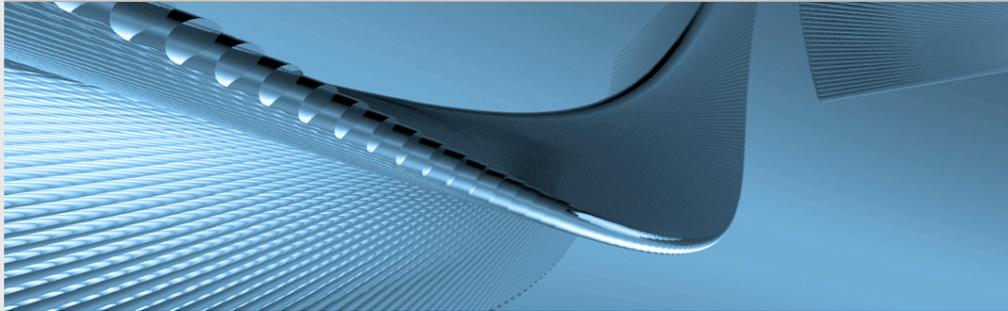


# Multi-objective Optimization Inspired by Nature

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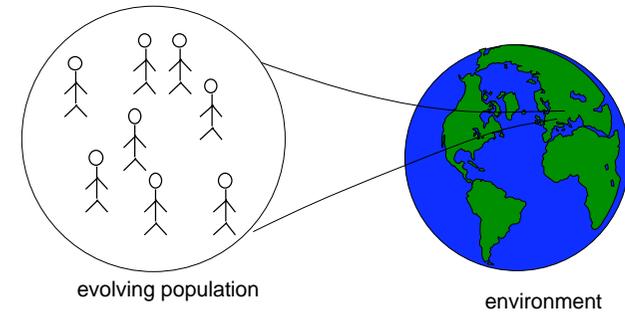


## Evolutionary algorithms

Darwin's principle of natural evolution:

**survival of the fittest**

in populations of individuals (plants, animals), the better the individual is adapted to the environment, the higher its chance for survival and reproduction.



## Menu

### Appetizer

Evolutionary algorithms

### Main course

Using evolutionary algorithms instead of exact optimizers for MOPs

Multi-objective evolutionary algorithms

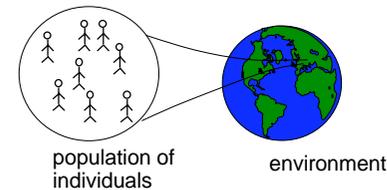
Including preference information in MOEAs

### Desert

Current research

Summary

## Transfer to optimization



### Natural evolution

- individual
- environment
- fitness/how well adapted
- survival of the fittest
- mutation
- crossover

### Evolutionary algorithms

- potential solution
- problem
- cost/quality of solution
- good solutions are kept
- small, random perturbations
- recombination of partial solutions

## Basic algorithm

### INITIALIZE population

(set of solutions)

### EVALUATE Individuals

according to goal ("fitness")

### REPEAT

**SELECT** parents

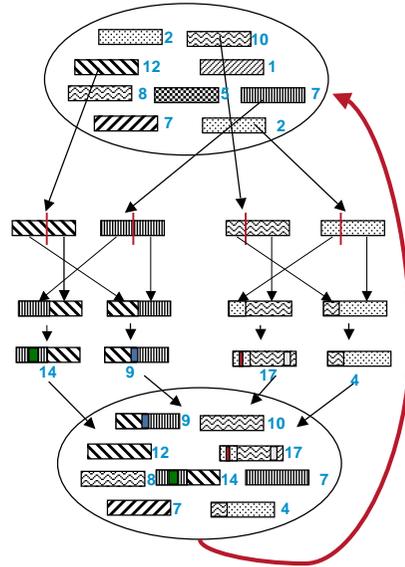
**RECOMBINE** parents (**CROSSOVER**)

**MUTATE** offspring

**EVALUATE** offspring

**FORM** next population

**UNTIL** termination-condition



## Industrial applications

- Warehouse location problem (Locom)
- Process scheduling (Unilever)
- Job shop scheduling (Deer & Company, SAP, Volvo)
- Turbine design (Rolce Royce, Honda)
- Portfolio optimization (First Quadrant)
- Cleaning team assignment (Die Bahn)
- Chip design (Texas Instruments)
- Roboter movement (Honda)
- Nuclear fuel reloading (Siemens)
- Design of telephone networks (US West)
- Games (creatures)
- Military pilot training (British Air Force)
- Vehicle routing (Pina Petroli)
- Coating of fluorescent lamps (Philips)
- ....

