

MATHEMATICS OF DATA SCIENCE

November 7, 2023

Today: Last session on convex optimization
Next up: statistics for data science

SOLVING OPTIMIZATION PROBLEMS (Pt 2)

① Existence principles

② Duality

Domain of (P):
 $X = \{x \in \mathbb{R}^n \mid f(x) < \infty, g_i(x) < \infty \forall i=1..m, h_i(x) < \infty \forall i=1..l\}$

$$(P) \begin{cases} \text{minimize} & f(x) \\ x \in \mathbb{R}^n \end{cases} \quad \text{s.t.} \quad \begin{cases} g_i(x) \leq 0 & i=1..m \\ h_i(x) = 0 & i=1..l \end{cases}$$

$$f, g_i, h_i : \mathbb{R}^n \rightarrow (-\infty, +\infty] \quad g = [g_i]_{i=1..m} \quad h = [h_i]_{i=1..l}$$

The Lagrangian associated with (P) is the function

$$\mathcal{L} : \mathbb{R}^n \times \mathbb{R}^m \times \mathbb{R}^l \rightarrow \bar{\mathbb{R}}$$

$$\begin{aligned} (x, \lambda, \mu) &\mapsto \mathcal{L}(x, \lambda, \mu) = f(x) + \lambda^T g(x) + \mu^T h(x) \\ &= f(x) + \sum_{i=1}^m \lambda_i g_i(x) + \sum_{i=1}^l \mu_i h_i(x) \end{aligned}$$

Property: Suppose that $x \in \mathbb{R}^n$ is feasible for (P). Then

$$\mathcal{L}(x, \lambda, \mu) \leq f(x) \quad \forall \lambda \in \mathbb{R}_+^m \quad \forall \mu \in \mathbb{R}^l \quad \Rightarrow \left\{ \begin{array}{l} \lambda_i \geq 0 \\ i=1..m \end{array} \right\}$$

Definition

- Primal function associated with (P)

$$p : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$$

$$x \mapsto \begin{cases} \sup_{\lambda, \mu \in \mathcal{Y}} \mathcal{L}(x, \lambda, \mu) & \text{if } x \in X \\ +\infty & \text{if } x \notin X \end{cases}$$

optimal value of a maximization problem

where X is the domain of (P)

$$\text{and } Y = \{ (\lambda, \mu) \in \mathbb{R}^m \times \mathbb{R}^l \mid \lambda_i \geq 0 \quad i=1..m \}$$

\hookrightarrow If (P) is feasible (feasible set not empty), then (P) is equivalent to minimize $p(x)$
 $x \in \mathbb{R}^n$

\oplus The new formulation is unconstrained

\ominus The new objective function has a complicated expression
(each value $p(x)$ is the optimal value of an optimization problem)

• Dual function (of problem (P))

$$d: \mathbb{R}^m \times \mathbb{R}^l \rightarrow \bar{\mathbb{R}}$$
$$(\lambda, \mu) \mapsto d(\lambda, \mu) = \begin{cases} \inf_{x \in X} \mathcal{L}(x, \lambda, \mu) & \text{if } (\lambda, \mu) \in Y \\ -\infty & \text{if } (\lambda, \mu) \notin Y \end{cases}$$

\hookrightarrow The function d is always concave!

Def: Dual optimization problem

The dual problem of (P) is

$$(D) \quad \begin{array}{l} \text{maximize} \\ \lambda \in \mathbb{R}^m \\ \mu \in \mathbb{R}^l \end{array} d(\lambda, \mu) \quad \text{s.t.} \quad \lambda \geq 0 \quad (\Leftrightarrow \lambda_i \geq 0 \quad i=1..m)$$

\Rightarrow This is a convex optimization problem

$$\text{(Reformulation:)} \quad \begin{array}{l} \text{minimize} \\ \lambda \in \mathbb{R}^m \\ \mu \in \mathbb{R}^l \end{array} -d(\lambda, \mu) \quad \text{s.t.} \quad -\lambda_i \leq 0 \quad i=1..m$$

The dual optimal value of (D) is the optimal value of (P), that is

$$d^* = \sup \{ d(\lambda, \mu) \mid \lambda \geq 0 \}$$

$\mathbb{R}^m \times \mathbb{R}^l \ni (\lambda, \mu)$ is dual feasible if $\lambda \geq 0 \Rightarrow$ Feasible set always nonempty

Example: Linear programming

Canonical form $Ax = b$
 $-x \leq 0$

minimize $C^T x$ s.t. $x \in \mathbb{R}^m$

$$\begin{cases} Ax = b \\ x \geq 0 \end{cases}$$

$A \in \mathbb{R}^{l \times m}$
 $b \in \mathbb{R}^l$
 $C \in \mathbb{R}^m$

$$L(x, \lambda, \mu) = C^T x - \lambda^T x + \mu^T (Ax - b)$$

\mathbb{R}^m \mathbb{R}^l \mathbb{R}^l

Dual function: $d(\lambda, \mu) = \begin{cases} -b^T \mu & \text{if } \underbrace{A^T \mu - \lambda + c = 0}_{\text{by definition}} \text{ and } \lambda \geq 0 \\ -\infty & \text{otherwise} \end{cases}$

