On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments
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KERNEL STABLE COALITION FORMATION

Bardia Khalesi, Magnus Nord

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General

Introduction KCA algorithm

- On safe kernel stable coalition forming among agents Introduction Properties of the KCA
- 3 Feasible Formation of Coalitions in NonSuperAdditive Environments

Introduction DEK-CFM Protocol Truncated Transfer Scheme DNPK-CFM Protocol



Conclusion

General ●00 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{_{\circ\circ\circ\circ\circ}}$	Feasible Formation of Coalitions in NonSuperAdditive Environments
Introducti	on	



• Formation of kernel stable coalitions



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Introducti	00	



- Formation of kernel stable coalitions
 - KCA algorithm

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Intro	luction	



• Local value or *lworth*_a(*C*) of an agent a is the sum of the self-worth and the marginal contribution to the coalition *C*.

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Intro	luction	



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- Local value or *lworth_a*(*C*) of an agent a is the sum of the self-worth and the marginal contribution to the coalition *C*.
- Non-super-additive Games

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Intro	luction	

Overview

- Local value or *lworth*_a(*C*) of an agent a is the sum of the self-worth and the marginal contribution to the coalition *C*.
- Non-super-additive Games
 - At least one pair of potential coalitions are not better off by merging

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- Local value or *lworth_a(C)* of an agent a is the sum of the self-worth and the marginal contribution to the coalition C.
- Non-super-additive Games
 - At least one pair of potential coalitions are not better off by merging
 - Costly to increase the amount of members in a coalition

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Introd	uction	

Kernel

- Why the kernel?
 - Will not be empty



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- Why the kernel?
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 - Handles agent symmetry

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 - Pareto optimality is insufficient for the evaluation of possible coalitions.

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KCA algorithm

Communication

1 Every agent is coalition leader in its singelton coalition

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KCA algorithm

Communication

- Every agent is coalition leader in its singelton coalition
- 2 Send and receive tasks from all other agents

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KCA algorithm

Communication

- Every agent is coalition leader in its singelton coalition
- 2 Send and receive tasks from all other agents
- 3 Send and receive evaluations of the tasks

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KCA algorithm

Communication

- Every agent is coalition leader in its singelton coalition
- 2 Send and receive tasks from all other agents
- 3 Send and receive evaluations of the tasks
- For all possible coalitions: evaluate *lworth_a(C)* and send to all agents

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KCA algorithm

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- **5** Receive all local values from all other agents
- Generating Proposals
 - 1 If the agent is not leader of the coalition, 4.3.

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KCA algo	rithm	

- 8 Evaluating proposal
 - 1 Evaluate received proposals, choose the most beneficial



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KCA algo	rithm	

- 8 Evaluating proposal
 - Evaluate received proposals, choose the most beneficial
 - 2 Inform all leaders about accepted proposal
- Deciding coalition configuration

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KCA algo	rithm	

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 - Receive accepted proposals: if none was accepted, then stop

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- 8 Evaluating proposal
 - Evaluate received proposals, choose the most beneficial
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 - Receive accepted proposals: if none was accepted, then stop
 - Choose one configuration, by considering the order of preferences: bilateral > unilateral, biggest payoff distribution than greatest computational power.

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Inform all coalition members about new configuration

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- 3 Evaluating proposal
 - Evaluate received proposals, choose the most beneficial
 - 2 Inform all leaders about accepted proposal
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 - Receive accepted proposals: if none was accepted, then stop
 - 2 Choose one configuration, by considering the order of preferences: bilateral > unilateral, biggest payoff distribution than greatest computational power.

3 Inform all coalition members about new configuration A New coalition leader is the agent with the highest computational power. The other coalition leaders are informed about the new leader

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- 8 Evaluating proposal
 - Evaluate received proposals, choose the most beneficial
 - Inform all leaders about accepted proposal
- Occiding coalition configuration
 - Receive accepted proposals: if none was accepted, then stop
 - Choose one configuration, by considering the order of preferences: bilateral > unilateral, biggest payoff distribution than greatest computational power.
 - 3 Inform all coalition members about new configuration
 - A New coalition leader is the agent with the highest computational power. The other coalition leaders are informed about the new leader
 - If grand coalition is formed, or time ends: stop. Else go back to Generating proposals

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• Some elements which can affect the performance

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- Some elements which can affect the performance
 - Distribution

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KCA algorithm

- · Some elements which can affect the performance
 - Distribution
 - Communication cost

