Long-term office space reallocation: A case study

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Dauphine | PSL LAMSADE

A joint effort









The LAMSADE team

- Stéphane Airiau, Lucie Galand, Jérôme Lang, Sonia Toubaline (+ CR).
- Expertise: computational social choice, multicriteria decision aiding, optimization.

+ Our clients: V. Renaudin, P.-F. Guimont, Dauphine.









Reallocation plan

- Nouveau Campus

The Nouveau Campus project



- New wing in construction \Rightarrow 2024.
- Others renovated in order: B, P, C+D, A.
- Expected year of completion: 2027.

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- Take available space \Rightarrow Dispersion.
- Maximize global satisfaction of entities (departements, research centers, etc).

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Real-world challenges

- This is all happening once!
- Deadlines set by the university and the construction company.
- \Rightarrow We need something that works.

Problem data (1/2)

- \mathcal{P} : phases from 0 (initial) to 5 (final).
- E: 22 entities (departments, research centers, services).
- \mathcal{B} : \approx 1000 offices, with capacities { κ_b } (either 2 or 3).
- \mathcal{I} : ≈ 1000 "individuals", with weights $\{\rho_i\}_{i \in \mathcal{I}}$ in $\{1, 2, 3\}$ and entities $\{e_i\} \in \mathcal{E}^{|\mathcal{I}|}$.

An Excel spreadsheet⇒Lots of data cleaning!

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Renovation phases

- 5 (remaining) phases of planned durations τ_p .
- For every phase p, \mathcal{B}_p : offices in renovation at phase p.
- \mathcal{I}^c : individuals that can share their office during renovation.

Problem data (2/2)

Dauphine's graph

- Built by hand (!)
- $|\mathcal{B}|$ vertices.
- Three edge types:
 - Next door offices (distance 1).
 - Change wing (distance 5).
 - Change floor (distance 10).

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Resulting graph

- Connected, easy to build once.
- Distances vary between 1 and $98 \Rightarrow \text{Problematic}!$

Reallocation plan



Mathematical model

- Variables and constraints
- Criteria and aggregation



Main boolean variables

- x_{bep} : Office b allocated to entity e at phase p.
- r_{bep} : Office b remains in e at phases p-1 and p.

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Distance-related variables

- *v*_{bep}: Number of neighbors of *b* at phase *p* that belong to a different entity (out-of-entity).
- t_{bdep} : Number of offices in entity e_b that are at distance d of b at phase p.

$$\sum_{e \in \mathcal{E}} x_{bep} \leq 1 \qquad \forall b \in \mathcal{B}, \forall p \in \mathcal{P}.$$

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• All individuals from an entity should have an office at every phase:

$$\sum_{b\in\mathcal{B}}\kappa_b\,d_{bep}\geq\sum_{i:e_i=e}\rho_i\qquad\forall p\in\mathcal{P},\forall e\in\mathcal{E}.$$

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- Initial allocation set: $x_{be0} = x_{be}^0$.
- Final allocation set: $x_{be5} = x_{be}^5$.

Constraints ('ed)

Topological constraints

- Restriction of locations: Ex) PhD student offices
- Forbidden configurations:

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Many special cases

- Part of an entity moves out for one or more phase(s).
- Entities may change over the renovation period (Individual will).

For every entity e,

Number of moves (to be minimized)

$$\mathcal{M}(e) = \sum_{p \in \mathcal{P}} n_{ep}, \quad n_{ep} = \max\left\{\sum_{b \in \mathcal{B}} (x_{be(p-1)} - r_{bep}), \sum_{b \in \mathcal{B}} (x_{bep} - r_{bep})\right\}$$

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Oppression ratio (to be maximized)

$$C(e) = \sum_{p \in \mathcal{P}} \tau_p \, \frac{\sum_{b \in \mathcal{B}} x_{bep}}{\sum_{b \in \mathcal{B}} x_{be}^0}$$

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Compression ratio (to be maximized)

$$C(e) = \sum_{p \in \mathcal{P}} \tau_p \, \frac{\sum_{b \in \mathcal{B}} x_{bep}}{\sum_{b \in \mathcal{B}} x_{be}^0}$$

Solution Dispersion measure S(e) (to be minimized).

