R \in \mathbb{R}^{n \times n}$  to all vectors.

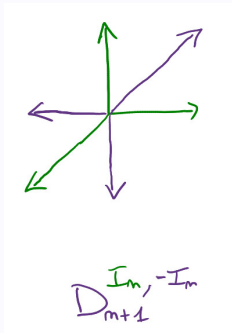
## Rotate vectors

Let  $R_1, \dots, R_k$  be  $k$  distinct positive real numbers. The set

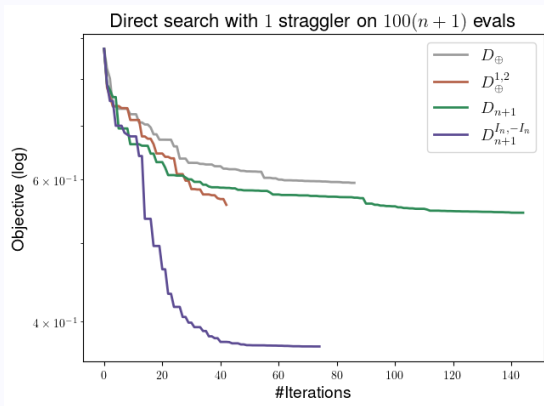
$$D_{R_{1:k}}^\oplus := \bigcup_{j=1}^k R_j D^\oplus$$

is a PkSS with

$$\text{cm}_k(D_{R_{1:k}}^\oplus) \geq \text{cm}(D^\oplus) = \frac{1}{\sqrt{n^2 + 2(n-1)\sqrt{n}}}.$$



# Numerical illustration



- Nonconvex regression problem,  $n = 10$  (Carmon et al '17).
- P2SSs obtained by **duplication** or **rotation**.
- Outperform PSSs based on  $D^{\oplus}$  or  $D^{\oplus}$ .

## Positive $k$ -basis (PkB)

A PkSS  $D$  is a **positive  $k$ -basis** if no proper subset of  $D$  is a PkSS.

### Intricate definition

- Want minimality (positive basis) and resiliency (PkSS).
- Previous examples: May not be PkBs, definitely not of smallest cardinality.

## Positive $k$ -basis (PkB)

A PkSS  $D$  is a **positive  $k$ -basis** if no proper subset of  $D$  is a PkSS.

### Intricate definition

- Want minimality (positive basis) and resiliency (PkSS).
- Previous examples: May not be PkBs, definitely not of smallest cardinality.

## Positive $k$ -basis (PkB)

A PkSS  $D$  is a **positive  $k$ -basis** if no proper subset of  $D$  is a PkSS.

### Intricate definition

- Want minimality (positive basis) and resiliency (PkSS).
- Previous examples: May not be PkBs, definitely not of smallest cardinality.

Can we use graphs to generate PkBs?

- 1 Positive spanning sets
- 2 A graphical view of PSS
- 3 Resilient positive spanning sets
- 4 Polyhedral approaches to resilient positive bases**

## The right graph notion

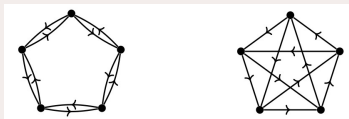
$G$  is  $k$ -strongly connected if every pair of vertices is connected by at least  $k$  paths.



*Minimally 2-strongly connected digraphs.*

## The right graph notion

$G$  is  $k$ -strongly connected if every pair of vertices is connected by at least  $k$  paths.



*Minimally 2-strongly connected digraphs.*

## Properties (Dalmazzo '77, Marcus '84)

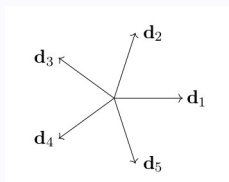
- $G$  is  $k$ -strongly connected if and only if its network matrix is a PkSS.
- If  $G = (V, E)$  has  $n + 1$  vertices and is **minimally**  $k$ -strongly connected, then

$$k(n + 1) \leq |E| \leq 2kn.$$

- From graph arguments, the cardinality of a positive  $k$ -basis is between  $kn + k$  and  $2kn...$

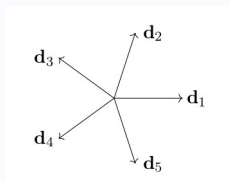
# Did we solve it?

