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TRICHOTOMY BASED PROCEDURE FOR MULTIPLE CRITERIA CHOICE PROBLEMS

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UNE METHODE MULTICRITERE DE CHOIX FONDEE SUR UNE PROCEDURE TRICHOTOMIQUE

Résumé

Cet article décrit une méthode de choix multicritère considérant un ensemble explicite d'actions de taille relativement grande. L'approche proposée se place à mi-chemin entre les méthodes qui requièrent des préférences du décideur a priori et les procédures interactives. Les préférences du décideur sont modélisées avec une relation de surclassement dans le voisinage d'un profil de référence de l'ensemble des solution non dominées. Ce modèle des préférences est utilisé pour définir une trichotomie de l'ensemble des actions non dominées (acceptation des bonnes actions, rejet des action non intéressantes et actions ne pouvant ni être acceptées, ni rejetées) sur la base de l'information préférentielle disponible. La méthode s'arrête si la classe des bonnes actions est suffisamment petite ou si le décideur est capable de sélectionner un meilleur compromis. Dans le cas contraire, le décideur peut modifier l'information préférentielle en changeant soit le profil de référence ou les seuils utilisés pour construire la relation de surclassement. En d'autres termes, le décideur définit dynamiquement les trois catégories. La description de la procédure est suivie de la présentation d'une application.

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Abstract

The paper describes a method for multiple criteria choice problems with an explicitly given but relatively large set of alternatives. The approach can be placed between methods with a priori specification of the decision maker's (DM's) preferences and interactive procedures. The DM's preferences are modeled with an outranking relation in the neighborhood of a reference profile in the non-dominated set. This preference model is used in order to define a trichotomy of the non-dominated set in terms of accepting good alternatives, rejecting non-interesting ones and defining alternatives that can neither be accepted, nor rejected based on the available preference information. The method stops if the class of good alternatives is sufficiently small and if the DM is able to select one of them as the best compromise. Otherwise, the DM can modify the preferential information by changing either the reference profile, or the thresholds used to build the outranking relation. In other words, the DM defines dynamically the three categories. The description of the procedure is followed by presentation of an application.

1 Introduction

A number of methods for multiple criteria choice problems use preferential information in the form of a reference profile z^{ref}, i.e., a point in the criteria space composed of aspiration levels on particular criteria. Goal Programming (Charnes and Cooper, 1961, 1977), Interactive Goal Programming (Franz and Lee, 1980), Reference Point method (Wierzbicki, 1980) and Max-Min method (Posner and Wu, 1981) belong to this class of methods. The methods either assume a priori specification of preferences (Goal Programming), or represent an interactive approach. All the methods use the reference profile z^{ref} as a parameter of a scalarizing function, e.g. a penalty function used in the Goal Programming, maximal deviation from the reference profile in the MAX-MIN method, or an achievement scalarizing function in the Reference Point method. The achievement scalarizing function proposed by Wierzbicki (1980, 1986) seems to be especially useful because it completely or almost completely characterizes the nondominated sets of linear, nonlinear and discrete problems in a relatively easy way. All of the scalarizing functions include, however, some additional parameters that have no clear interpretation for the decision maker (DM), e.g., the direction of projection in the achievement scalarizing function of Wierzbicki or weights in the penalty function used in some Goal Programming models. In some cases, the parameters are defined explicitly by the DM (e.g., Goal Programming), or are set automatically by the method (e.g., Reference Point method). By optimizing (projecting) the achievement scalarizing function on the feasible set with different sets of parameters, one can obtain many different nondominated points (see figure 1). So, the result of this step is rather arbitrary. The achievement scalarizing functions are especially suitable for an interactive approach of learning type (Vanderpooten, 1989) in which the DM is interested in free scanning of the whole non-dominated set. By changing the reference profile, the DM can direct the scanning towards desired regions of the non-dominated set. In this case, the reference profile starts to play a technical role. It becomes tool that allows the DM to control the search for the best compromise.

In this paper, we assume that the DM is not interested in just a free scanning of the non-dominated set and he/she expects the method to offer him/her more support. We assume also that the DM is willing and able to supply some additional preferential information that could be used in order characterize the non-dominated points close to the reference profile in non-arbitrary way.

