# On the Complexity of Finding a Potential Community

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Abstract. An independent 2-clique of a graph is a subset of vertices that is an independent set and such that any two vertices inside have a common neighbor outside. In this paper, we study the complexity of finding an independent 2-clique of maximum size in several graph classes and we compare its complexity with the complexity of maximum independent set. We prove that this problem is NP-hard on apex graphs, APX-hard on line graphs, not  $n^{1/2-\epsilon}$ -approximable on bipartite graphs and not  $n^{1-\epsilon}$ -approximable on split graphs, while it is polynomial-time solvable on graphs of bounded degree and their complements, graphs of bounded treewidth, planar graphs,  $(C_3, C_6)$ -free graphs, threshold graphs, interval graphs and cographs.

Keywords: Combinatorial optimization  $\cdot$  Complexity  $\cdot$  Algorithm  $\cdot$  Independent set  $\cdot$  Inapproximability

### 1 Introduction

Community detection is a well established research field in the area of social networks. It can find many applications in this area with the recent development of social networks like Facebook or Linkedin. A social network can be easily modeled by a graph in which vertices represent members and edges represent relationships between those members.

There are several ways to define a community. Intuitively, a community corresponds to a dense subgraph, that is to say a subgraph with a lot of edges. If a community is defined as a group of maximum size such that all members know each other, it corresponds to the well known NP-hard problem of finding a maximum clique. However, such a condition is strong and is not always relevant to describe a community.

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Another way to define a community is to relax the strong condition of a clique and focus on the distance between members of a social network. Different measures have been studied to describe it. Luce introduced in [12] the notion of k-cliques while Mokken extended this notion in [13] by defining k-clubs. A k-clique (resp. a k-club) of G is a subgraph S in which any two vertices are at distance at most k in G (resp. in the subgraph induced by S). The standard term 'clique' means both a 1-clique and a 1-club.

With the recent development of social networks and particularly online dating services, it could be interesting to investigate the detection of some group of people who do not know each other, but are related by their other relationships. Such a group could be considered as a 'potential' community since it does not form a community in the first place, but could become one thanks to their proximity. This may find various applications in online dating and meet-up services in which members expect not to know the other members.

More precisely, considering a graph G, we want to define potential communities by looking at independent sets in which any two members are related within a specified distance in G. Contrary to a k-club, the distance between two vertices must be realized via vertices outside of the subgraph. We call such a subset of vertices an independent k-clique, where k is the largest distance between vertices of S in the original graph. In this paper, we study the problem of finding an independent 2-clique of maximum size.

We investigate the complexity of finding an independent 2-clique of maximum size in several graph classes. Since this problem is close to finding an independent set of maximum size, we also compare the hardness of the two problems. Figure 1 summarizes the results we prove in the paper.

The paper is structured as follows. In Sect. 2 we introduce formally some notation and definitions. In Sect. 3 we show that the complexity of MAX INDE-PENDENT 2-CLIQUE jumps from polynomial-time solvable to NP-hard when the input class is extended from planar graphs to apex graphs. In Sect. 4 we present polynomial algorithms to solve MAX INDEPENDENT 2-CLIQUE in some graph classes. In Sect. 5 we show NP-hardness and non-approximability of MAX INDE-PENDENT 2-CLIQUE in some other graph classes. Conclusions are given in Sect. 6. Due to space limit, some proofs will be given in a journal version.

#### 2 Preliminaries

In this paper, all considered graphs are undirected. The *complement*  $\overline{G} = (V, \overline{E})$  of a graph G = (V, E) is the graph in which  $uv \in E$  if and only if  $uv \notin \overline{E}$ , for all vertex pairs  $u, v \in V$ . A *k*-cycle is a cycle of length *k*. The maximum degree of a vertex in a graph G will be denoted by the usual notation  $\Delta(G)$ .

We recall that a *clique* in a graph is a set of mutually adjacent vertices. A set of vertices is called a 2-*clique* if any two vertices of the set are at distance at most 2 in G. An *independent set* in a graph is a set of vertices such that no two of them are joint by an edge. An *independent 2-clique* is a subset of vertices which is an independent set and a 2-clique at the same time.