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KCA algorithm

- Some elements which can affect the performance
 - Distribution
 - Communication cost
 - · Limited computation time

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KCA algorithm

- · Some elements which can affect the performance
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- Therefore there is a trade-off between quality of solution, and speed

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KCA algorithm

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 - Distribution
 - · Communication cost
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- Therefore there is a trade-off between quality of solution, and speed
 - Quality: payoff maximization and stability
 - · Speed: efficiency and anytime algorithm

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On safe kernel stable coalition forming among agents

Investigates several properties of the KCA algorithm

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On safe kernel stable coalition forming among agents

- Investigates several properties of the KCA algorithm
 - Incomplete information

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On safe kernel stable coalition forming among agents

- Investigates several properties of the KCA algorithm
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On safe kernel stable coalition forming among agents

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On safe kernel stable coalition forming among agents

- Investigates several properties of the KCA algorithm
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On safe kernel stable coalition forming among agents

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- Paper contains many examples, but will skip these due to time constraints

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On safe kernel stable coalition forming among agents

- Investigates several properties of the KCA algorithm
 - Incomplete information
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 - Privacy
 - Fraud
- Paper contains many examples, but will skip these due to time constraints
- Fairly general: Considers both superadditive and non-superadditive games

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Incomplete information

Example: an agent does not receive the coalition value for some coalition

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- Example: an agent does not receive the coalition value for some coalition
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- Coalition negotiations are safe with respect to unknown coalition values

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Propertie	s of the KCA	

• During the negotiations agents might become unavailable (for example, network connection breaking down)

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- The severity depends on if it is a coalition leader or member which becomes unavailable
- If a leader drops out, the coalition will not be send out, or receive, any proposals. In addition the other members in the coalition will not be informed about the new configuration
- The coalition negotiation will therefore not be safe if the agent set is changing

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Propertie	s of the KCA	

• A surprising property of the KCA algorithm, is the ability of the agents to hide their local information without any profit loss in the final configuration

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- A surprising property of the KCA algorithm, is the ability of the agents to hide their local information without any profit loss in the final configuration
- This is caused by an inherent property of the definition of kernel stability: an amount added to the valuation function for a coalition will be subtracted when calculating the surplus.

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- Therefore the local values are not required to be communicated between the agents to reach a kernel stable solution
- If and only if, the local information is exclusively used to compute its self-value
- Therefore the coalition negotiations are safe with respect to privacy

Genera 000 000	On safe kernel stable coalition forming among agents ○ ○ ○ ○ ○	Feasible Formation of Coalitions in NonSuperAdditive Environments
Proper	ties of the KCA	

- A surprising property of the KCA algorithm, is the ability of the agents to hide their local information without any profit loss in the final configuration
- This is caused by an inherent property of the definition of kernel stability: an amount added to the valuation function for a coalition will be subtracted when calculating the surplus.
- Therefore the local values are not required to be communicated between the agents to reach a kernel stable solution
- If and only if, the local information is exclusively used to compute its self-value
- Therefore the coalition negotiations are safe with respect
 to privacy

General 000 000	On safe kernel stable coalition forming among agents ${\stackrel{\circ}{\scriptstyle\circ}}_{\circ\circ\circ\bullet}$	Feasible Formation of Coalitions in NonSuperAdditive Environments
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• Waiting to communicate *lworth*_a(*C*) until it has received all the other agent's *lworth*

General 000 000	On safe kernel stable coalition forming among agents ${\stackrel{\circ}{\scriptstyle\circ}}_{\circ\circ\circ\bullet}$	Feasible Formation of Coalitions in NonSuperAdditive Environments
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General 000 000	On safe kernel stable coalition forming among agents $\overset{\circ}{}_{\circ\circ\bullet}$	Feasible Formation of Coalitions in NonSuperAdditive Environments
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General 000 000	On safe kernel stable coalition forming among agents $\overset{\circ}{\underset{\circ}{\circ}}_{\circ\circ\circ\bullet}$	Feasible Formation of Coalitions in NonSuperAdditive Environments
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- Can not be prevented or detected
- However this is computational complex: the fraudulent agent has to check all (*O*(2^{*n*})) possible coalitions
- Other agents might become suspicious because of the delay in the deceiving agent's communication

General 000 000	On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments ● ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○

Environment Description

- Distributed AI:
 - Cooperative Distributed Problem Solving(CDPS)→ distribution of required effort for solving a particular problem among a number of modules(or nodes).