In the method presented, the reference profile is used in order to assign the non-dominated points to one of three mutually exclusive categories: C^+ , C^- and C^7 , composed of points not worse than the reference profile, worse than the reference profile, and incomparable with the reference profile, respectively. Obviously, the assignment to category C^+ , which means acceptance, may not be restricted to cases where each of the J criteria reaches a value better than or equal to the aspiration level. On the contrary, the fact that one of the criteria reaches a high value (regardless of the values taken by the other J-1 criteria) is not necessarily sufficient to imply an assignment to the acceptance category C^+ . In this paper, we propose to use an outranking relation in order to compare non-dominated points to the reference profile \mathbf{z}^{ref} . The outranking relation models local preferences of the DM with respect to \mathbf{z}^{ref} . It allows to take into account the existence of indifference and weak preference regions as well as incomparability of some points to the reference profile.

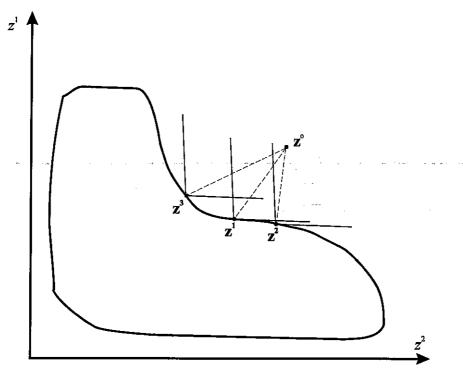


Figure 1. Nondominated points that can be found in the Reference Point method projecting the reference profile in different direction

The outranking relation has also been used as a preference model in the Cone Contraction interactive procedure proposed by Jaszkiewicz and Slowinski (1992), in Light Beam Search interactive procedure proposed by Jaszkiewicz and Slowinski (1995), and in the AIM method proposed by Lotfi et al. (1992). In all these methods, however, the outranking relation is used to model DM's preferences with respect to some non-dominated points, while in our approach, it models preferences with respect to the reference profile.

Trichotomic segmentation approach has already been used by Moscorola and Roy (1977) and Yu (1992) (see also Roy and Bouyssou 1993). Their methods, however, concern the multiple criteria sorting problems, and furthermore, are based on a priori specification of DM's preferences, while the proposed method assumes interaction.

The paper is organized in the following way: after a formal statement of the problem and basic definitions, the main idea and the general scheme of the procedure will be outlined. Some characteristics of the procedure will be described more precisely in the section 5. In section 6, an application of the interactive procedure will be described. Finally, main features of the procedure will be summarized.

2 Problem statement and basic definitions

The general Multiple Criteria Choice (MCC) problem is formulated as:

$$\max \left\{ f_1(a) = z_1, \dots, f_J(a) = z_J \right\}$$
s.t. $a \in A$, (P1)

where A is a finite set of feasible alternatives, f_1, \ldots, f_J are criterion functions (objectives). It is also assumed that set A is relatively large, i.e., its review needs a special guidance characteristic for interactive procedures. So, problem P1 belongs to the multiple-criteria choice problems with large sets of alternatives (MCCL) (see Jaszkiewicz and Slowinski, to appear a). The problem P1 can be the original decision problem, e.g., the problem of selecting the best candidate for a position from a large set of applicants. The set A can also be obtained by generating a relatively large number of solutions of a multiple objective mathematical programming problem, e.g., A may be obtained by generating a large number of schedules of a multiple objective scheduling problem.

An image of an alternative a in the criterion space is a *point* $\mathbf{z}^a = [z_1^a, ..., z_J^a]$, such that $z_j^a = f_j(a)$, j=1,...,J. An image of a set A in the criterion space is a set Z composed of points being images of feasible alternatives.

Problem (P1) can also be formulated more succinctly as:

$$\max\{\mathbf{z}\}$$
 (P2) s.t. $\mathbf{z} \in Z$.

Point $\mathbf{z}' \in Z$ is non-dominated if and only if there is no $\mathbf{z} \in Z$ such that $z_j \geq z_j'$, $\forall j$, and $z_i > z_i'$ for at least one *i*. Point $\mathbf{z}' \in Z$ is weakly non-dominated if there is no $\mathbf{z} \in Z$ such that $z_j > z_j'$, $\forall j$. The set composed of all non-dominated points constitutes the non-dominated set denoted by N. For other definitions concerning non-dominance and efficiency, see, e.g., Wierzbicki (1986) and Steuer (1986).

