

On the emergence of social conventions

Michael Replinger

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Introduction

Classical Games

Stochastic Games

Experimental Results

Discussion

What we are interested in

- ▶ We want to model systems of agents trying to achieve different goals
- ▶ In such systems, rules helps promote cooperative behavior, increasing efficiency
- ▶ Rules could be agreed upon beforehand, or emerge during the process

How to model it

- ▶ Classical (static) framework of game theory; social laws in this framework
- ▶ Rationality as individual advantage
- ▶ Stochastic setting in which certain conventions emerge through repeated interaction
- ▶ Analytic and empirical considerations regarding emergence of conventions

The static game

- ▶ k-person games, as Normal-form game
- ▶ Only symmetric games:
 - ▶ Agents have same strategies
 - ▶ Identical play, identical payoff
 - ▶ Invariant under permutation, i.e. payoff does not depend on role
- ▶ Further restriction: 2-person 2-choice games

2-person 2-choice game, general form

$$\begin{pmatrix} x, x & u, v \\ v, u & y, y \end{pmatrix}$$

Coordination game (e.g driving conventions)

$$\begin{pmatrix} 1, 1 & -1, -1 \\ -1, -1 & 1, 1 \end{pmatrix}$$

Cooperation game (Prisoner's dilemma)

$$\begin{pmatrix} 1, 1 & -3, 3 \\ 3, -3 & -2, -2 \end{pmatrix}$$

Strategies and results

- ▶ Rational agents are maximizers of individual utility. (*)
- ▶ Maximin strategy: highest minimal payoff (find worst payoff, decide on best response). Makes sense if other players might be imbeciles.
- ▶ Nash equilibrium is sensible if other players know the game as well and are rational as defined above (as they will not choose a bad payoff for themselves).
- ▶ Pareto optimality: if no joint action exists that improves one player while the others stay at least as good.

Applied to our examples

- ▶ Coordination: maximin value is -1 , both strategies are maximin strategies; $1,1$ and $2,2$ are Nash equilibria and Pareto optimal.
- ▶ Cooperation: maximin value is -2 , $2,2$ is maximin strategy and Nash equilibrium. Everything *but* $2,2$ is Pareto optimal.

Central authority

- ▶ Without a central authority, it seems plausible that players defect (even though they suffer).
- ▶ Constraints that benefit society as a whole, or each individual could be introduced by an authority.
- ▶ The interesting question: can such (globally beneficial) constraints emerge from individual interaction? If so, only if all (or most) players accept a constraint as individually rational.

Definitions

- ▶ A **social law** is a restriction on the set of actions of the agents.
- ▶ **Game variables**: $V(g)$ is the value (or set of values) that can be achieved by a certain strategy wrt. a game g .
- ▶ **Rational social law** wrt. g and V : if $V(g) < V(g_{sl})$. NB: Ordering simple for maximin.
- ▶ **Social convention**: a social law that restricts players to one particular strategy.

Applied to our examples

- ▶ Coordination: two rational conventions wrt. maximin value: 1,1 and 2,2.
- ▶ Cooperation: unique rational convention: cooperate.

Outline of the model

- ▶ Repeated games of individual interaction, with limited information. (*)
- ▶ Despite restrictions, potential convergence to global, rational state as if players had complete information.

n-k-g stochastic social game

- ▶ n agents, k -person game g , unbounded sequence of tuples of k selected players (out of the n agents).

Selection function

- ▶ Which information can agents rely on? Two principles:
 - ▶ Obliviousness: identity of agents or names of agents are inaccessible.
 - ▶ Locality: selection function based on personal history.
- ▶ **Local selection function**: based on the history of actions and payoffs of the agent alone.
- ▶ **Semi-local selection function**: based on the history of actions and payoffs of the agent and the agents he encountered.

Intuitions behind the formal properties

- ▶ Coordination problem could be trivially solved, ahead of time, by reference to "left" or "right", if we would not demand *obliviousness*.
- ▶ Better example: specifying assembly robot behavior in general terms, without reference what they should use, but only how they should react given their (payoff) observations.

Highest cumulative reward rule

- ▶ An agent switches to a new action iff the total payoff from that action in the last m iterations was greater than the total payoff of the current action in the same time period.
- ▶ NB: cannot be pure *locality*, otherwise agents would never switch (since there is no random mutation or error).
According to their own definition, it should be considered *semi-local*, I believe, or, equivalently, with some knowledge of the game (i.e. payoff for actions not taken).

Social agreement games

(The class of games to which their results apply)

$$\begin{pmatrix} x, x & u, v \\ v, u & y, y \end{pmatrix}$$

with $x, y, u, v \neq 0$; $x > 0$ or $y > 0$; $u < 0$ or $v < 0$; if both $x > 0$ and $y > 0$, then $x = y$.

Convergence result

- ▶ Probability of social convention being reached approaches 1.
- ▶ This social convention is stable.
- ▶ Every agent receives at least initial maximin value (i.e. maximin in the unrestricted game)
- ▶ If a *rational* social convention exists wrt. the maximin value, it will be reached.

What it means

- ▶ Local rule brings about emergence of globally reasonable stable convention. (*)
- ▶ Emergence of *cooperation* and *coordination* by local update rule.

Efficiency, analytic

- ▶ Section is a complete mess, but probably: lower bound (= minimal number of iterations) in the order of $n * \log(n)$ (where n is the total number of agents).
- ▶ Upper bound is not stated explicitly at all (as far as I can see), but probably in the order of x^n .