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General 000 000	On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments ●○○ ○○○ ○○○ ○○○

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- Distributed AI:
 - Cooperative Distributed Problem Solving(CDPS)→ distribution of required effort for solving a particular problem among a number of modules(or nodes).
 - Multiagent Systems (MAS)→ coordinating intelligent behavior among autonomous, heterogeneous, intelligent agents.

General ooo ooo	On safe kernel stable coalition forming among agents o	Feasible Formation of Coalitions in NonSuperAdditive Environments ●○○ ○○○ ○○○ ○○○

Environment Description

- Distributed AI:
 - Cooperative Distributed Problem Solving(CDPS)→ distribution of required effort for solving a particular problem among a number of modules(or nodes).
 - Multiagent Systems (MAS)→ coordinating intelligent behavior among autonomous, heterogeneous, intelligent agents.
- Protocols:
 - Any interaction among agents requires some protocols. As more protocols are enforced on the agents, communication usually decreases. Yet the protocols may be contradictory to the rationality of an individual agent.
 - Any deviation from the protocols must be revealable and penalizable, or the protocols must be self-enforced.
 - Some constrains are needed to avoid an endless loop of rejected proposals for coalition formation.

General 000 000	On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●○ ○○○ ○○○ ○○○

Environment Description

- Strategies:
 - the method that agents employ to handle proposals, such as increasing the payoff or satisfying an equilibrium requirement.

General 000 000	On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●○ ○○○ ○○○ ○○○

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 - Approach 1: High computations, thus vast increase in the complexity of the model.

General 000 000	On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●○ ○ ○ ○ ○ ○

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General 000 000	On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●○ ○ ○ ○ ○ ○

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 - Approach 2: Bounded rationality leads to approximations which is not satisfactory due to existence of better decisions.
 - Approach 3: Time-bounded equilibrium → By belief of maximizing the expected utility with respect to a bounded computation time of a strategy.

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General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\circ} \overset{\text{O}}{\circ} $	Feasible Formation of Coalitions in NonSuperAdditive Environments

Definitions

- Payment Configuration (**PC**(**U**,**C**)):
 - **U** =< *u*₁, *u*₂, ..., *u*_n >, where *u*_i is the payoff to *A*_i

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General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\circ} \overset{\text{O}}{\circ} $	Feasible Formation of Coalitions in NonSuperAdditive Environments

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 - $\mathbf{C} = \{C_i\}$, where $\cup_i C_i = N; \forall C_i, C_j; C_i \neq C_j; C_i \cap C_j = \emptyset$

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General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\circ} \overset{\text{O}}{\circ} $	Feasible Formation of Coalitions in NonSuperAdditive Environments

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General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\underset{O}}{\underset{O}{O$	Feasible Formation of Coalitions in NonSuperAdditive Environments

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- PC relative error: $\mathbf{e}_{\mathbf{r}} = \frac{\mathbf{e}}{\sum u_i}$

Genera 000 000	al On safe kernel stable coalition forming among agents O OOOO	Feasible Formation of Coalitions in NonSuperAdditive Environments

DEK-CFM Protocol

 Distributed, Exponential, Kernel-oriented Coalition-Formation Model (*DEK-CFM*) leads to a PC that is Pareto optimal and K-stable.

Genera 000 000	al On safe kernel stable coalition forming among agents O OOOO	Feasible Formation of Coalitions in NonSuperAdditive Environments

DEK-CFM Protocol

- Distributed, Exponential, Kernel-oriented Coalition-Formation Model (*DEK-CFM*) leads to a **PC** that is **Pareto optimal** and **K-stable**.
- In cases where time, communications, and computation are cheap or costless,or in cases where there is a small number of agents, *DEK-CFM* is adequate.

Genera 000 000	On safe kernel stable coalition forming among agents o oooo	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○ ○ ○ ○ ○

- Protocol:
 - compute all of the coalitions and corresponding coalitional values and transmit all of them to other agents.

Genera 000 000	On safe kernel stable coalition forming among agents o oooo	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○ ○ ○ ○ ○

• Protocol:



- compute all of the coalitions and corresponding coalitional values and transmit all of them to other agents.
- 2 A_i is assigned to a unique random integer $z_i \in [1, n]$

Genera 000 000	I On safe kernel stable coalition forming among agents o oooo	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○●● ○ ○○○
	EM Brotocol	

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Genera 000 000	I On safe kernel stable coalition forming among agents o oooo	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○●● ○ ○○○
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- 4 find a K-stable PCs of each computed CCs.