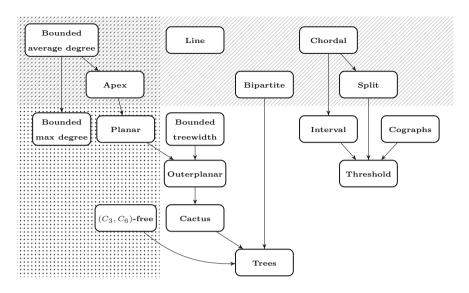


Fig. 1. Relationship among some classes of (connected) graphs, where each child is a subset of its parent. We compare the hardness of MAX INDEPENDENT 2-CLIQUE and MAX INDEPENDENT SET in studied graph classes. MAX INDEPENDENT 2-CLIQUE is NP-hard on graph classes at the top (hatched area) and is polynomial-time solvable on graph classes on the bottom (non-hatched area). MAX INDEPENDENT SET is NP-hard on graph classes on the left (dotted area) and is polynomial-time solvable on graph classes on the right (non-dotted area).

In this paper we are interested in the following optimization problem:

MAX INDEPENDENT 2-CLIQUE **Input**: A graph G = (V, E).

**Output**: A subset  $S \subset V$  which is an independent 2-clique of maximum size.

The MAX INDEPENDENT 2-CLIQUE problem is closely related to another well known one:

MAX INDEPENDENT SET **Input** : A graph G = (V, E). **Output** : A subset  $S \subset V$  such that S is an independent set of maximum size.

Given a graph G, the standard notation for the maximum size of an independent set in G is  $\alpha(G)$ . The maximum number of vertices in an independent 2-clique of G will be denoted by  $\alpha_{=2}(G)$ . The subscript '=2' intends to express that the distance between any two vertices of the independent set is exactly 2.

Note that  $\alpha_{=2}(G) \geq 2$  whenever at least one connected component of G is not a complete graph. (Indeed, any such component contains two vertices at distance exactly two, hence forming an independent 2-clique of size 2.) Moreover, if G is disconnected and has components  $G_1, \ldots, G_k$  then

$$\alpha_{=2}(G) = \max_{1 \le i \le k} \alpha_{=2}(G_i)$$

For these reasons we assume throughout that G is a non-complete, connected graph (although some of the algorithms also need to handle disconnected graphs temporarily).

Some Classes of Graphs. A *cactus* is a graph in which each edge occurs in at most one cycle. A  $(C_3, C_6)$ -free graph is a graph containing no triangle  $C_3$ and no induced cycle of length 6. An *interval graph* is a graph for which there exists a family of intervals on the real line and a bijection between the vertices of the graph and the intervals of the family in such a way that two vertices are joined by an edge if and only if the intersection of the two corresponding intervals is non-empty. A threshold graph is a graph which can be constructed from the empty graph by a sequence of two operations: insertion of an isolated vertex, and insertion of a dominating vertex (i.e., a vertex adjacent to all the other vertices). A *cograph* is a graph that can be generated from the singlevertex graph by (repeated applications of) complementation and vertex-disjoint union. A split graph is a graph whose vertex set can be partitioned into two subsets, one inducing an independent set S and the other one inducing a clique K. We denote by  $K_{p,m}$  the complete bipartite graph with p and m vertices in its vertex parts. The line graph of a graph G is the graph L(G) whose vertices represent the edges of G, and two vertices of L(G) are adjacent if and only if the corresponding two edges of G share a vertex. A graph is *outerplanar* if it has a crossing-free embedding in the plane such that all vertices are on the same face. A graph is k-outerplanar if for k = 1, G is outerplanar and for k > 1 the graph has a planar embedding such that if all vertices on the exterior face are deleted, the connected components of the remaining graph are all (k-1)-outerplanar. A graph G is apex if it contains a vertex v such that  $G \setminus v$  is planar. A family of graphs on n vertices is  $\delta$ -dense if it has at least  $\frac{\delta n^2}{2}$  edges. It is everywhere- $\delta$ dense if the minimum degree is at least  $\delta n$ . A family of graphs is dense (resp. everywhere-dense) if there is a constant  $\delta > 0$  such that all members of this family are  $\delta$ -dense (resp. everywhere- $\delta$ -dense).