The point \mathbf{z}^* composed of the best attainable criteria function values is called the *ideal point*:

$$z_j^* = \max\{f_j(a), a \in A\}, j = 1,...,J$$

The point z_* composed of the worst criteria function values in the non-dominated set is called the *nadir point*.

3 Main idea of the method

At each iteration the method assigns the non-dominated points to one of three mutually exclusive categories C^+ , C^- and $C^?$. Category C^+ is composed of points not worse than the reference profile \mathbf{z}^{ref} , C^- of points worse than \mathbf{z}^{ref} , and $C^?$ of points incomparable to \mathbf{z}^{ref} . Clearly, to category C^+ belongs each non-dominated point \mathbf{z}^a such that, $\forall j, \quad z_j^a \geq z_j^{ref}$. In practice, however, small differences on a criterion are insignificant to the DM and he/she considers two points indifferent with respect to this criterion. The existence of an indifference region can be caused by an inability of the DM to perceive small differences on a criterion, as well as by imprecision and uncertainty of measurement, and/or of the mathematical model. This phenomenon can be modeled with the *indifference threshold* q_j which is, in general, a function of z_j . So, the assignment of a given non-dominated point \mathbf{z}^a to the acceptance category

 C^+ remains justified if the inequalities $z_j^a \ge z_j^{ref}$ are slightly contradicted for some of the J criteria.

Furthermore, experience indicates that, usually, there is no precise limit between indifference and strict preference, but there exists an intermediary region where the DM hesitates between both while comparing two alternatives a and b. This corresponds to the situation of weak preference between the two alternatives. It can be modeled by the preference threshold p_j which is, in general, a function of z_j , such that:

$$p_j(z_j) \ge q_j(z_j) \ge 0$$

Criterion z_j involving indifference and preference thresholds is called a *pseudo-criterion*. If z_j is to be maximized, then:

a
$$I_j$$
 b, i.e., a and b are indifferent with respect to \mathbf{z}_j \iff $-q_j(z_j^a) \leq z_j^a - z_j^b \leq q_j(z_j^b)$. a Q_j b, i.e., a is weakly preferred to b with respect to \mathbf{z}_j \iff $q_j(z_j^b) \leq z_j^a - z_j^b \leq p_j(z_j^b)$ a P_j b, i.e., a is strictly preferred to b with respect to \mathbf{z}_j \iff $p_j(z_j^b) \leq z_j^a - z_j^b$.

From the other side, often even significant gains on some criteria, may not compensate losses on other criteria. The *veto threshold* v allows to take into account the possible difficulties of comparing two alternatives when one is significantly better than the other on a subset of criteria, but much worse on at least one other criterion. In general, the veto threshold is also a function of z. Alternative a cannot be considered not worse than b if there exists a criterion b such that $z_j^b \ge z_j^a + v_j(z_j^a)$ regardless of the other criteria. If neither a can be considered not worse than b nor b can be considered not worse than a, the two alternatives are qualified as incomparable.

So, the preference model used to compare a non-dominated point \mathbf{z}^a with the reference profile \mathbf{z}^{ref} should take into account the four following situations: indifference I, weak preference Q, strict preference P and incomparability P. For this purpose, the concept of an outranking binary relation P (Roy, 1985) is used. The outranking relation is defined as a grouped relation of P and P. In other words, P P means that P is **not worse** than P Using the outranking relation, one can express all preference situations with respect to two alternatives P and P:

$$a S b$$
 and not $(b S a)$ $\Rightarrow a P b$ or $a Q b$,
 $a S b$ and $b S a$ $\Rightarrow a I b$,
not $(a S b)$ and not $(b S a) \Rightarrow a ? b$.

Construction of the outranking relation S is essentially based on two concepts called concordance and discordance tests. The goals of these tests are, respectively, to:

• characterize a group of criteria considered to be in concordance with the affirmation a S b and assess the relative importance of this criteria group compared to the

remainder criteria, and

• characterize, among the criteria which are not in concordance with the affirmation being studied, the ones whose opposition is strong enough to reduce the credibility of a S b, which would result from taking into account just concordance.