- From graph arguments, the cardinality of a positive  $k$ -basis is between  $kn + k$  and  $2kn$ ...
- ...but both bounds are loose!
  - Smallest cardinality is  $2k + n - 1$ .
  - Largest cardinality strictly bigger than  $2kn$  for large  $n$ .



# Did we solve it?

- From graph arguments, the cardinality of a positive  $k$ -basis is between  $kn + k$  and  $2kn$ ...
- ...but both bounds are loose!
  - Smallest cardinality is  $2k + n - 1$ .
  - Largest cardinality strictly bigger than  $2kn$  for large  $n$ .



Can tools from polytope theory help?

$X_D$  is a Gale diagram of  $D \in \mathbb{R}^{n \times p}$  if the columns of  $X_D^T$  form a basis for the null space of  $D$ .

$X_D$  is a Gale diagram of  $D \in \mathbb{R}^{n \times p}$  if the columns of  $X_D^T$  form a basis for the null space of  $D$ .

## Theorem (Shephard '71)

$D$  is a PSS of  $\mathbb{R}^n$  if and only if  $0 \notin \text{conv}(X_D)$ .

→ Yet another characterization of PSS!

$X_D$  is a Gale diagram of  $D \in \mathbb{R}^{n \times p}$  if the columns of  $X_D^T$  form a basis for the null space of  $D$ .

## Theorem (Shephard '71)

$D$  is a PSS of  $\mathbb{R}^n$  if and only if  $0 \notin \text{conv}(X_D)$ .

→ Yet another characterization of PSS!

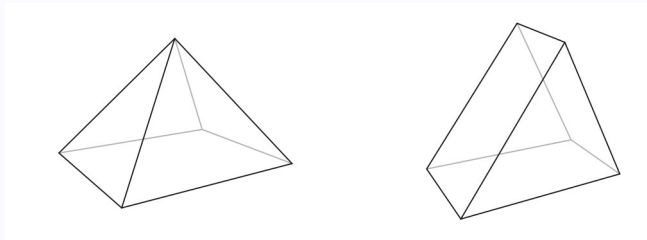
## For polytopes

Let  $\mathcal{P}$  be a convex polytope in  $\mathbb{R}^m$  and  $P \in \mathbb{R}^{p \times m}$  the matrix of its vertices coordinates. A Gale diagram for  $P$  is called a Gale diagram for  $\mathcal{P}$ .

# Generating $PkSS$ from polytopes

**Classes of polytopes**  $\mathcal{P}$  convex polytope,  $P$  matrix of vertices.

- $\mathcal{P}$  is lifted if last row of  $P$  is all ones.
- $\mathcal{P}$  is  $k$ -neighborly if each set of  $\leq k$  vertices generates a face.
- $\mathcal{P}$  is  $k$ -unneighborly if each vertex can be included in a set of  $k + 1$  vertices that do not generate a face.



4-neighborly and 1-unneighborly polytopes in  $\mathbb{R}^3$  (Woltzlaw '09).

**Classes of polytopes**  $\mathcal{P}$  convex polytope,  $P$  matrix of vertices.

- $\mathcal{P}$  is lifted if last row of  $P$  is all ones.
- $\mathcal{P}$  is  $k$ -neighborly if each set of  $\leq k$  vertices generates a face.
- $\mathcal{P}$  is  $k$ -unneighborly if each vertex can be included in a set of  $k + 1$  vertices that do not generate a face.

**Theorem (Marcus '84)**

Let  $\mathcal{P}$  be a lifted polytope in  $\mathbb{R}^p$  with  $q > p$  vertices, and  $P$  its vertex matrix. Let  $X_P$  be a Gale diagram for  $\mathcal{P}$ .

- $X_P$  is a PkSS for  $\mathbb{R}^{q-p} \Leftrightarrow \mathcal{P}$   $k - 1$ -neighborly.
- If  $\mathcal{P}$  is also  $k - 1$ -unneighborly,  $X_P$  positive  $k$ -basis!