Genera 000 000	I On safe kernel stable coalition forming among agents o oooo	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○●● ○ ○○○
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- **5** list personally *Pareto optimal* **PC**s from computed **PC**s.

General 000 000	On safe kernel stable coalition forming among agents o ooco	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○ ○ ○ ○ ○
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- 6 merge lists of all agents in one list and find the Pareto optimal PCs:

General 000 000	On safe kernel stable coalition forming among agents o ooco	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○ ○ ○ ○ ○
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 - iteration *j*: A_i s.t. $z_i \mod 2^j = 1$ merge its list with A_k s.t. $z_k = z_i + 2^{j-1}$

General 000 000	On safe kernel stable coalition forming among agents o ooco	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○ ○ ○ ○ ○
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General 000 000	On safe kernel stable coalition forming among agents o ooco	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○ ○ ○ ○ ○
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General 000 000	On safe kernel stable coalition forming among agents o ooco	Feasible Formation of Coalitions in NonSuperAdditive Environments ○●● ○ ○ ○ ○ ○
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 - stop iteration if all of the agents have been approached.
- choose one of the found *Pareto optimal* PCs by the decision-making method

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DEK-CFM Protocol



8 transmit all the details of the calculations to other agents



KERNEL STABLE COALITION FORMATION

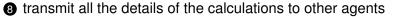
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	Protocol	



8 transmit all the details of the calculations to other agents

9 any deceitful PC can be detected and canceled by the received calculations.

General 000 000	On safe kernel stable coalition forming among agents ° ° °	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ○○○ ○○○○
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- any deceitful PC can be detected and canceled by the received calculations.
 - complexity of the computation of coalitional values and configurations is O(nⁿ)

General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\underset{O}{O$	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○ ○

- To calculate the K-ε-stable PCs:
 - Start with a U₀

General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\underset{O}{O$	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○ ○

- To calculate the K-ε-stable PCs:
 - **1** Start with a U_0
 - **2** If $\sum u_i > \sum V(\mathbf{C})$ Then use the n-correction of Wu(1977)

General 000 000	On safe kernel stable coalition forming among agents o	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○○○ ● ○○○

- To calculate the K-*ɛ*-stable **PC**s:
 - Start with a U₀
 - **2** If $\sum u_i > \sum V(\mathbf{C})$ Then use the n-correction of Wu(1977)
 - **3** Calculate the demand functions with respect to U_i

General 000 000	On safe kernel stable coalition forming among agents o	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○○○ ● ○○○

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 - 4 Find the greatest d_{ij}

General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\underset{O}{O$	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○ ○

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 - Find the greatest d_{ij}
 - **5** Pass part α , $0 < \alpha \leq d_{ij}$ of **U**_i of one agent to another agents

General 000 000	On safe kernel stable coalition forming among agents o	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○○○ ● ○○○

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 - 3 Calculate the demand functions with respect to U_i
 - 4 Find the greatest d_{ii}
 - **5** Pass part α , $0 < \alpha \leq d_{ii}$ of U_i of one agent to another agents
 - 6 Form **U**_{*i*+1}

General 000 000	On safe kernel stable coalition forming among agents o	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○○○ ● ○○○

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 - **7** If $\mathbf{e}_{\mathbf{r}} \leq \varepsilon$, Then stop and return \mathbf{U}_{i+1} as the result

General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\underset{O}{O$	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○ ○

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General 000 000	On safe kernel stable coalition forming among agents o	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○○○ ● ○○○

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 - 6 Form **U**_{*i*+1}
 - **7** If $\mathbf{e}_{\mathbf{r}} \leq \varepsilon$, Then stop and return \mathbf{U}_{i+1} as the result
 - If not, do next iteration
- complexity of the computation of the K-ε-stable and Pareto optimal PCs is O(n2ⁿ)

General 000 000	On safe kernel stable coalition forming among agents o	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ○○○ ● ○○○