Specifically, it is assumed that:

- if $-q_j(z_j^a) \le z_j^a z_j^b \le q_j(z_j^b)$, then criterion z_j is completely concordant with assertion $a \ S \ b$,
- if $q_j(z_j^a) \le z_j^b z_j^a \le p_j(z_j^a)$, then criterion z_j is partially concordant with assertion $a \ S \ b$.
- if $z_i^b z_i^a \ge v_i(z_i^a)$, then criterion z_i is completely discordant with assertion a S b,
- if $p_j(z_j^a) \le z_j^b z_j^a \le v_j(z_j^a)$, then criterion z_j is partially discordant with assertion a S b.

In the proposed method, the preference model is used to assign the non-dominated points to one of three categories:

$$\mathbf{z}^{a}$$
 is assigned to $C^{+} \Leftrightarrow \mathbf{z}^{a}P \ \mathbf{z}^{ref}$ or $\mathbf{z}^{a}Q \ \mathbf{z}^{ref}$ or $\mathbf{z}^{a}I \ \mathbf{z}^{ref}$, i.e., $\mathbf{z}^{a}S \ \mathbf{z}^{ref}$, \mathbf{z}^{a} is assigned to $C^{-} \Leftrightarrow \mathbf{z}^{ref}P \ \mathbf{z}^{a}$ or $\mathbf{z}^{ref}Q \ \mathbf{z}^{a}$, i.e., $\mathbf{z}^{ref}S \ \mathbf{z}^{a}$ and $\operatorname{not}(\mathbf{z}^{a}S \ \mathbf{z}^{ref})$, \mathbf{z}^{a} is assigned to $C^{7} \Leftrightarrow \mathbf{z}^{a} \ ?\mathbf{z}^{ref}$, i.e., $\operatorname{not}(\mathbf{z}^{a}S \ \mathbf{z}^{ref})$ and $\operatorname{not}(\mathbf{z}^{ref}S \ \mathbf{z}^{a})$.

The categories are mutually exclusive and $A = C^+ \cup C^- \cup C^?$.

Let us note that in the proposed method, the outranking relation models the local preferences of the DM with respect to the reference profile. Thus, a single value of each threshold is needed for a given reference profile. Specifying such values is much easier for the DM than explicitly defining functional thresholds $p_j(z_j)$, $q_j(z_j)$, and $v_j(z_j)$, which have to be defined if the outranking relation is used as a global preference model (cf. Roy and Bouyssou, 1993).

4 General Scheme of the Interactive Procedure

The following is a general scheme of the proposed procedure presented in a Pascal like form:

Find the ideal z*, and nadir z. points; present them to the DM.

Ask the DM to specify a reference profile zref.

Repeat

Get the (updated) preferential information (the indifference and optionally the

preference and/or veto thresholds).

Calculate the three categories (C^+ , C^- and $C^?$).

If $\{C^+ \neq \emptyset\}$ Then

Present to the DM points belonging to this category.

EndIf

If $\{C^? \neq \emptyset\}$ Then

Present (optionally) to the DM points incomparable to the reference profile which are contained in category C?, with possibility of presenting only a given number of representative points.

EndIf

If $\{C \neq \emptyset\}$ Then

Present (optionally) to the DM points belonging to this category.

EndIf

If the DM wants to store the reference profile Then

Add it to the set of "stored points".

If the DM cannot select the final solution from C^+ Then he/she can either:

- attempt to reduce the number of points belonging to C⁺ by defining an optimistic reference profile, i.e., specifying a new profile dominating the current one,
- attempt to increase the number of points belonging to C⁺ by defining a
 pessimistic reference profile, i.e., specifying a new profile dominated by the
 current one.

define a new reference profile nondominated with respect to the current one

- in order to scan a new non-dominated region,
- update the preferential information used to build the outranking relation,
- return to one of the stored points and consider it as a reference profile.