## 3 Complexity Jump from Planar Graphs to Apex Graphs

According to [8], MAX INDEPENDENT SET is known to be NP-hard in planar graphs, and thus also in apex graphs. On the other hand, we prove that MAX INDEPENDENT 2-CLIQUE is polynomial-time solvable on planar graphs but NP-hard on apex graphs. This shows that inserting or removing a single vertex in a graph may dramatically change the complexity of MAX INDEPENDENT 2-CLIQUE.

**Theorem 1.** MAX INDEPENDENT 2-CLIQUE is NP-hard on apex graphs.

*Proof.* We establish a polynomial reduction from MAX INDEPENDENT SET on cubic planar graphs, which is proved NP-hard in [8], to MAX INDEPENDENT 2-CLIQUE on apex graphs. Let G = (V, E) be a cubic planar graph, an instance

of MAX INDEPENDENT SET. The instance G' = (V', E') of MAX INDEPENDENT 2-CLIQUE is defined by inserting an additional vertex z that is adjacent to every vertex of V. It is easy to see that  $\{z\}$  itself is a one-element non-extendable independent 2-clique, while the independent 2-cliques of G' not containing z are precisely the independent sets of G.  $\Box$ 

This first theorem implies another interesting result:

**Corollary 2.** MAX INDEPENDENT 2-CLIQUE is NP-hard on the class of graphs of average degree at most 5.

*Proof.* Cubic graphs on n vertices have 3n/2 edges, thus the graph constructed in the proof of Theorem 1 is of order n+1 and has 5n/2 edges, yielding average degree less than 5.

Now, in order to prove that MAX INDEPENDENT 2-CLIQUE is polynomialtime solvable on planar graphs, we use a famous theorem introduced by Courcelle in [6] which states that any problem expressible in Monadic Second-Order Logic is linear-time solvable for graphs of bounded treewidth. This allows to show first the following:

**Theorem 3.** MAX INDEPENDENT 2-CLIQUE is linear-time solvable on graphs with bounded treewidth.

*Proof.* We observe that the property 'Independent 2-Clique' is expressible in Monadic Second-Order Logic:

$$I2C(S) := \forall x \forall y (Sx \land Sy) \rightarrow (\neg edg(x, y) \land (\exists z, edg(x, z) \land edg(y, z)))$$

Since any problem expressible in Monadic Second-Order Logic is linear-time solvable for graphs of bounded treewidth (see [6]),  $\alpha_{=2}$  can be determined in linear time in graphs of bounded treewidth.

Based on this result, we prove the following result.

**Theorem 4.** MAX INDEPENDENT 2-CLIQUE is polynomial-time solvable on planar graphs.

Proof. Let G = (V, E) be a planar graph and  $v \in V$  any vertex. Then all the other vertices in an independent 2-clique S containing v are at distance exactly 2 apart from v. Further, the 2-clique property for  $S \setminus \{v\}$  is ensured by vertices within distance at most 3 from v. Thus, the vertices relevant for S to be an independent 2-clique induce a subgraph G' in G such that G' belongs to the class of '4-outerplanar' graphs. Graphs which are 4-outerplanar have treewidth at most 11 (more generally, all k-outerplanar graphs have treewidth at most 3k - 1, due to [3]). Then, using Theorem 3, a polynomial-time algorithm for MAX INDEPENDENT 2-CLIQUE in planar graphs consists in solving the problem for all subgraphs G' (which have treewidth at most 11) defined from each vertex v.

#### 4 Graph Classes with Polynomial-Time Algorithms

In the following we identify some graph classes on which MAX INDEPENDENT 2-CLIQUE is computable in polynomial time, while MAX INDEPENDENT SET is not always polynomial-time solvable.