Efficiency, empirical

- ▶ Despite identical framework, coordination is much faster than cooperation. In fact, cooperation seems to be untenable.
- ▶ Coordination game convergence approaches lower bound.
- ▶ Assumptions for the following results (unless noted otherwise): unlimited memory, 100 agents

Update delay

95% goal. 1600 iterations. Out of 4000 trials.
Result: high update frequency is good.

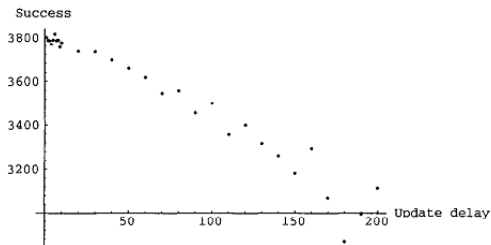


Fig. 1. The effects of update frequency.

Memory restart

85% goal. 800 iterations. Out of 4000 trials.

Result: At least for now, full memory is good.

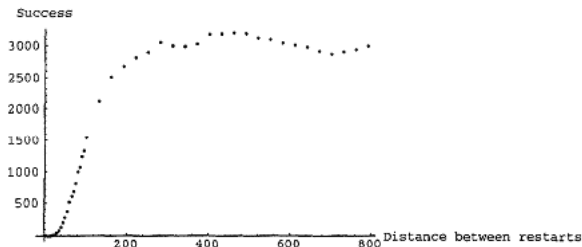


Fig. 2. The effects of memory restarts.

Combined delay and restart

95% goal. 1600 iterations. Out of 4000 trials.

Result: linked restart and update are better than full memory and update delays.

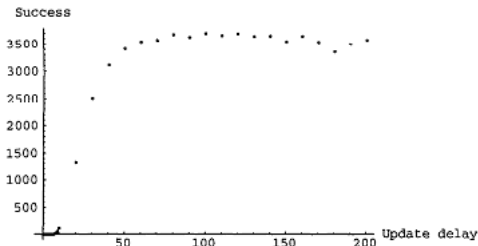


Fig. 3. The case in which update frequency = memory restart frequency.

Limited memory window, observations

85% goal. 800 iterations. Out of 4000 trials.

Result: (Somewhat) limited (continuous) memory is beneficial.

NB: Difference to Fig. 1 probably due to number of iterations.

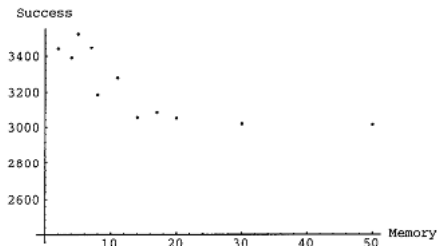


Fig. 4. Limited memory (latest observations).

Limited memory window, iterations

85% goal. 800 iterations. Out of 4000 trials.

Result: Same as for Fig. 4.

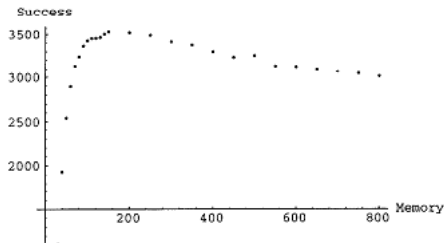


Fig. 5. Limited memory (latest iterations).

Convergence behavior

Full memory.

Result: Slow in the beginning and the end.

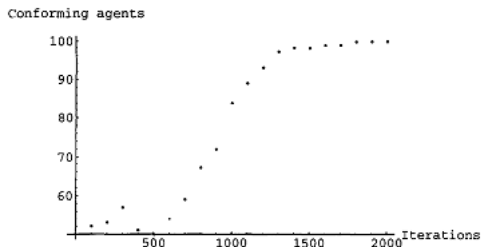


Fig. 6. The shape of convention evolution.

Extended coordination game

Definition: payoff for both agents is $x > 0$ iff the coordinate, $-x$ otherwise.

Result: Number of potential conventions (i.e. more possible actions for players) decreases efficiency, but relatively slowly.

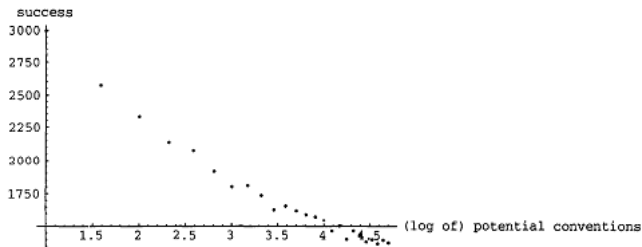


Fig. 7. The effects of the number of potential conventions.

Results, according to the authors

- ▶ Interesting because local update rules plus global interaction yields global advantages through stable conventions.
- ▶ "Some of our results refer to the emergence of social conventions that are not Nash equilibria". That's great, why didn't you show us those (practical) results?

Comparison to previous frameworks

- ▶ Young, "Evolution of Conventions"
 - ▶ Similarities: stochastic process (repeated games); classic game theoretical setting
 - ▶ Differences: Nash equilibria; best response (global knowledge, but error and limited memory)
- ▶ Axelrod "Evolutionary Approach to Norms":
 - ▶ Similarities: stochastic process; evolutionary setting
 - ▶ Differences: no analytic results (stable states are neither named nor proven), perhaps because they are more complex

Suggestions for discussion

- ▶ "Rational agents are maximizers of individual utility" (Always true?)
- ▶ "Repeated games of individual interaction, with limited information" (How little do they know; the game, other players' decisions, etc?)
- ▶ "Local rule brings about emergence of globally reasonable stable convention." (But only wrt. maximin value.)
- ▶ What is the idea behind the class of *social agreement games*?
- ▶ No mutation or error assumed in this approach.