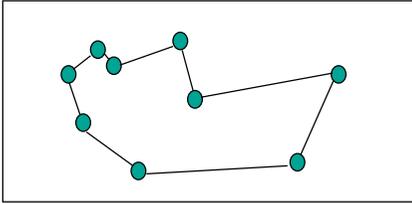
## Advantages/Disadvantages

- + No restriction w.r.t. fitness function (e.g. does not have to be differentiable)
- + Universal applicability
- + Easy to integrate heuristic knowledge if available
- + Easy to parallelize
- + Easy to use (usually inexpensive to develop)
- + Anytime algorithms (available time is fully utilized)
- + Can deal with multiple objectives
- + User-interaction possible
- + Allow for continuous adaptation
- + Can work with stochastic fitness functions
  
- Computationally expensive
- No guaranteed solution quality
- Parameter tuning necessary

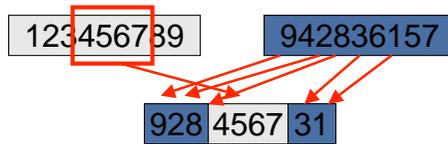
## Major design decisions

- Representation
- Genetic operators
  
- Selection mechanism
- Crossover/Mutation probability
- Population size
- Stopping criterion

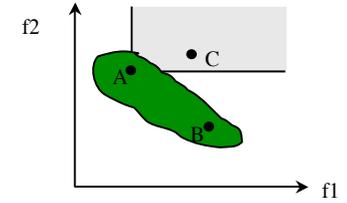
## Simple example: Travelling Salesman Problem



- Permutation encoding: 3-1-4-5-7-2-6-8-9
- Mutation: Exchange two cities
- Order crossover (OX)
  - select partial sequence from one parent, fill up in order of other parent



## Multiple objectives



- It is not always clear which solution is better
- Let  $f_i, i=1\dots d$  be the different optimization criteria. Then, a solution  $x$  is said to **dominate** a solution  $y$  ( $x \succ y$ ) if and only if the following condition is fulfilled:

$$x \succ y \Leftrightarrow f_i(x) \leq f_i(y) \quad \forall i \in \{1\dots d\} \\ \wedge \exists j : f_j(x) < f_j(y)$$

- Among a set of solutions  $P$ , the **non-dominated set** of solutions  $P'$  are those that are not dominated by any member of the set  $P$
- A solution which is not dominated by any other solution in the search space is called **Pareto-optimal**.
- User preferences are required

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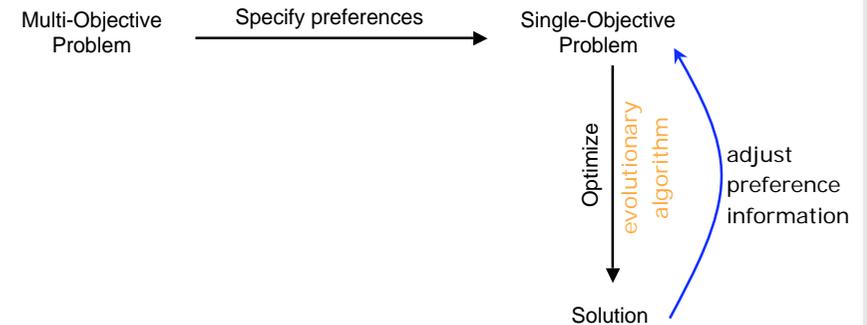
Including preference information in MOEAs

### Desert

Current research

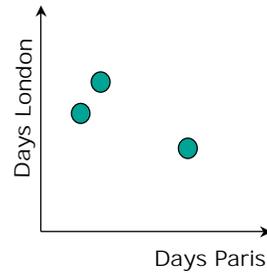
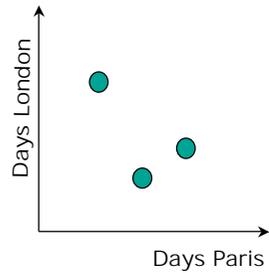
Summary

## A priori approach



## Specifying preferences

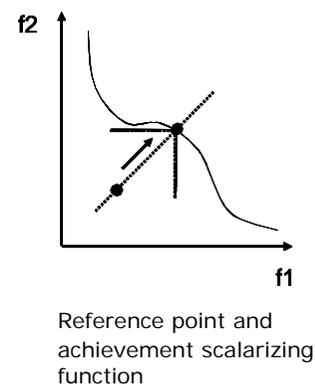
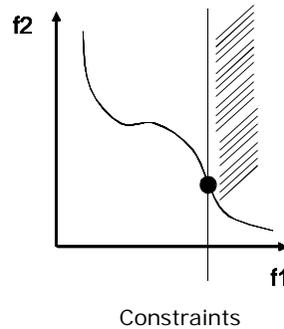
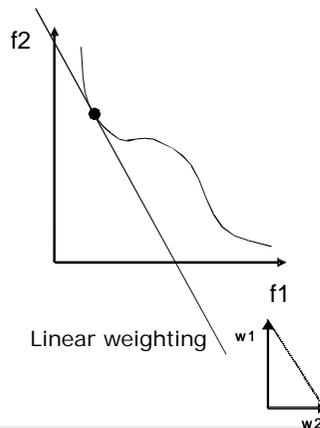
Difficult!  
Example: Tell me which travel plan you prefer!