The dispersion objective

Several possible choices

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• Choose a coarser grid of distance values, e.g. 5:

$$\mathcal{S}(e) = \sum_{p \in \mathcal{P}} \sum_{b \in \mathcal{B}} \sum_{\ell=1}^{5} \ell \, g_{b\ell ep}.$$

where $g_{b\ell ep}$ corresponds to an interval of distances.

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where $g_{b\ell ep}$ corresponds to an interval of distances.

• Use the number of out-of-entity neighbors:

$$S(e) = \sum_{p \in \mathcal{P}} \sum_{b \in \mathcal{B}} v_{bep}.$$

Criteria normalization and aggregation

Normalization

- Map criteria into [0,1].
- For entity e,

$$M(e) \leftarrow rac{M(e)}{|\mathcal{P}|\sum_{b \in \mathcal{B}} x_{be}^5}, C(e) \leftarrow 1 - rac{C(e)}{\sum_{p \in \mathcal{P}} \tau_p}$$

• Normalization for *S*(*e*) depends on maximum distance considered and/or maximum number of neighbors.

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Aggregation

$$\sum_{e\in\mathcal{E}}w_M M(e) + w_C C(e) + w_S S(e).$$

- Simple choice $w_M = w_C = w_S = 1$ (to be adjusted).
- We are thinking of something less utilitarian!

Setup

- Problem solved using Gurobi.
- Run on LAMSADE server.
- Orders: 10⁶ variables/constraints.

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Tuning the function dispersion

- No dispersion metric >> Very different solution from the current one.
- Use full distances > Struggle to find a feasible point.
- Surrogates
 - Use a smaller number of distance values \Rightarrow 2 days to find a feasible point!
 - Use the number of out-of-entity neighbors $\Rightarrow 2$ days to go beyond 10% optimality gap.

- We optimize over all phases.
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Our last results

- We optimize over all phases.
- The Nouveau Campus team computes the next phase by hand.

Next phase comparison

- Hand-coded solution is better on all three criteria!
- Number of moves similar (206 vs 216).
- Many exchanges to refine ours without significant change in next phase.

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What now?

- Their solution has been adopted (time constraints).
- But the following phases will be obtained through our model.



G Current and future work

Weighting our objectives

Current objective

$$\sum_{e\in\mathcal{E}}f(e)=M(e)+C(e)+S(e)$$

- Sums the three terms equally.
- Our goal: Add (fixed) weights for every entity

$$\sum_{e \in \mathcal{E}} w^e_M M(e) + w^e_C C(e) + w^e_S S(e), \quad w^e_M + w^e_C + w^e_S = 1$$

About the entities

- Different priorities!
- Compression/Dispersion do not have the same importance.
- \Rightarrow Entities will select their own weights.

Ongoing approach

- Based on ordered weighted averaging (Yager, '88)
- MILP model (Ogryczak & Olender, '12).

Current objective

$$\sum_{e\in\mathcal{E}}\omega(e,f)f(e)$$

- ω(e, f): Ordered weights from saddest to happiest entity (linearization)
- Our first test: $(5, 2, 1, \ldots, 1)$.
- Several others in the pipeline!

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ROADEF-adjacent

- Continuous relaxation (given as a course project in M1 at Dauphine).
- Could use modern solvers for generalized linear programming (Summer internship).

What we have

- An MILP model that can be solved in reasonable time.
- A certificate that the next moving plan compares to the optimum.
- A flexible framework through OWA.

Moving forward

- Including entity preference data (poll).
- Explore alternate solving techniques (decomposition, continuous relaxations).
- We have limited time but appreciate all suggestions!

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Thank you for your attention! clement.royer@lamsade.dauphine.fr