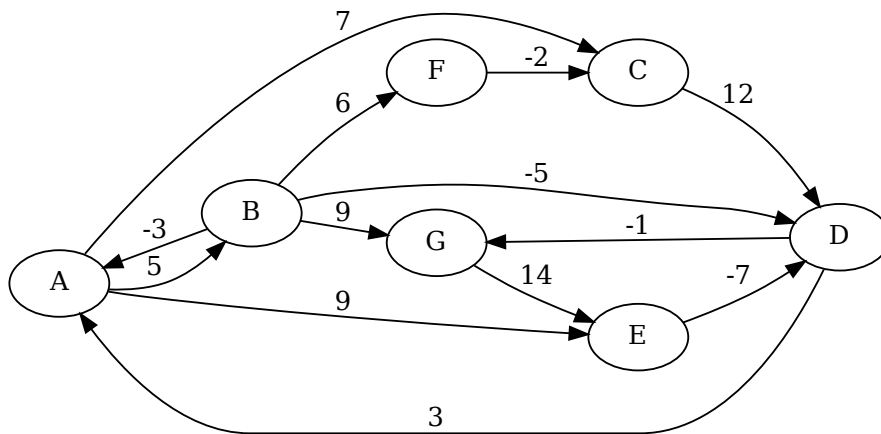


TD 6: APSP

1 Execute Johnson's algorithm

Execute Johnson's algorithm on the graph below.



2 Shortest Cycles

We are given as input a directed graph $G = (V, A)$ with positive weights on the arcs in adjacency list form (that is, you can assume that for each vertex you have a list of outgoing arcs and their corresponding weights).

- Give an efficient algorithm that takes as input an arc $ij \in A$ and outputs the shortest cycle that contains ij (or correctly reports that none exists).
- Give an efficient algorithm that outputs the shortest cycle in G .

How does your answer change if the graph may have negative weights? (you are promised that no negative cycles exist)

3 Many distances

We are given as input a directed graph $G = (V, A)$ with positive arc weights in adjacency list form. Furthermore, we are given a set of k special vertices $S \subseteq V$. We define the S -distance of a vertex $x \in V$ as $\text{dist}_S(x) = \min_{s \in S} \text{dist}(x, s)$. Give an efficient algorithm that computes the S -distances of all vertices.

To motivate the problem, consider the following scenario: G represents the road network between different cities, arc weights represent distances, and S represents a set of cities that contain an important facility (e.g. a large hospital). For other cities, we want to calculate what is the minimum distance we need to traverse to reach *some* important facility.

4 (Min,+)-Product

4.1 The basics

Suppose we are given two matrices A, B with dimensions $n_1 \times n_2$ and $n_2 \times n_3$ respectively. Then, the $(\min, +)$ -product of A, B , denoted $A \otimes B$ is defined as the $n_1 \times n_3$ matrix C satisfying the following:

$$C[i, j] = \min_{k \in \{1, \dots, n_2\}} \{A[i, k] + B[k, j]\}, \quad \forall i \in \{1, \dots, n_1\}, j \in \{1, \dots, n_3\}$$

Recall the following facts, discussed in class:

- Given two $n \times n$ matrices A, B , $A \otimes B$ can be computed in $O(n^3)$ time (assuming arithmetic operations take time $O(1)$).
- Assume we have an algorithm that can calculate $A \otimes A$, where A is an $n \times n$ matrix, in time $O(T)$. Then, we can solve APSP on weighted directed graphs without negative cycles in time $O(T \log n)$.

4.2 (min,+) and APSP equivalence

As discussed in class, the question of whether APSP can be solved in time $O(n^{3-\epsilon})$ is one of the most important open problems in theoretical computer science. The above indicate that one approach to obtain such an algorithm would be to design a faster algorithm for $(\min, +)$ -product. This approach, however, presents some serious challenges (discussed again below). One could, then, hope, that perhaps we can obtain a faster APSP algorithm through some other means.

- Prove that it is in fact impossible to obtain a sub-cubic APSP algorithm without improving upon the best algorithm for $(\min, +)$ -product. More precisely, show that if there is an algorithm solving APSP in time $O(n^{3-\epsilon})$, then such an algorithm also exists for computing the $(\min, +)$ -product of two $n \times n$ matrices. (Hint: given two matrices, construct a graph such that the result is hidden in the APSP matrix of the graph).

4.3 (min,+) squares

So far we have tried (and failed) to improve upon the fastest APSP algorithm by using $(\min, +)$ -matrix multiplication. One could, however, object that there is an angle we have neglected: in order to speed up the best APSP algorithm it is not necessary to speed up $(\min, +)$ -multiplication in general; rather, it is sufficient to have a faster algorithm for computing **squares**. In other words, we can focus on the special case of the problem where $A = B$.

- Show that this idea does not help. That is, there is an algorithm which can compute $A \otimes B$, for two $n \times n$ matrices, in time $O(T)$, if and only if there is such an algorithm for the case $A = B$.

4.4 (min,+) to normal products

Recall that, as we discussed in class, the usual matrix multiplication operations (where $\min$ is replaced by $+$ and $+$ is replaced by $\times$) does have sub-cubic algorithms (notably, Strassen's algorithm). Unfortunately, it does not seem possible to use such algorithms to compute the $(\min, +)$ -product faster than time $O(n^3)$, because such algorithms rely on the ability to perform subtractions. In the $(\min, +)$ case we would therefore need a function that is the inverse of $\min$. Let us explore an idea that may allow us to do this.

We are given two $n \times n$ matrices A, B , and let W be the largest absolute value of any entry in A, B . Consider the following algorithm to compute $A \otimes B$:

1. Compute that matrix A' with $A'[i, j] = (n+1)^{W-A[i, j]}$. Similarly, compute B' .
2. Compute $C' = A' \cdot B'$ (using the normal matrix product).

3. For each $i, j \in \{1, \dots, n\}$ compute $C[i, j]$ as follows: let x be the maximum integer such that $(n+1)^x \leq C'[i, j]$; then set $C[i, j] := 2W - x$.
- Prove that the algorithm above correctly calculates $A \otimes B$.
 - Explain why the algorithm above still does not lead to a faster APSP algorithm (even though step 2 can be performed using Strassen's algorithm).