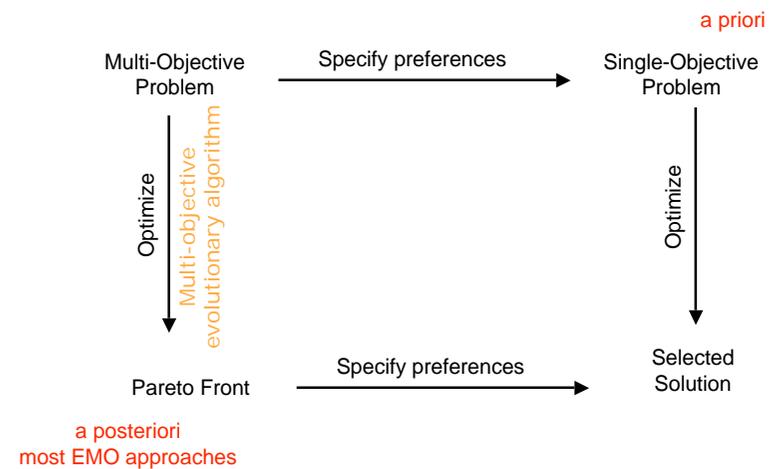
## Advantages / Disadvantages of EAs

- + Allows to solve problems where no exact methods exist
- Metaheuristics do not guarantee (Pareto-) optimality
- Solutions generated in subsequent iterations may dominate each other
- Adjusting preference information may lead to unexpected results
- Computationally expensive

## Specifying preferences



## A posteriori - The power of populations



# Multiobjective Evolutionary Algorithms (MOEAs)

- Since EAs work with a population of solutions, they can search for all (a representative subset of) Pareto-optimal solutions in one run
- Single EMO run is usually much more effective than multiple runs with different objectives

# Basic structure

**INITIALIZE** population  
(set of solutions)

**EVALUATE** Individuals  
according to goal ("fitness")

**REPEAT**

**SELECT** parents

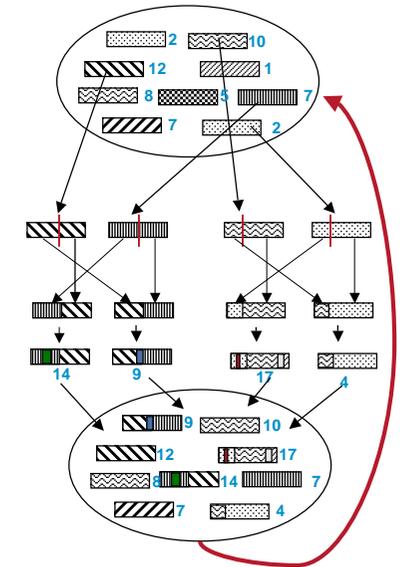
**RECOMBINE** parents (**CROSSOVER**)