Truncated Transfer Scheme

- To calculate the K-*ɛ*-stable **PC**s:
 - Start with a U₀
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 - 3 Calculate the demand functions with respect to U_i
 - Find the greatest d_{ij}
 - **6** Pass part α , $0 < \alpha \leq d_{ij}$ of **U**_i of one agent to another agents
 - 6 Form U_{i+1}
 - **7** If $\mathbf{e}_{\mathbf{r}} \leq \varepsilon$, Then stop and return \mathbf{U}_{i+1} as the result
 - If not, do next iteration
- complexity of the computation of the K-ε-stable and Pareto optimal PCs is O(n2ⁿ)
- Thus, **DEK-CFM** has $O(n2^n n^n)$

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General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\underset{O}}{\underset{O}{O$	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ○ ● ● ● ● ●

The Negotiation-oriented CFM

• Distributed, Negotiation-based, Polynomial, Kernel-oriented Coalition-Formation Model (*DNPK-CFM*) is a reduced-cost CFM based on negotiation.

General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\circ} \overset{\text{O}}{\circ} $	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ○ ● ● ○○○

The Negotiation-oriented CFM

- Distributed, Negotiation-based, Polynomial, Kernel-oriented Coalition-Formation Model (*DNPK-CFM*) is a reduced-cost CFM based on negotiation.
- It is an anytime Algorithm due to reaching a steady state:
 - the agents have reached a K-stable and Pareto optimal PC, or
 - the agents have not reached a PC as in 1, but have no more possible beneficial proposals (allowed by the protocols) to be transmitted to others.

General 000 000	On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ● ● ● ● ●

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- It is an anytime Algorithm due to reaching a steady state:
 - 1 the agents have reached a K-stable and Pareto optimal PC. or

 - 2 the agents have not reached a PC as in 1, but have no more possible beneficial proposals (allowed by the protocols) to be transmitted to others.
- protocols must be agreed on that will direct the agents to a well-defined polynomial set of coalitions.
 - thus, only coalitions of sizes in the ranges $[K_1; K_2]$ are allowed to be considered for excess calculations.

Gene 000 000	ral On safe kernel stable coalition forming among agents o o o o o o o	Feasible Formation of Coalitions in NonSuperAdditive Environments
DNP	K-CFM Protocol	

The Negotiation-oriented CFM

 Preliminary Stage: Prior to negotiation, the agents must calculate the values of coalitions in the range of sizes K₁ to K₂, using the calculation methods of the DEK-CFM.

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The Negotiation-oriented CFM

- Preliminary Stage: Prior to negotiation, the agents must calculate the values of coalitions in the range of sizes K_1 to K_2 , using the calculation methods of the DEK-CFM.
- First Stage:

 - agents receive proposals as a member of a coalition
 - 2 coalitions coordinate their actions either via a representative or by voting (or both)



3 coalitions perform iteratively as follow:

- transmit a proposal to a target coalition; wait for responses
- accept P_{rp} only if $P_{rp} = P_{pr}$
- if P_{rp} was accepted and mutually confirmed, form C_{r+p}; if necessary, choose the representative.
- send acceptance of P_{rp} to other coalitions and reject other proposals.

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The Negotiation-oriented CFM

First Stage:



The above sequence should be repeated until a steady state is reached, or when the time-period ends.

S Announce th status (if there are any more proposals to transmit)

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- First Stage:

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- Second (optional) Stage:

General 000 000	On safe kernel stable coalition forming among agents $\overset{\text{O}}{\underset{O}}{\underset{O}{O$	Feasible Formation of Coalitions in NonSuperAdditive Environments ○○○ ○○○ ○○●○

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- Announce the status

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General 000 000	On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments
DNPK-C	EM Protocol	

• DNPK-CFM is enforceable because deviation from it is revealable.

General 000 000	On safe kernel stable coalition forming among agents o oooo	Feasible Formation of Coalitions in NonSuperAdditive Environments
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$$n_{\text{coalitions}} = \sum_{i=K_1}^{K_2} \frac{n!}{i!(n-i)!}$$

• preliminary stage: $O(n^2 \times n_{coalitions})$

Genera 000 000	I On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments
DNPK-	CEM Protocol	

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- communication: $O(n^2 \times n_{coalitions})$
- thus, the upper limit is of order $O(n^n)$

General 000 000	On safe kernel stable coalition forming among agents	Feasible Formation of Coalitions in NonSuperAdditive Environments 000 000 000

Using the KCA algorithm one can achieve kernel stable solutions

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- By modifying KCA two approaches can be achieved
 - DEK-CFM: pareto optimal and k-stable coalition
 - DNPK-CFM: polynomial and k-*\varepsilon*-stable
 - These algorithms are enforceable and thus deviations are revealable