EndIf

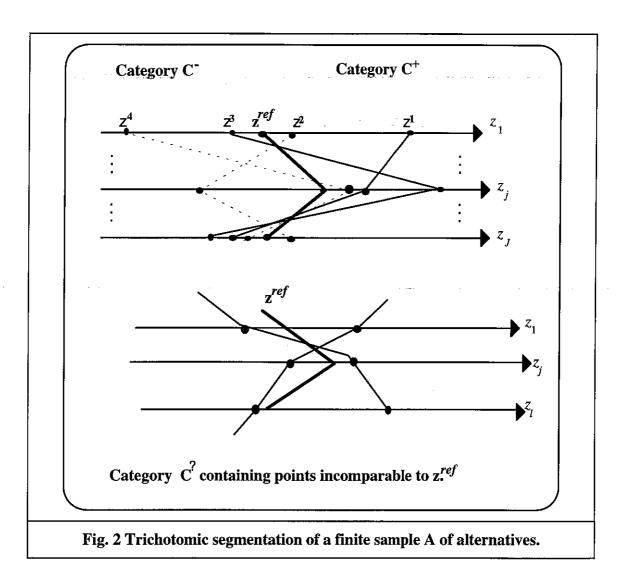
Until The DM feels satisfied with a point found during the interactive process or decides that there is non acceptable solution.

5. Detailed description of particular steps

The method starts by filtering the non-dominated points from the set A. Then the ideal \mathbf{z}^* and nadir \mathbf{z}_* points are found and presented to the DM.

In the first step, the starting reference profile (reference point) \mathbf{z}^{ref} is specified by the DM. Then, the DM is asked to give the preferential information for each criterion \mathbf{z}_j (i.e., the indifference and, optionally, the preference and veto thresholds). At this stage, the DM should decide if he/she wants to specify the preference and/or veto thresholds, however, he/she is allowed to change these settings at each step of the procedure.

The definition of the outranking relation used in this method is based on that proposed in the LBS-Discrete method (Jaszkiewicz and Slowinski, to appear b). This definition does not use criteria weights, but assumes that none of the criteria is more important than all the others together.



In order to test if a point z^a outranks a reference point z^b , the following numbers are used:

 $m_O(\mathbf{z}^a, \mathbf{z}^b)$: the number of criteria for which point \mathbf{z}^a is weakly preferred to \mathbf{z}^b .

 $m_p(\mathbf{z}^a, \mathbf{z}^b)$: the number of criteria for which point \mathbf{z}^a is strictly preferred to \mathbf{z}^b .

 $m_V(\mathbf{z}^a, \mathbf{z}^b)$: the number of criteria being in a strong opposition to the assertion $\mathbf{z}^b \otimes \mathbf{z}^a$.

i.e., card
$$\{j: \mathbf{z}_{i}^{a} \ge z_{i}^{b} + v_{i}, (j=1..,J) \}$$

The construction of the outranking relation depends on the type of preferential information supplied by the DM. If he/she has specified all the thresholds, the following definition of the outranking relation is used:

$$\mathbf{z}^{a} S^{I} \mathbf{z}^{b} \Leftrightarrow \begin{cases} m_{V}(\mathbf{z}^{b}, \mathbf{z}^{a}) = 0 & and \\ m_{P}(\mathbf{z}^{b}, \mathbf{z}^{a}) \leq 1 & and \\ m_{Q}(\mathbf{z}^{b}, \mathbf{z}^{a}) + m_{P}(\mathbf{z}^{b}, \mathbf{z}^{a}) \leq m_{Q}(\mathbf{z}^{a}, \mathbf{z}^{b}) + m_{P}(\mathbf{z}^{a}, \mathbf{z}^{b}) + m_{V}(\mathbf{z}^{a}, \mathbf{z}^{b}) \end{cases}$$

If the DM has decided not to specify the veto thresholds, the following definition of the outranking relation is used:

$$\mathbf{z}^{a} S^{II} \mathbf{z}^{b} \Leftrightarrow \begin{cases} m_{p}(\mathbf{z}^{b}, \mathbf{z}^{a}) = 0 \text{ and} \\ m_{Q}(\mathbf{z}^{b}, \mathbf{z}^{a}) \leq m_{Q}(\mathbf{z}^{a}, \mathbf{z}^{b}) + m_{p}(\mathbf{z}^{a}, \mathbf{z}^{b}) \end{cases}$$