**MUTATE** offspring

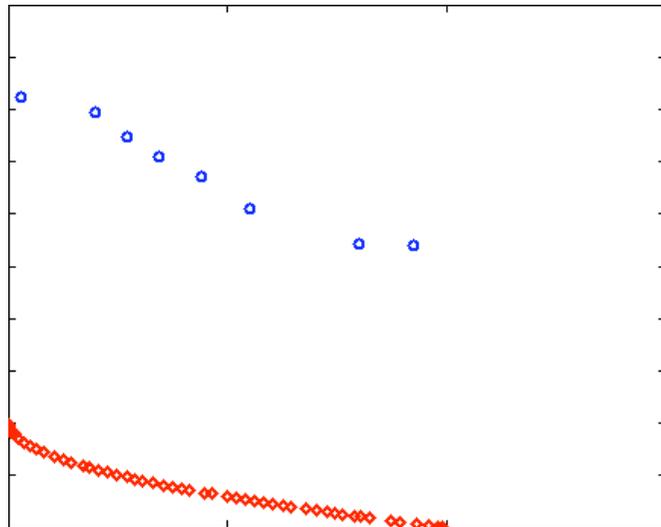
**EVALUATE** offspring

**FORM** next population

**UNTIL** termination-condition

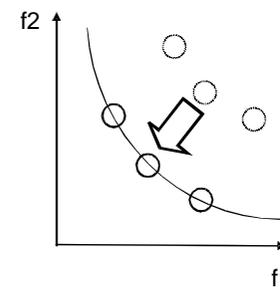


# Demo

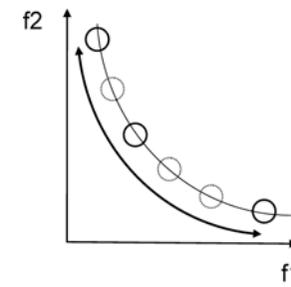


# What is a good approximation?

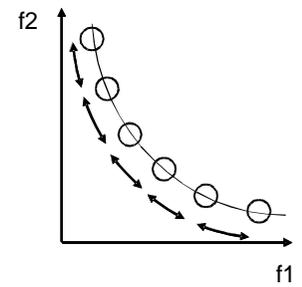
close to the Pareto front



wide spread



equally distributed

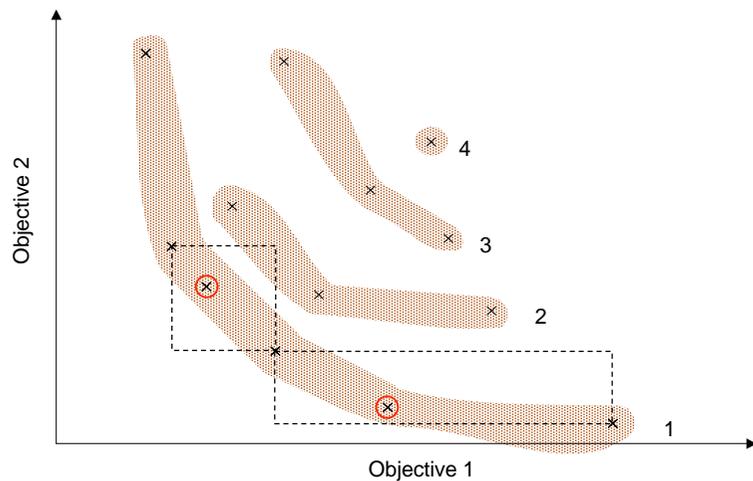
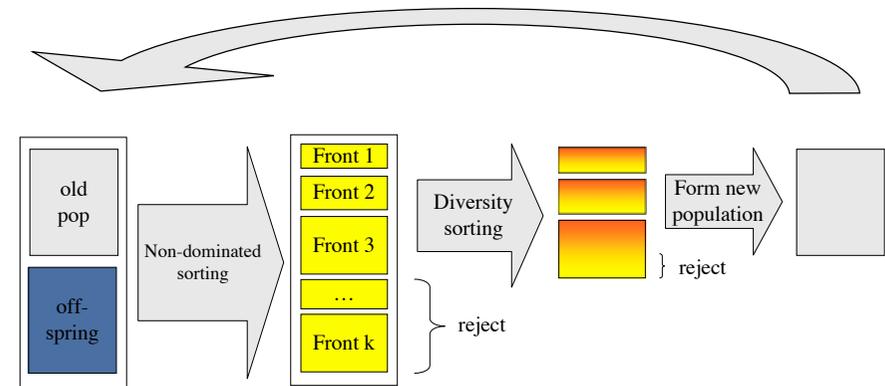


Based on two ideas:

1. **Pareto ranking:** based on Pareto-dominance
2. **Crowding distance:** mechanism to maintain diversity in the population

Other popular approach:

Strength Pareto Evolutionary Algorithm (SPEA) by Zitzler



- + Not necessary to specify preferences a priori
- + Allows DM to choose solution after having seen the alternatives
- + Interactive search of Pareto front
  - Optimization prior to interaction, thus interaction very fast
  - Only non-dominated solutions are presented to the user
  - Direct navigation by user is possible
  - Additional information on distribution of solutions along the front may be provided to the user (nadir point, ideal point, ...)

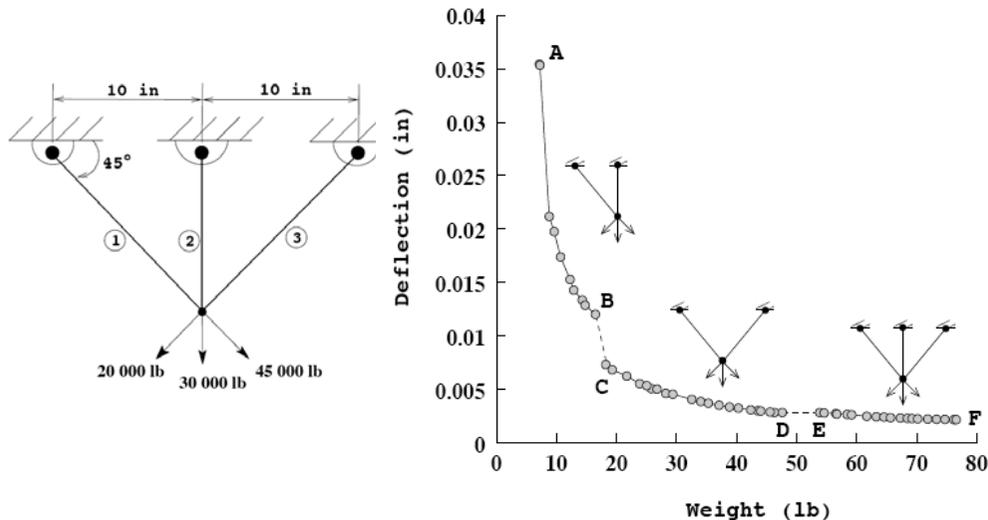
## Advantages of finding the complete front

- + Not necessary to specify preferences a priori
- + Allows DM to choose solution after having seen the alternatives
- + Interactive search of Pareto front
- + Offer different alternatives to different customers (e.g., mean-variance portfolio optimization)
- + Reveal common properties among Pareto-optimal solutions (some variables are always the same)
- + Understand the causes for the trade-off