# Cardinality of positive $k$ -bases

**Corollary** Minimal cardinality of a  $PkB$  is  $2k + n - 1$ .

# Cardinality of positive $k$ -bases

**Corollary** Minimal cardinality of a  $PkB$  is  $2k + n - 1$ .

## Construction for fixed $(k, n)$

- Set  $q = 2k + n - 1$ ,  $p = q - n$ .
- Pick  $q$  different values  $t_1, \dots, t_q$  and let

$$\mathcal{P} = \text{conv} \left\{ \begin{bmatrix} 1 \\ t_i \\ \vdots \\ t_i^{q-1} \end{bmatrix} \mid i = 1, \dots, q \right\}.$$

- $X_{\mathcal{P}}$  (Gale diagram) gives a positive  $k$ -basis of cardinality  $q$ .

**Example** ( $k = n = 2$ ,  $t_i = i$ )

$$X_{\mathcal{P}} = \begin{bmatrix} -1 & 3 & -3 & 1 & 0 \\ -3 & 8 & -6 & 0 & 1 \end{bmatrix}.$$

## Marcus' counterexample ('84)

- Original conjecture: maximum size of a positive  $k$ -basis is  $2kn$ .
- Claimed to have found a counterexample

**Note added in proof**

As this goes to press, the author has discovered an unneighborly polytope of dimension 36 having only 49 vertices.

- Counterexample was lost, rediscovered in Woltzlaw's thesis.

## Marcus' counterexample ('84)

- Original conjecture: maximum size of a positive  $k$ -basis is  $2kn$ .
- Claimed to have found a counterexample

### Note added in proof

As this goes to press, the author has discovered an unneighborly polytope of dimension 36 having only 49 vertices.

- Counterexample was lost, rediscovered in Woltzlaw's thesis.

## Theorem (Woltzlaw '09)

- If  $n \leq 12$  or  $k = 1$ , largest cardinality of positive  $k$ -bases is  $2kn$ .
  - Otherwise, it is at most  $kn(n+1)^{k-1}$ .
- Largest examples found have cardinality  $\mathcal{O}(kn^2)$ .
- **Exact value still unknown!**

## Positive spanning sets and bases

- Fundamental tool in DFO.
- Minimality is important.

## Positive spanning sets and bases

- Fundamental tool in DFO.
- Minimality is important.

## Connections to discrete techniques

- Graphs (+Decomposition)
- Gives structure+Minimality arguments.

## Positive spanning sets and bases

- Fundamental tool in DFO.
- Minimality is important.

## Connections to discrete techniques

- Graphs (+Decomposition)
- Gives structure+Minimality arguments.

## Open questions

- Cardinality of positive  $k$ -bases.
- Polytopes give explicit constructions.

- D. Cornaz, S. Kerleau and C. W. Royer, *A characterization of positive spanning sets with ties to strongly connected digraphs*, Discrete Applied Mathematics, 2025.
- W. Hare, G. Jarry-Bolduc, S. Kerleau and C. W. Royer, *Using orthogonally structured positive bases for constructing positive  $k$ -spanning sets with cosine measure guarantees*, Linear Algebra and Applications, 2024.
- S. Kerleau, **Graphical and geometrical perspectives on positive spanning sets with applications to derivative-free optimization**, Université PSL, 2025.

- D. Cornaz, S. Kerleau and C. W. Royer, *A characterization of positive spanning sets with ties to strongly connected digraphs*, Discrete Applied Mathematics, 2025.
- W. Hare, G. Jarry-Bolduc, S. Kerleau and C. W. Royer, *Using orthogonally structured positive bases for constructing positive  $k$ -spanning sets with cosine measure guarantees*, Linear Algebra and Applications, 2024.
- S. Kerleau, **Graphical and geometrical perspectives on positive spanning sets with applications to derivative-free optimization**, Université PSL, 2025.

Thank you!

`clement.royer@lamsade.dauphine.fr`