If the DM has decided not to specify the preference threshold, the following definition of the outranking relation is used:

$$\mathbf{z}^{a} S^{III} \mathbf{z}^{b} \Leftrightarrow \begin{cases} m_{V}(\mathbf{z}^{b}, \mathbf{z}^{a}) = 0 \text{ and} \\ m_{P}(\mathbf{z}^{b}, \mathbf{z}^{a}) \leq 1 \text{ and} \\ m_{P}(\mathbf{z}^{b}, \mathbf{z}^{a}) \leq m_{P}(\mathbf{z}^{a}, \mathbf{z}^{b}) + m_{v}(\mathbf{z}^{a}, \mathbf{z}^{b}) \end{cases}$$

Finally, if the DM has decided to specify only the indifference thresholds, the following definition of the outranking relation is proposed:

$$\mathbf{z}^a S^{IV} \mathbf{z}^b \Leftrightarrow m_p(\mathbf{z}^b, \mathbf{z}^a) = 0$$

Observe that, for a given set of values q_i , p_j , v_j (j = 1,...,l) the following inclusions hold:

$$S^{IV} \subseteq S^{II} \subseteq S^I$$
 and $S^{IV} \subseteq S^{III} \subseteq S^I$. Moreover, $S^{II} = S^I$ if $p_j = v_j, \forall j, \quad S^{III} = S^I$ if $q_j = p_j, \forall j, \quad S^{III} = S^I$ if $q_j = p_j = v_j, \forall j.$

In the computation phase of the procedure, three categories C^+ , C^- and $C^?$ delimited by an outranking profile given by the DM are calculated. Each point belonging to the set N is compared to the reference profile \mathbf{z}^{ref} , the ones which outrank \mathbf{z}^{ref} are classified in the acceptance category C^+ , corresponding to the sub-region containing points which are not worse than the profile, i.e., outrank the profile. The ones which are outranked by \mathbf{z}^{ref} and do not outrank \mathbf{z}^{ref} are classified in the rejection category C^- , and the ones which are incomparable to \mathbf{z}^{ref} are classified in the incomparability category $C^?$.

The three categories C^+ , C^- and C^7 are calculated in the following way:

For each non-dominated point z^a belonging to the non-dominated set N:

If
$$z^a S z^{ref}$$
 then $z^a \in C^+$

else

If
$$(\mathbf{z}^{ref} S \mathbf{z}^a)$$
 then $\mathbf{z}^a \in C^{\bullet}$
else $\mathbf{z}^a \in C^{\circ}$

In the decision phase, if the acceptance category C^+ is not empty, then it is presented to the DM. If he/she thinks that the number of points belonging to this category is too large, it is possible to present to him/her the so called *characteristic points* of the acceptance category and the *locally ideal* point $\overline{\mathbf{z}}^*$. The characteristic points are points \mathbf{z}^j , j=1,...,J, that maximize particular criteria within this category. The locally ideal point $\overline{\mathbf{z}}^*$ is defined from the characteristic points: $\overline{z}_j^* = z_j^j$, j=1,...,J.

The DM can also see the points belonging to incomparable category C^2 . Presentation of incomparable points can help the DM in defining a new reference profile non-dominated with respect to the previous one. In the case where the number of points in C^2 is too large, the DM may specify the number of representative points that he/she would like to see. Selecting a given number of the most representative points consists in solving the maximal dispersion problem (cf. White, 1991). Because finding the optimal solution of this problem is prohibitively time consuming, it is advised to use one of the heuristic filtering techniques (Steuer, 1986, Chap. 11; Törn 1980).

Optionally, the DM can see the rejection category C.

If the acceptance category C^+ is not empty but contains too many points, the DM has the possibility to define interactively an *optimistic reference profile* by increasing successively or simultaneously the performances of the reference profile \mathbf{z}^{ref} . Otherwise, if the category C^+ is empty or contains too few points, the DM has, as above, the possibility to define interactively a pessimistic reference profile by decreasing successively or simultaneously the performances of the reference profile \mathbf{z}^{ref} . Moreover, he/she can scan another sub-region of the non-dominated set by defining another reference profile non-dominated with respect to the current one.

The procedure stops if one of the points presented is satisfactory for the DM on all criteria.

Before continuing the scanning, the DM can store the reference profile. He/she is allowed to go back to one of the stored points at any time.

Finally, the DM is able to modify the preferential information given for each criterion, i.e., the values of indifference, preference and veto thresholds. He/she can also change the type of the outranking relation.