## Advantages of finding the complete front

- + Allows DM to choose solution after having seen the alternatives
- + Interactive search of Pareto front
- + Offer different alternatives to different customers (e.g., mean-variance portfolio optimization)
- + Reveal common properties among Pareto-optimal solutions (some variables are always the same)
- + Understand the causes for the trade-off
- + Aid in other optimization tasks (constraints, multi-objectivization)

## Understanding trade-offs



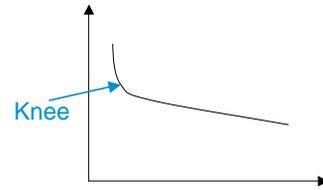
## Do we really need the whole front?

- Computational overhead
- Large set of alternatives, difficult to search by DM
- Identify “most interesting” regions
- Take into account partial user preferences
- Bias the distribution
- Restrict the distribution

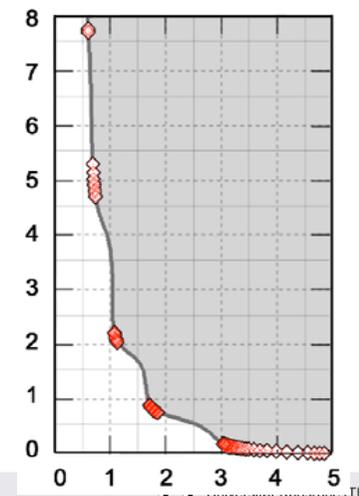
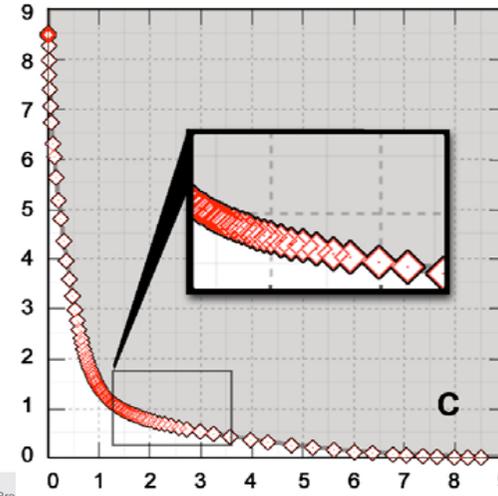


## Identifying knees

- Solutions where an improvement in either objective leads to a significant worsening of the other objective are more likely to be preferred -> knee

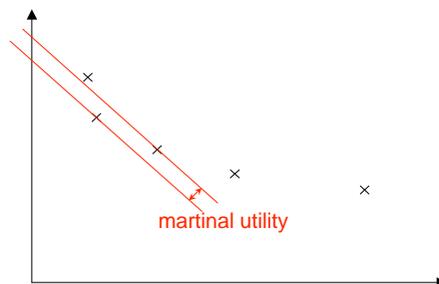


- If crowding distance is replaced by marginal utilities, algorithm focuses on knees
- No preference information necessary



## Marginal Utilities [Branke et al. 2004]

- Assume user has linear utility function
- Evaluate each solution with expected loss of utility if solution would not be there



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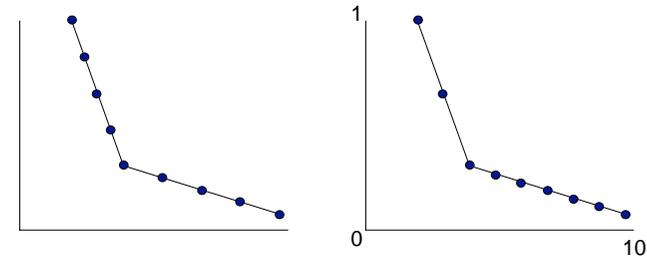
### Desert

Current research

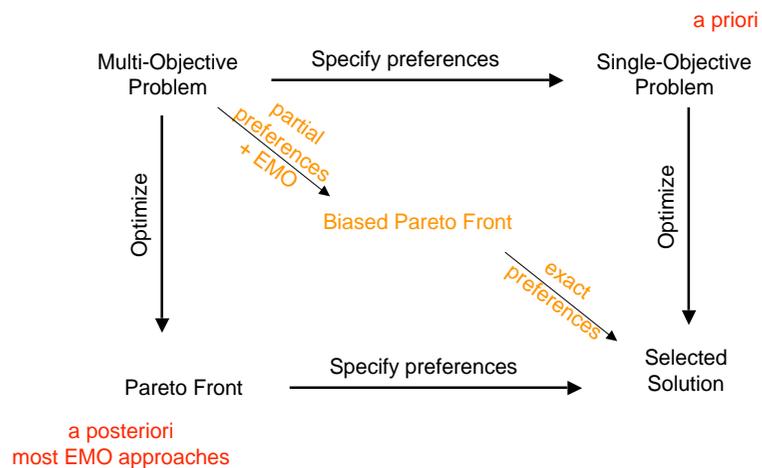
Summary

- Although a user generally cannot specify his/her preferences exactly before alternatives are known, he/she usually has some rough idea as to what solutions are desired
  - “A solution should have at least x in objective f1.”
  - “f1 of x would be good, f1 of y would be great.”
  - “My target solution would look something like this.”
  - “If a solution is worse by one unit in objective f1, it should be at least x units better in objective f2 to be interesting.”
  - “Objective f1 is somewhat more important than objective f2.”
- Hope: Find a larger variety of more interesting solutions more quickly.