First, it is interesting to notice that, according to the next propositions, MAX INDEPENDENT 2-CLIQUE is polynomial-time solvable on graphs of bounded degree and also on complements of graphs of bounded degree, while MAX INDE-PENDENT SET is NP-hard on graphs of bounded degree [8] but polynomial-time solvable on their complements (using exhaustive search in the non-neighborhood of each vertex, which can be done in linear time).

**Proposition 5.** MAX INDEPENDENT 2-CLIQUE is linear-time solvable on graphs with bounded maximum degree, and also on graphs of minimum degree at least (n-d), where d is constant.

Now, notice that a natural way to find an independent 2-clique is to take an independent set included in the neighborhood of one vertex. Then, it is interesting to investigate the properties of a graph in which an independent 2-clique is not included in the neighborhood of one vertex. We show in Lemma 6 that such a graph necessarily contains a cycle of length 3 or 6, and cannot be a cactus if such an independent 2-clique has a certain size. Such properties allow to get an easy polynomial-time algorithm for MAX INDEPENDENT 2-CLIQUE on  $(C_3, C_6)$ -free graphs, while MAX INDEPENDENT SET is NP-hard on this class of graphs (see [1]). From Theorem 4 we already know that MAX INDEPENDENT 2-CLIQUE is linear-time solvable on cactus graphs, but the property of Lemma 6 allows to give a simpler algorithm for this class of graph.

**Lemma 6.** Let G = (V, E) be a graph. Suppose that there exists an independent 2-clique S not contained in the neighborhood of a single vertex. Then G contains an induced cycle of length 3 or 6. Moreover, if  $|S| \ge 4$ , G is not a cactus.

This lemma implies the following theorem:

**Theorem 7.** Any  $(C_3, C_6)$ -free graph G satisfies  $\alpha_{=2}(G) = \Delta(G)$  and MAX INDEPENDENT 2-CLIQUE is linear-time solvable on it.

Recalling that a tree does not contain any cycle, for the classical class of trees we obtain the following:

**Corollary 8.** Any tree T satisfies  $\alpha_{=2}(T) = \Delta(T)$  and MAX INDEPENDENT 2-CLIQUE is linear-time solvable on it.

Finally, Lemma 6 allows to give a polynomial-time algorithm for MAX INDE-PENDENT 2-CLIQUE on cactus.

**Proposition 9.** MAX INDEPENDENT 2-CLIQUE is linear-time solvable on cactus graphs.

We focus in the following part of this section on classes of graphs on which both MAX INDEPENDENT 2-CLIQUE and MAX INDEPENDENT SET are polynomial-time solvable. We first investigate a subclass of split graphs, namely threshold graphs. It follows from the definitions that a threshold graph G = (V, E) is a split graph with the following property: the vertices of the independent set S can be ordered as  $v_1, \ldots, v_p$  such that  $N_G(v_1) \subseteq N_G(v_2) \subseteq \ldots \subseteq N_G(v_p)$ . We denote by  $u_1, \ldots, u_q$  the vertices of the clique K, and we suppose that  $d_G(u_1) \leq d_G(u_2) \leq \ldots \leq d_G(u_q)$ . Without loss of generality, we assume that there is no isolated vertex in G. Note that a threshold graph can be recognized in linear time (see [10]).

**Proposition 10.** MAX INDEPENDENT 2-CLIQUE is linear-time solvable on threshold graphs. Moreover, in every threshold graph G without isolated vertices we have  $\alpha_{=2}(G) = \alpha(G)$ .

Proof. Let G = (V, E) be a threshold graph with the previous decomposition into S and K. Let  $N_G(v_p) = \{u_r, u_{r+1}, \ldots, u_q\}$ , for some  $r \ge 1$ . Then a maximum independent 2-clique in G is S if  $K \setminus N_G(v_p) = \emptyset$ , and otherwise it is  $S \cup \{z\}$  with any  $z \in K \setminus N_G(v_p)$ , since in both cases the common neighbor of all these vertices is  $u_q$ . Since MAX INDEPENDENT SET can be solved in linear time in threshold graphs [7], MAX INDEPENDENT 2-CLIQUE can be solved in linear time.  $\Box$ 

The previous result can be extended in two directions, for interval graphs and for cographs.