The dual problem can be reformulated as

$$\begin{aligned} &\text{maximize}_{\lambda \in \mathbb{R}^m, \mu \in \mathbb{R}^l} -b^T \mu \quad \text{s.t.} \quad A^T \mu - \lambda + c = 0 \\ &\lambda \geq 0 \end{aligned}$$

and this is a convex optimization problem, equivalent to

$$\begin{aligned} &\text{minimize}_{\lambda \in \mathbb{R}^m, \mu \in \mathbb{R}^l} b^T \mu \quad \text{s.t.} \quad -\lambda \leq 0 \\ &A^T \mu - \lambda + c = 0 \end{aligned}$$

) convex optimization problem in standard form

Q) Link between the dual problem and (P)?

Th 1 Weak duality

For any (x, λ, μ) such that $x \in X$ and $(\lambda, \mu) \in Y$,
$$d(\lambda, \mu) \leq p(x)$$

implying that

$$d^* \leq p^* = \inf_{x \in \mathbb{R}^n} \{ p(x) \}$$

→ optimal value for the primal problem

$$= \inf_{x \in \mathbb{R}^n} \{ f(x) \mid g(x) \leq 0, h(x) = 0 \}$$

↑ optimal value of (P)
when the feasible set is not empty

Solving the dual gives an underestimate of the optimal value of (P)

NB. If $d^* = +\infty$, then the primal problem has an empty domain

⚠ In general, $d^* < p^*$ (duality gap: $p^* - d^*$)

So the dual is an approximation of the problem, not a reformulation (but it is a convex approximation, hence easier to analyze)

↳ When (P) is convex, then under mild conditions, we have $d^* = p^*$, and the dual is a reformulation of (P)

Ex) If all constraints in (P) are linear, then (D) is a reformulation of (P)

Ex) If the problem is a convex optimization problem in standard form

$$\begin{array}{ll} \text{minimize} & f(x) \\ \text{s.t.} & g_i(x) \leq 0 \quad i=1, \dots, m \\ & a_i^T x - b_i = 0 \quad i=1, \dots, l \end{array}$$

with f, g_1, \dots, g_m convex, such that

$$\exists x \in \mathbb{R}^n \text{ satisfying } \begin{cases} - g_i(x) < 0 & \forall i=1..m \\ - a_i^T x - b_i = 0 \\ - f(x) < \infty \end{cases}$$

then $d^* = p^*$ also holds.

When $d^* = p^*$, we say that strong duality holds.

③ KKT conditions

Consider again problem (P) and suppose that $f, g_1, \dots, g_m, h_1, \dots, h_l$ differentiable on \mathbb{R}^n (for simplicity).
 \Rightarrow domain of (P) is \mathbb{R}^n

Suppose also that strong duality holds.

Then if $x^* \in \mathbb{R}^n$ is a solution of (P), then there exist $(\lambda^*, \mu^*) \in \mathbb{R}^m \times \mathbb{R}^l$ that is a solution of (D) and we have

KKT conditions

$$\left\{ \begin{aligned} \nabla f(x^*) + \sum_{i=1}^m \lambda_i^* \nabla g_i(x^*) + \sum_{i=1}^l \mu_i^* \nabla h_i(x^*) &= 0 \\ g_i(x^*) &\leq 0 & \forall i=1..m \\ h_i(x^*) &= 0 & \forall i=1..l \\ \lambda_i^* &\geq 0 & \forall i=1..m \\ g_i(x^*) \lambda_i^* &= 0 & \forall i=1..m \end{aligned} \right.$$

If (P) is convex, x^* is a solution of (P) if and only if there exist (λ^*, μ^*) such that the KKT conditions hold.

Application: Given $(A, b) \in \mathbb{R}^{m \times m} \times \mathbb{R}^m$, find $x \in \mathbb{R}^m$ such that $Ax = b$

if $m > n$ and $\text{rank}(A) = n$, there exist infinitely many values of x that satisfy $Ax = b$

\Rightarrow In practice, we like solutions that are not too sensitive to changes in the data. One type of such solutions is the minimal-norm solution, obtained by solving

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \quad \frac{1}{2} \|x\|^2 \quad \text{s.t.} \quad Ax = b$$

convex function
convex constraint

\Rightarrow Convex optimization problem

\Rightarrow Linear constraints, so strong duality holds

\Rightarrow KKT equations

$$x^* \text{ is a solution } \Leftrightarrow \exists \mu^* \in \mathbb{R}^m, \quad Ax^* = b$$

$$x^* + A^T \mu^* = 0$$

$$\Leftrightarrow x^* = A^T (A A^T)^{-1} b$$

\Rightarrow The KKT equations give the solution and μ^* indicates the sensitivity of x^* with respect to each constraint