- All EMO approaches attempt to find a representative set of the Pareto optimal front
- Usually, representative means well distributed



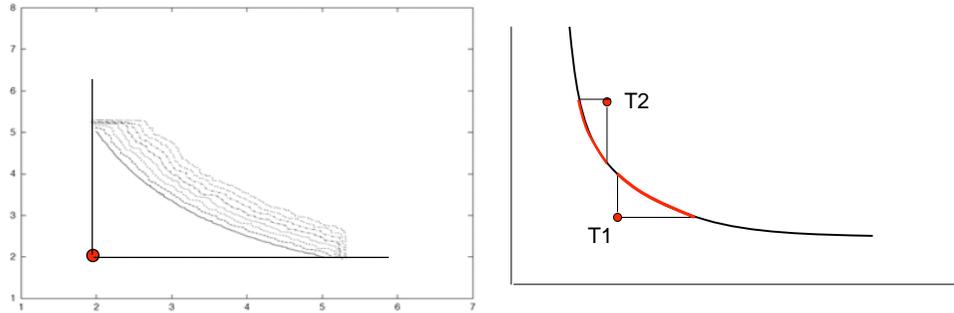
- But: distribution depends on scaling of the objectives



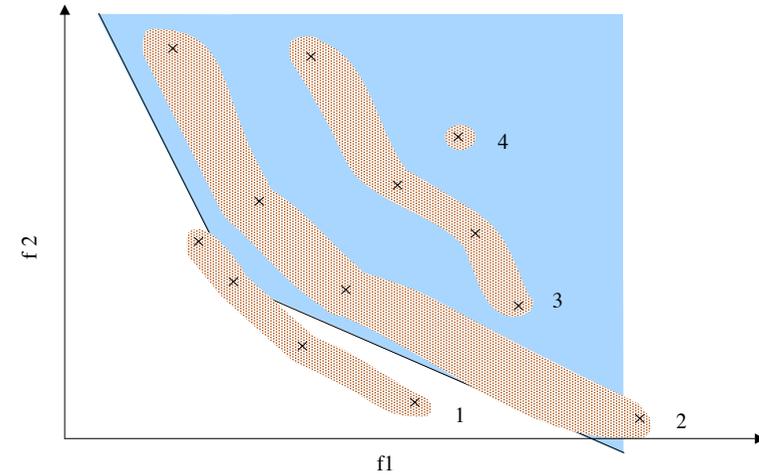
- Constraint:  $f1 > x$
- Constraints are easy to integrate into EMO
  - Lexicographic ordering (feasible solution always dominates infeasible solution)
  - Penalty
  - Additional objective
  - ...

## “... target solution ...”

1. Minimize distance to ideal solution (single objective)
2. Minimize maximal distance in any objective (single objective)
3. Goal Attainment [Fonseca & Fleming, 1993]/Goal Programming [Deb, 1999]
  - Do not reward improvement over ideal solution  
 $f_1 \rightarrow \max\{0, f_1 - f_1^*\}$



## Guided dominance criterion



## “... at least x units better in objective f2 ...”

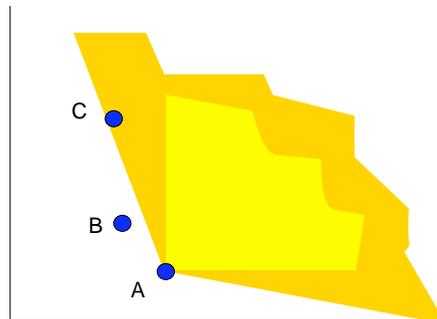
- Maximal and minimal trade-offs
  - Guided MOEA [Branke et al. 2001]
  - Modify definition of dominance
- 
- Can be achieved by a simple transformation of the objectives
  - Not so easy for more than 2 objectives

$$\Omega_1(x) = f_1(x) + w_{12}f_2(x)$$

$$\Omega_2(x) = f_2(x) + w_{21}f_1(x)$$

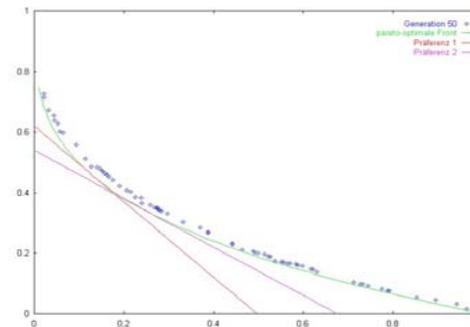
$$x \succ y \Leftrightarrow \Omega_i(x) \leq \Omega_i(y) \quad \forall i \in \{1,2\}$$