Using the results of Booth and Lueker [4] it can be tested in linear time whether a graph G is an interval graph; and if it is, then an interval representation  $I_1, \ldots, I_n$  of G can also be generated.

**Proposition 11.** MAX INDEPENDENT 2-CLIQUE is polynomial-time solvable on interval graphs.

Proof. Consider any G = (V, E) and let  $I_1, \ldots, I_n$  be an interval representation of G. In order to determine  $\alpha_{=2}(G)$ , first notice that all vertices of an independent 2-clique S of G must have a common neighbor. Indeed, if I and I' are the leftmost and the rightmost intervals of S then any of their common neighbors intersects all intervals located between them, and therefore is a common neighbor of all members of S. Then, for every vertex I, we compute a maximum independent set in the subgraph induced by the neighborhood of I. An optimal solution is such an independent set with maximum size. Since MAX INDEPENDENT SET is polynomial-time solvable on interval graphs [9], the result follows.  $\Box$ 

We consider now the class of cographs, that contains all threshold graphs.

**Proposition 12.** MAX INDEPENDENT 2-CLIQUE is polynomial-time solvable on cographs.

Notice that since MAX INDEPENDENT SET is linear-time solvable on chordal graphs [7], it is also polynomial-time solvable on interval graphs and threshold graphs. Moreover, MAX INDEPENDENT SET is also polynomial-time solvable on cographs by bottom-up tree computation [5].

#### 5 NP-hardness and Non-approximability

Using the reduction from the proof of Theorem 1, we can conclude:

- MAX INDEPENDENT 2-CLIQUE is NP-hard on dense (resp. everywhere dense) graphs, since MAX INDEPENDENT SET is NP-hard on dense (resp. everywhere dense) graphs. Moreover, MAX INDEPENDENT 2-CLIQUE is not  $n^{1-\varepsilon}$ -approximable for any  $\varepsilon > 0$ , if  $P \neq NP$ , on everywhere dense graphs (and respectively dense graphs) since the same result holds for MAX INDEPENDENT SET on everywhere dense graphs (and respectively dense graphs). In order to get this last result, we use the same inaproximability result for MAX INDEPENDENT SET on general graphs [15] and a reduction preserving approximation from general graphs to everywhere dense graphs (that consists of adding a clique of the same size as the size of the graph and joining every vertex from the original graph to all vertices in this clique).
- MAX INDEPENDENT 2-CLIQUE is NP-hard on  $K_4$ -free graphs, since MAX INDEPENDENT SET is NP-hard on  $K_3$ -free graphs [1].

We now investigate graph classes in which MAX INDEPENDENT 2-CLIQUE is NP-hard while MAX INDEPENDENT SET is polynomial-time solvable. We first consider a graph class containing threshold graphs, namely the class of split graphs, for which MAX INDEPENDENT 2-CLIQUE becomes NP-hard (and even not  $n^{1-\varepsilon}$ -approximable). Since MAX INDEPENDENT SET is polynomial-time solvable on chordal graphs [7], it is also polynomial-time solvable on split graphs.

**Theorem 13.** On split graphs, MAX INDEPENDENT 2-CLIQUE is NP-hard and it is not  $n^{1-\varepsilon}$ -approximable in polynomial time unless P = NP.

We prove now that MAX INDEPENDENT 2-CLIQUE is NP-hard (and even not  $n^{1/2-\epsilon}$ -approximable) on bipartite graphs while MAX INDEPENDENT SET is polynomial-time solvable since the number of vertices in a maximum independent set equals the number of edges in a minimum edge covering.

**Theorem 14.** On bipartite graphs, MAX INDEPENDENT 2-CLIQUE is NP-hard and is not  $n^{1/2-\varepsilon}$ -approximable in polynomial time, unless P = NP.