6 Application

In order to illustrate the work with the procedure, a nurse scheduling problem is used. The problem is described in Jaszkiewicz and Lewandowska (1996). Because of limited space a brief description only is given here. The data used come from the God's Transformation Hospital in Poznan. The precise description of the problem is available from the authors upon request.

The problem consists in finding a feasible schedule, i.e. in selecting a working shift (morning, afternoon or night) or a day-off for each nurse and each day in the scheduling period such that all the constraints are satisfied. The scheduling period is one month and 15 nurses are scheduled. The following goals are taken into account:

- Grouping of working days in which a nurse works on the same shift. In order to achieve this goal the average number of working days pairs in which a nurse works on different shifts (C_1) is minimized.
- Grouping of working days. This goal is achieved by minimizing the average deviation of the length of each sequence of working days form a desired length (C_2) .
- Grouping of free days. In order to achieve this goal the average length of each sequence of free days (C_3) is maximized.
- Uniform distribution of types of working shifts over the personnel. This goal is achieved by minimizing the average deviation of the number of each type of the working shifts from the numbers of shifts resulting from totally uniform distribution (C_4) .
- Uniform distribution of nurses on morning shifts. In order to achieve this goal the average deviation of the number of person during each morning shift from such a number resulting from totally uniform distribution is minimized (C_s) .

All the above criteria are averaged over the set of all nurses.

The problem defined above belongs to the class of multiple objective combinatorial optimization problems. In order to solve it a two stages procedure is proposed. In the first stage a sample of potentially efficient solution approximating the whole set of efficient solutions is generated by the Pareto-Simulated Annealing metaheuristic procedure (Czyzak and Jaszkiewicz, 1996). In result of the first stage 544 different solutions were obtained. In the second stage the trichotomy based procedure was used to support the decision maker in selecting the best compromise schedule. An exemplary interactive session is presented below.

The ideal z^* point is as follows:

$$C_1 = 0.93$$
, $C_2 = 6.28$, $C_3 = 2.20$, $C_4 = 1.74$, $C_5 = 1.710$,

while the nadir \mathbf{z}_* is:

$$C_1 = 6.50$$
, $C_2 = 18.43$, $C_3 = 1.29$, $C_4 = 10.55$, $C_5 = 2.097$.

The above two points are presented to the DM, then he/she specifies the following reference profile \mathbf{z}^{ref} and thresholds q_j , p_j , v_j :

$$C_1 = 2.5$$
, $C_2 = 9.5$, $C_3 = 2$, $C_4 = 4$, $C_5 = 1.8$.

Criterion	C_1	C_2	C_3	C_4	C_5
Indifference q_i	0.2	0.2	0.1	0.5	0.1
Preference p _i	0.5	0.5	0.2	1	0.2
Veto v,	1.5	1.5	0.5	3	0.5

In the computational phase, the three categories C^{+} , C^{-} , C^{0} are obtained. Number of points in each category is given below:

Category	C+	C-	C^{γ}
Number of point	0	430	114

None of the solutions can be considered not worse than \mathbf{z}^{ref} because the aspiration levels specified by the DM are too demanding and the preferential thresholds too strict. So, one of options that the DM may consider is to define a more pessimistic reference profile by giving on all or some objectives worse values of the aspiration levels. The DM is, however, interested in seeing the C^7 category. Because the number of points in C^7 is too large, he/she decides to see 16 representative points, which are given below:

<u> </u>		T .	1		
Criterion	C_1	C_2	C_3	C_4	C_5
$\mathbf{z}^{_1}$	4	6.64	1.87	3.72	1.97
\mathbf{z}^2	4.14	6.57	1.95	4.21	1.84
\mathbf{z}^3	2	15.36	1.46	3.35	1.84
\mathbf{z}^4	5.64	7	2.01	3.22	1.71
z ⁵	4	7.36	1.94	4.21	1.84
\mathbf{z}^6	6.07	8.57	2.15	3.51	1.71
\mathbf{z}^7	5	9.5	2.14	2.88	1.84
z ⁸	1.93	14.93	1.49	2.88	1.97
Z ⁹	6.36	7.93	1.96	2.95	1.71
\mathbf{z}^{10}	4.21	6.36	1.93	4.14	1.84
\mathbf{z}^{11}	4.36	6.29	1.89	3.26	1.90
\mathbf{Z}^{12}	4.79	9	2.1	2.88	1.9
Z ¹³	3.86	7.36	1.82	4.14	1.84
\mathbf{Z}^{14}	4.29	6.64	1.87	3.26	1.9
\mathbf{Z}^{15}	4.79	6.36	1.98	4.01	1.77
\mathbf{Z}^{16}	4	6.29	1.89	3.9	1.9