$$\wedge \exists j : \Omega_j(x) < \Omega_j(y)$$

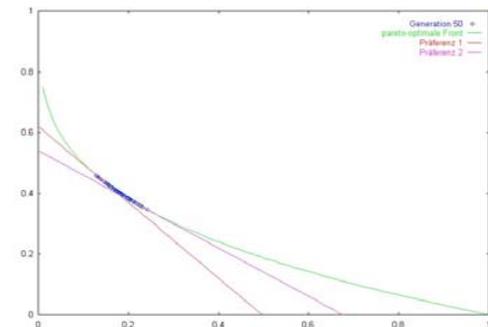


## The effect of guidance

standard MOEA



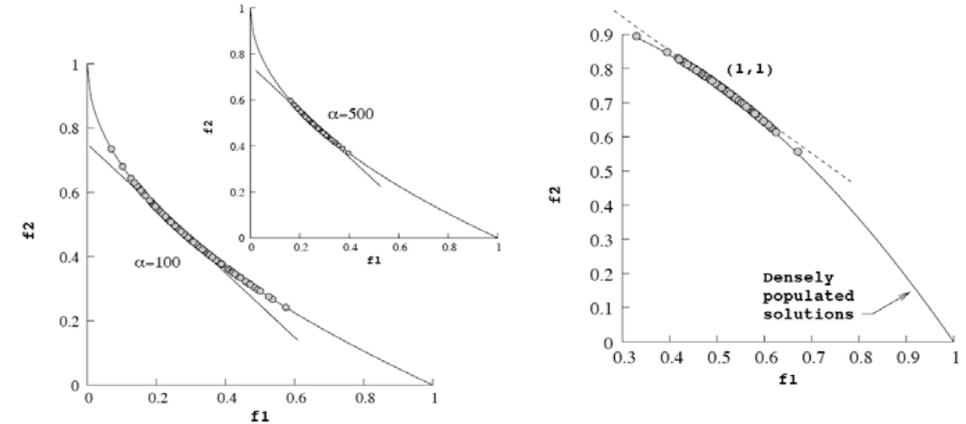
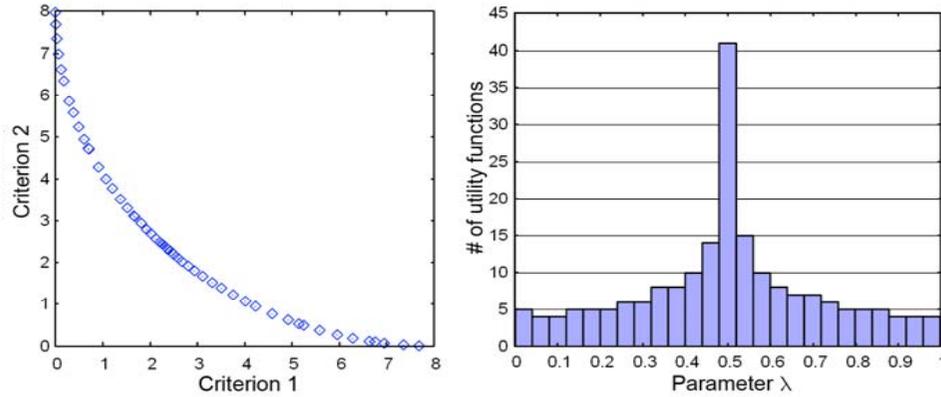
guided MOEA



➔ Faster convergence and better coverage of the interesting area of the Pareto-optimal front

## Marginal utility with preferences

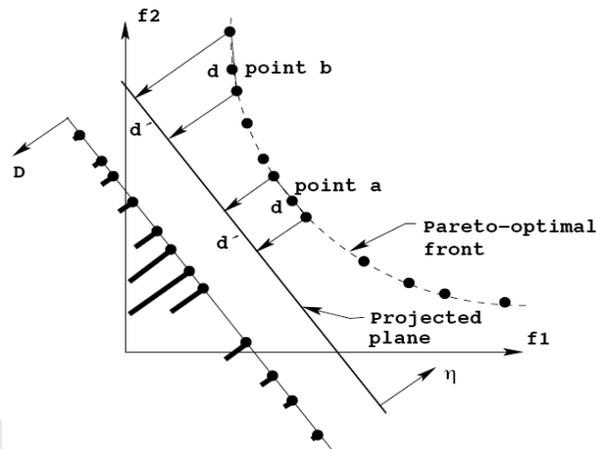
- With non-uniform distribution of utility functions