**Proof.** First we prove the NP-hardness. MAX INDEPENDENT SET is known to be NP-hard on 3-regular graphs [8], so MAX CLIQUE is also NP-hard on (n-4)regular graphs (where n is the number of vertices), by considering its complement. We reduce MAX CLIQUE on (n-4)-regular graphs to MAX INDEPENDENT 2-CLIQUE on bipartite graphs. Let G = (V, E) be an (n-4)-regular graph. We construct an instance of G' = (V', E') of MAX INDEPENDENT 2-CLIQUE on bipartite graphs as follows (see Fig. 2).

Let  $V_1, V_2, V_3, V_4$  be four copies of V. Let  $E_1$  be a set of |E| vertices corresponding to the edges in E, and define  $V' := V_1 \cup V_2 \cup V_3 \cup V_4 \cup E_1$ . Let there exist an edge in E' between a vertex v in  $V_i, i \in \{1, 2, 3, 4\}$  and a vertex e in  $E_1$ 

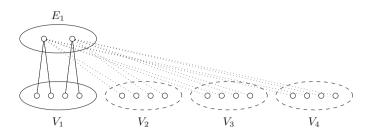


Fig. 2. The bipartite graph G', an instance of MAX INDEPENDENT 2-CLIQUE

if and only if the corresponding vertex v in V is incident with the corresponding edge e in E.

Now we show that G contains a clique of size at least k if and only if G' contains an independent 2-clique of size at least 4k.

Given a clique  $C \subseteq V$  of size at least k in G, the union of the four copies of C in G' is an independent 2-clique of size at least 4k.

For the other direction, notice first that the value of a maximum independent set in a 3-regular graph is at least  $\lceil \frac{n}{4} \rceil$ . Then, the value of a maximum clique in an (n-4)-regular graph is also at least  $\lceil \frac{n}{4} \rceil$ . Thus the size of a maximum independent 2-clique in G' is at least n.

We consider now a solution C' of MAX INDEPENDENT 2-CLIQUE in G' with at least  $4k \ge n$  vertices (this restriction is always possible because of the previous comment). Notice that C' cannot contain both a vertex from  $E_1$  and a vertex from  $V' \setminus E_1$  since the distance between any two vertices of C' must be 2. A solution which is a subset of  $E_1$  would mean pairwise intersecting edges in G, hence would have size at most max(3, n-4) < n. Therefore C' must be a subset of  $V' \setminus E_1$ . Notice that for any  $i \in \{1, 2, 3, 4\}, C' \cap V_i$  must be a copy of a clique in G. Then C' is a union of copies of four cliques in G, and  $|C'| \ge 4k$ . Let  $C_0$ be the copy of largest size, which thus has  $|C_0| \ge k$ . Then  $C_0$  is the copy of a clique C of G of size at least k.

For the proof of non-approximability, we construct an E-reduction (see [11]) from MAX CLIQUE. Let I = (V, E) be an instance of MAX CLIQUE. Consider a reduction similar to the one for the proof of NP-hardness, except that we now consider  $\ell = |V|$  copies  $V_1, \ldots, V_\ell$  instead of four copies of V; adjacencies are defined in the same way as before. We denote by I' = (V', E') the corresponding instance of MAX INDEPENDENT 2-CLIQUE from the reduction. As in previous proof, starting with a clique of size opt(I), we can construct an independent 2-clique of size  $\ell \cdot opt(I)$  in G' and thus  $opt(I') \ge \ell \cdot opt(I)$ . Let S' be any independent 2-clique in I' of size at least  $\ell$  (it always exists, take e.g. the  $\ell$  copies of the same vertex, one copy in each  $V_i$ ). As before, S' cannot contain both a vertex of  $E_1$  and a vertex from  $V \setminus E_1$  since two vertices of S' must have distance 2 in G', and S' cannot contain only vertices from  $E_1$  since any independent 2-clique included in  $E_1$  is of size at most max $(3, \Delta(G)) < \ell - 1$ . Moreover, each subset  $V_i \cap S'$  corresponds to a clique in G. Let S be the subset  $V_i \cap S'$  of largest size. We have  $|S| \ge \frac{|S'|}{\ell}$  and then  $opt(I) \ge |S| \ge \frac{|S'|}{\ell} = \frac{opt(I')}{\ell}$  when S' is an optimal solution. Using that  $opt(I') \ge \ell \cdot opt(I)$  we get  $opt(I') = \ell \cdot opt(I)$  and we obtain:

$$\epsilon(I,S) = \frac{opt(I)}{|S|} - 1 \le \frac{\ell \cdot opt(I')}{\ell \cdot |S'|} - 1 = \epsilon(I',S')$$

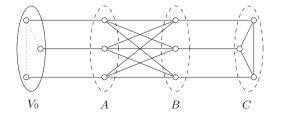
Since we clearly have  $opt(I') \leq p(|I|) \cdot opt(I)$  with a polynomial p, the reduction is an E-reduction. Then, since MAX CLIQUE is not  $\ell^{1-\varepsilon}$ -approximable unless P = NP [15], the same property holds for MAX INDEPENDENT 2-CLIQUE. Thus MAX INDEPENDENT 2-CLIQUE is not  $n^{1/2-\varepsilon}$  approximable where n = |V'| since  $n = \ell^2 + |E|$ .

Finally we prove that MAX INDEPENDENT 2-CLIQUE is NP-hard (and even APX-hard) on line graphs, while MAX INDEPENDENT SET is polynomial-time solvable since it consists in a maximum matching in the original graph.

**Theorem 15.** On line graphs, MAX INDEPENDENT 2-CLIQUE is NP-hard and even APX-hard.

Proof. First we prove the NP-hardness. We establish a reduction from the MAX CLIQUE problem on graphs of minimum degree at least n - 4. Consider an instance G = (V, E) of MAX CLIQUE with |V| = n. We construct a graph G' = (V', E') (see Fig. 3) as follows. Let  $G_0 = (V_0, E_0)$  be a copy of G. Let V' be  $V_0 \cup A \cup B \cup C$  where A, B, C are three sets of n vertices. Then, let  $E' = E_0 \cup E_1 \cup E_2 \cup E_3 \cup E_4$  such that  $E_1$  is a perfect matching between  $V_0$  and  $A, E_2$  is the set of all possible edges (i.e., a complete bipartite graph) between the vertices of A and the vertices of  $B, E_3$  is a perfect matching between B and C, and  $E_4$  is the set of all possible edges between any two vertices of C (a complete subgraph). The line graph of G', denoted by L(G'), is an instance of MAX INDEPENDENT 2-CLIQUE. Notice that an independent 2-clique in L(G') corresponds to a set of edges in G' such that, for each pair of edges  $\{e_1, e_2\}$  in the set,  $e_1$  and  $e_2$  are not adjacent but are joined by an edge. We show that G contains a clique of size at least k if and only if L(G') contains an independent 2-clique of size at least k + n.

Consider a clique S of size k in G, and let  $S_0$  be its copy in G'. We define a set of edges S' of size at least k + n in G' as follows. For any vertex  $v \in S_0$ ,



**Fig. 3.** The graph G' for which the corresponding line graph L(G') is an instance of MAX INDEPENDENT 2-CLIQUE

add in S' its adjacent edge in  $E_1$ . Moreover add the entire  $E_3$  to S'. We show now that any pair of edges in S' have an adjacent edge in common. Two edges of  $S' \cap E_1$  have a common adjacent edge in  $E_0$  since the subgraph induced by  $S_0$  is a clique. Similarly, two edges of  $E_3$  have a common adjacent edge in  $E_4$ . Moreover, an edge of  $S' \cap E_1$  and an edge of  $E_3$  have a common adjacent edge in  $E_2$  since the subgraph induced by  $A \cup B$  is  $K_{n,n}$ . Then, the corresponding set of vertices in L(G') is an independent 2-clique of size k + n.