It can be observed that only two of the points are better on criterion C_1 than the corresponding aspiration level's value. The same two points are the only ones that are worse of criterion C_2 than the corresponding aspiration level's value. So, the DM decided to be less demanding on C_1 and more demanding on C_2 , He/she tries to achieve it by defining a new reference profile.

$$C_1 = 5$$
, $C_2 = 8$, $C_3 = 2$, $C_4 = 4$, $C_5 = 1.8$.

This changes the assignment of points to C^{+} , C^{-} , C^{0} categories. Number of points in each category is given below:

Category	C+	C	C^{γ}
Number of point	86	197	261

The DM decides to see a representation of the C+ category composed of 10 points which are

given below:

Criterion	C_1	C_2	C_3	C_4	C ₅
$\mathbf{z}^{_1}$	4.86	8.93	2.13	2.88	1.9
\mathbf{z}^2	4.21	9.43	2.17	3.93	1.9
z 3	-5:21	-8.93	2.13	2.97	1.84
\mathbf{Z}^4	4.93	6.36	1.98	3.58	1.77
\mathbf{z}^5	4.14	9.21	2.14	3.41	1.9
\mathbf{z}^6	4.36	9.43	2.18	3.41	1.9
\mathbf{z}^7	4.29	6.79	2.03	3.79	1.71
z ⁸	4.29	6.36	1.98	4.14	1.84
z 9	4.43	6.79	2	3.6	1.71
\mathbf{z}^{10}	4.07	7.14	2	3.83	1.71

Analyzing the points the DM sees a possibility of finding solutions giving relatively good results on C_1 , C_2 and C_4 . So, he/she decides to specify an optimistic reference profile by being more demanding of the three criteria and update the preferential thresholds. He/she specifies the following reference profile:

$$C_1 = 4$$
, $C_2 = 7$, $C_3 = 2$, $C_4 = 3$, $C_5 = 1.8$.

The updated thresholds are as follows:

Criterion	C_1	C_2	C_3	C_4	C_5
Indifference q_i	0.2	0.2	0.1	0.5	0.1
Preference p,	0.4	0.4	0.2	.7	0.2
Veto v,	1	1	0.5	1.5	0.5

Observe, that the DM has decreased values of preference and veto thresholds on C_1 , C_2 and C_4 . This means that at this moment smaller differences of C_1 , C_2 and C_4 result in strict preference, and smaller worsening of values of these criteria results in rejection of a given alternative.

Number of points in each category is given below:

Category	C+	C	C^{7}
Number of point	4	354	186

The following points belong to the C^+ category:

Criterion	C_1	C_2	C_3	C_4	C_5
\mathbf{z}^1	4.14	6.79	2.01	3.83	1.71
\mathbf{Z}^2	4.79	6.79	1.97	3.46	1.71
\mathbf{z}^3	4.86	6.79	1.97	3.34	1.71
\mathbf{Z}^4	4.14	6.57	1.95	4.21	1.84

Finally, the DM feels satisfied with point z^1 . So, the best compromise gives the following values of objectives:

$$C_1 = 4.14$$
, $C_2 = 6.79$, $C_3 = 2.01$, $C_4 = 3.83$, $C_5 = 1.71$.

7 Conclusion

A procedure for solving the multiple-criteria choice problems with large sets of alternatives (MCCL) is proposed. It models the preferences of the DM with respect to a reference profile by using outranking relation. The preference model is used in order to distinguish the class C^+ of alternatives that can be considered not worse than the reference profile, the class C^- of alternatives being worse than the reference profile and class C^0 of alternatives incomparable to the reference profile. During the interaction, the procedure helps the DM in concentrating on the most interesting region of the non-dominated set and in reducing the size of the C^+ class such the he/she can select the best alternative from this class.

In the decision phase, many non-dominated points may be presented to the DM. Both numerical and graphical forms of presentation with statistical data (like the percent of nondominated points belonging to each category) should be used to help the DM in evaluating large amounts of information.

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