## Biased sharing [Branke & Deb 2004]

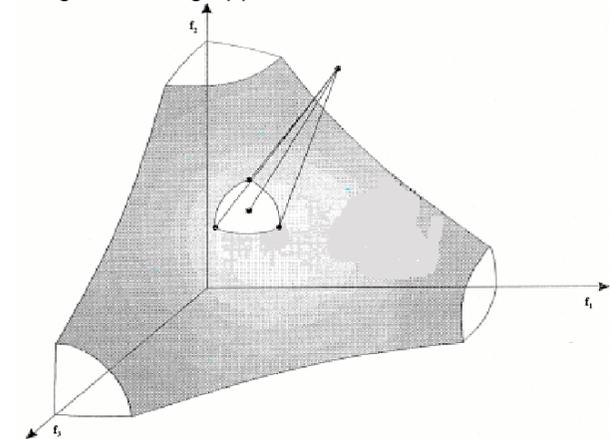
- User specifies weights and spread parameter
- Crowding distance calculation is modified

$$D_i = d_i \left( \frac{d'_i}{d_i} \right)^\alpha$$



## Light Beam Search [Deb&Kumar 2007]

- Specify aspiration and reservation point
- Determine projection on Pareto front
- Identify interesting local area using outranking approaches



- Narrow down / refocus search **during** MOEA run
- Explicitly by
  - adjusting constraints
  - moving the target
  - modifying the max/min trade-offs
  - ...
- Implicitly by comparing solutions
  - learn user preferences

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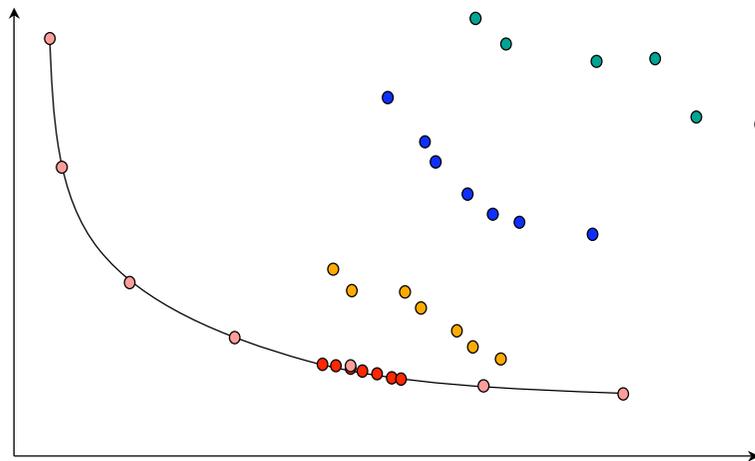
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Current research

Summary



- Many-objective problems (difficulty: almost all solutions non-dominated)
- Multiobjectivization (influence diversity and search space structure)
- Noisy objective functions (e.g., stochastic simulation)
- Worst-case multi-objective optimization
- Using metamodels in case of expensive fitness evaluation
- Individual = Set of solutions

- Evolutionary algorithms open new possibilities in multi-objective optimization because
  - they are very general problem solvers
  - they work on a population of solutions and can thus search for a whole set of solutions simultaneously
- Different ways to use EAs in MOO:
  1. As single-objective optimizer in classical MOO techniques
  2. To generate an approximation to the whole Pareto front
  3. With partial user preferences resulting in a partial front or biased distribution
  4. Interactively guided by the user

- [Branke et al. 2001] J. Branke, T. Kaußler, H. Schmeck: "Guidance in evolutionary multi-objective optimization". *Advances in Engineering Software*, 32:499-507
- [Branke et al. 2004] J. Branke, K. Deb, H. Dierolf, M. Osswald: "Finding knees in multi-objective optimization". *Parallel Problem Solving from Nature*, Springer, pp. 722-731  
Branke and Deb Biased
- [Branke and Deb 2004] J. Branke and K. Deb: "Integrating user preferences into evolutionary multi-objective optimization". In Y. Jin, editor, *Knowledge Incorporation in Evolutionary Computation*, Springer, pages 461–477
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- [Deb et al. 2002] K. Deb, S. Agrawal, A. Pratap, T. Meyarivan: "A fast and Elitist multi-objective Genetic Algorithm: NSGA-II". *IEEE Transactions on Evolutionary Computation* 6(2):182-197
- [Deb and Kumar 2007] K. Deb and A. Kumar: "Light beam search based multi-objective optimization using evolutionary algorithms". *Congress on Evolutionary Computation*, IEEE, pp. 2125-2132
- [Fonseca and Fleming 1993] C. M. Fonseca and P. J. Fleming: "Genetic algorithms for multiobjective optimization: Formulation, discussion, and generatization". *International Conference on Genetic Algorithms*, Morgan Kaufmann, pp. 416-423

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- K. Deb: "Multi-objective optimization using evolutionary algorithms". Wiley, 2001
- C. Coello Coello, D. A. Van Veldhuizen and G. B. Lamont: "Evolutionary algorithms for solving multi-objective problems". Kluwer, 2002
- J. Branke, K. Deb, K. Miettinen, R. Slowinski: "Multi-objective optimization - interactive and evolutionary approaches". Springer, to appear

### Websites:

- <http://www.lania.mx/~coello>