In the other direction, consider an independent 2-clique in L(G') of size k+n. Notice that it is always possible to take the set of vertices in L(G') corresponding to  $E_3$  in G' and two edges in  $E_1$  whose vertices in  $V_0$  are neighbors in G', hence we can suppose that  $k \geq 2$ . Let S' be the set of all corresponding edges in G'. Suppose first that there is exactly one edge from  $E_0$  in S'. Then, there are at most n-2 edges from  $E_1$  in S', and there are at most 2 edges from  $E_2$  in S', due to the constraints of an independent 2-clique. There cannot be edges from  $E_3 \cup E_4$  in S' since they would not be joined to the edge of  $E_0 \cap S'$  by any edge. Then, S' contains at most n + 1 edges in S', which contradicts  $k \ge 2$ . Suppose now that there are at least two edges from  $E_0$  in S'. Name two of them  $e_{0,1}$ and  $e_{0,2}$ . Then, there are at most n-4 edges from  $E_1$  in S' but there is no edge from  $E_2$  in S'. Indeed, an edge  $e_2$  from  $E_2$  in S' can be joined by an edge to at most one of  $e_{0,1}$  and  $e_{0,2}$ . Then the size of S' does not exceed n, which contradicts  $k \geq 2$ . Thus, we can assume that there is no edge from  $E_0$  in S'. Similarly, there is no edge from  $E_4$  in S'. Now, notice that  $|S' \cap (E_2 \cup E_3)| \leq n$ since if  $S' \cap (E_2 \cup E_3)$  contained n+1 edges then at least two of these edges would have a common endpoint. Consequently,  $|S' \cap E_1| \geq k$ . Moreover, any two edges from  $S' \cap E_1$  must have a common adjacent edge in  $E_0$  since they cannot have a common adjacent edge in  $E_2$ . Then, the subgraph of G induced by the set of vertices in  $V_0$  which are the endpoints of the edges in  $S' \cap E_1$  must be a clique whose size is at least k.

For the proof of APX-hardness, we prove that the reduction above is an L-reduction (see [14]). We proved in the NP-hardness part that any independent 2-clique in I' has a size at most 2n. Then  $opt(I') \leq 2n = 8 \cdot \frac{n}{4} \leq 8 \cdot opt(I)$  follows since  $opt(I) \geq \frac{n}{4}$  in graphs of degree at least n - 4. Moreover, starting with a clique of size opt(I), we can construct an independent 2-clique of size opt(I) + n and therefore  $opt(I') \geq +n + opt(I)$ . Let S' be an independent 2-clique in I' of size at least n + 2 (we proved in the NP-hardness part that it always exists and that such a set must be included in  $E_1 \cup E_2 \cup E_3$ ). Let S be the set of vertices in  $V_0$  which are incident with edges in  $E_1 \cap S'$ . We have  $|S'| - |S| \leq n$  which implies  $n + |S| \geq |S'|$ . Then we obtain  $opt(I) - |S| \leq opt(I') - n - |S| = opt(I') - (n+|S|) \leq opt(I') - |S'|$ . Since MAX INDEPENDENT SET is APX-hard on the class of graphs of maximum degree 3 [2], MAX CLIQUE is also APX-hard on the class of graphs of minimum degrees n = -4. Thus, MAX INDEPENDENT 2-CLIQUE is APX-hard on line graphs.

## 6 Conclusion

Even if MAX INDEPENDENT 2-CLIQUE and MAX INDEPENDENT SET are similar problems, their complexity can be very different depending on the graph class we try to solve the problem in. We showed that MAX INDEPENDENT 2-CLIQUE is NP-hard on apex, dense and everywhere dense,  $K_4$ -free, split, bipartite and line graphs while it is polynomial-time solvable on bounded treewidth, planar, bounded degree (and complement of bounded degree),  $(C_3, C_6)$ -free, interval graphs and on cographs. Many further types of graphs may be of interest, concerning separation of graph classes in which the problem is NP-hard from the ones where the problem is solvable in polynomial-time.

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